

Math 8250: Day 5

Ex: Consider $M = O(n)$. Then an element of $T_{\mathbf{I}} O(n)$ is a tangent vector; i.e., the tangent to a curve α at $\mathbf{I}$

Let $\alpha: (-\varepsilon, \varepsilon) \rightarrow O(n)$ s.t. $\alpha(0) = \mathbf{I}$. Then $\alpha(t)$ is an orthogonal matrix for all $t \in (-\varepsilon, \varepsilon)$, so

$$\alpha(t) \alpha(t)^T = \mathbf{I}$$

Differentiate: $\alpha'(t) \alpha(t)^T + \alpha(t) \alpha'(t)^T = 0$.

At $t=0$, this reduces to $\alpha'(0) + \alpha'(0)^T = 0$, so $\alpha'(0)$ is skew-symmetric.

In other words, $T_{\mathbf{I}} O(n) = \text{skew-symmetric matrices}$.

Now, if $Q \in O(n)$ and we define $\ell_Q: O(n) \rightarrow O(n)$ by $\ell_Q(A) = QA$, then

$$(d\ell_Q)_{\mathbf{I}} \Delta = Q \Delta.$$

Since $(d\ell_Q)_{\mathbf{I}}: T_{\mathbf{I}} O(n) \rightarrow T_Q O(n)$ is clearly surjective, we see that $T_Q O(n)$ consists of matrices of the form $Q \Delta$ where Δ is skew-symmetric.

Therefore, a vector field X on M is given at each point $Q \in M$ as $X_Q = Q \Delta_Q$.

A vector field where $\Delta_Q = \Delta_{\mathbf{I}} \forall Q \in M$ is called **left-invariant**.

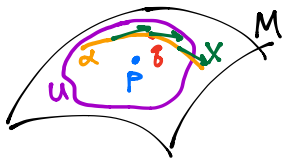
If X & Y are left-invariant & $X_{\mathbf{I}} = \Delta_1$, $Y_{\mathbf{I}} = \Delta_2$, then $[X, Y]_{\mathbf{I}} = \Delta_1 \Delta_2 - \Delta_2 \Delta_1$ &

$$[X, Y]_Q = Q(\Delta_1 \Delta_2 - \Delta_2 \Delta_1).$$

Def: Let X be a vector field on M . A curve $\alpha: (a, b) \rightarrow M$ is called an **integral curve** (or **trajectory**) of X if $\alpha'(t) = X(\alpha(t))$ for all $t \in (a, b)$.

Prop: Let X be a v.f. on M and let $p \in M$. Then there exist a neighborhood U of p , an interval $(-\delta, \delta)$, $\delta > 0$

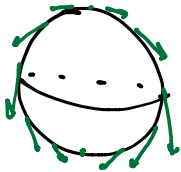
and a map $\varphi: (-\delta, \delta) \times U \rightarrow M$ s.t. $t \mapsto \varphi(t, g)$ is the unique smooth curve satisfying $\frac{\partial \varphi}{\partial t} = X(\varphi(t, g))$ and $\varphi(0, g) = g$.



Proof: Since M is locally diffeomorphic w/ $\mathbb{R}^n$, this follows from the fundamental theorem on existence & uniqueness of ODEs. $\square$

Often denote $\phi_t(p) = \phi(t, p)$, called the **local flow** of X .

Ex:



$$M = S^2 \quad X = (zx, zy, z^2 - 1)$$

Then the local flow pushes the mass of the sphere down towards the south pole

Note: This is the image under diffeomorphism of mass stere. proj. of the vector field $(-x, -y)$ on $\mathbb{R}^2$

This is an example of a so-called **complete** vector field b/c the flow exists for all time at every point.

If the manifold were instead the sphere w/ the antipodal circle removed, then the vector field would not be complete.

Now we can interpret the bracket $[X, Y]$ as a derivation of f along the trajectories of X .

Prop: Let X and Y be smooth vector fields on M , let $p \in M$, and let ϕ_t be the local flow of X in a nbd U of p . Then

$$[X, Y](p) = \lim_{t \rightarrow 0} \frac{1}{t} [Y - d\phi_t Y](\phi_t(p))$$

Proof: For f differentiable in a nbd of p , our goal is to show that

$$\lim_{t \rightarrow 0} \frac{1}{t} (Y - d\phi_t Y)(\phi_t(p)) = ((XY - YX)f)(p).$$

Notice that $(d\phi_t Y)f(\phi_t(p)) = Y(f \circ \phi_t)(p)$, so LHS is

$$\lim_{t \rightarrow 0} \frac{(Yf)(\phi_t(p)) - Y(f \circ \phi_t)(p)}{t}$$

If we could get $\lim_{t \rightarrow 0} \frac{(Yf)(\phi_t(p)) - Y(f \circ \phi_t)(p)}{t} = \frac{d(Yf \circ \phi_t)}{dt} \Big|_{t=0} = X(Yf)(p)$, we would be in business.

To that end, define $h(t, g) := f(\phi_t(g)) - f(g)$ for all g in the domain of f and t sufficiently small.

Claim: $\exists$ smooth function g s.t. $t g(t, g) = h(t, g)$; in particular, $g(0, g) = \frac{\partial h(t, g)}{\partial t} \Big|_{t=0}$.

Assuming the claim, we have that

$$(f \circ \phi_t)(g) = f(g) + t g(t, g) \text{ and } g(0, g) = Xf(g).$$

But then

$$(d\phi_t Y)f(\phi_t(p)) = (Y(f \circ \phi_t))(p) = (Yf)(p) + t Yg(t, p)$$

and

$$\begin{aligned} \lim_{t \rightarrow 0} \frac{1}{t} ((Y - d\phi_t Y)f)(\phi_t(p)) &= \lim_{t \rightarrow 0} \frac{(Yf)(\phi_t(p)) - Yf(p)}{t} - Yg(0, p) \\ &= (X(Yf))(p) - (Y(Xf))(p) \\ &= ([X, Y]f)(p). \end{aligned}$$

□

Proof of Claim: Define $g(t, g) := \int_0^1 \frac{\partial h(ts, g)}{\partial (ts)} ds$

Then, letting $u = ts$, $du = t ds$, so

$$g(t, g) = \frac{1}{t} \int_0^t \frac{\partial h(u, g)}{\partial u} du = \frac{1}{t} h(t, g),$$

as desired.

□