

Math 8250: Day 2

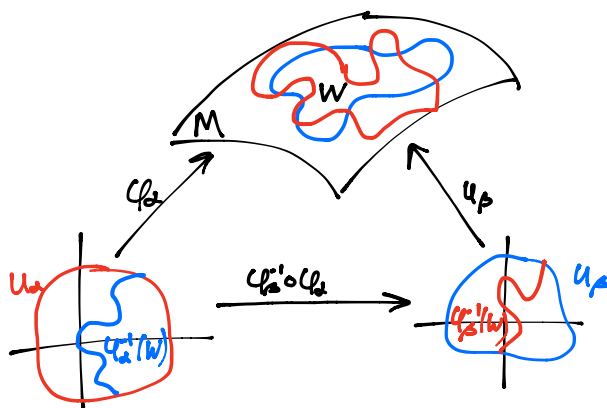
Def: A *differentiable manifold of dimension n* is a Hausdorff, second countable topological space M

together w/ a family of injective maps $\phi_\alpha: U_\alpha \subset \mathbb{R}^n \rightarrow M$ of open sets U_α of $\mathbb{R}^n$ s.t.:

① $\bigcup_\alpha \phi_\alpha(U_\alpha) = M$

② for any α, β s.t. $\phi_\alpha(U_\alpha) \cap \phi_\beta(U_\beta) = W \neq \emptyset$, the sets $\phi_\alpha^{-1}(W)$ and $\phi_\beta^{-1}(W)$ are open sets in $\mathbb{R}^n$ and the maps $\phi_\beta^{-1} \circ \phi_\alpha$ & $\phi_\alpha^{-1} \circ \phi_\beta$ are smooth (C^∞).

③ The family $\{U_\alpha, \phi_\alpha\}$ is maximal w.r.t. ① & ②



The (U_α, ϕ_α) are called
coordinate charts

Ex: ① The maximal collection containing $(\mathbb{R}^n, \text{id})$ obviously makes $\mathbb{R}^n$ into an n -manifold.

② $\mathbb{RP}^n$ is the set of straight lines in $\mathbb{R}^{n+1}$ or, equivalently, the quotient of $\mathbb{R}^n - \{0\}$ by the equiv. relation

$$(x_1, \dots, x_{n+1}) \sim (\lambda x_1, \dots, \lambda x_{n+1}) \forall \lambda \in \mathbb{R}, \lambda \neq 0.$$

Note points in homogeneous coords $[x_1, \dots, x_n]$. In particular, if $x_i \neq 0$

$$[x_1, \dots, x_n] = \left[\frac{x_1}{x_i}, \dots, \frac{x_{i-1}}{x_i}, 1, \frac{x_{i+1}}{x_i}, \dots, x_n \right]$$

Define $\phi_i: \mathbb{R}^n \rightarrow \mathbb{RP}^n$ by $\phi_i(x_1, \dots, x_n) = [x_1, \dots, x_{i-1}, 1, x_i, \dots, x_n]$

then maximal family containing $\{(\mathbb{R}^n, \varphi_i)\}$ makes $\mathbb{RP}^n$ into a manifold.

① Obvious

② $\varphi_i^{-1}(\varphi_i(\mathbb{R}^n) \cap \varphi_j(\mathbb{R}^n)) = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_j \neq 0\}$ if $i > j$, which is clearly open, and

$$\begin{aligned}\varphi_i^{-1} \circ \varphi_j(x_1, \dots, x_n) &= \varphi_i^{-1}[x_1, \dots, x_{j-1}, 1, x_j, \dots, x_n] \\ &= \varphi_i^{-1}\left[\frac{x_1}{x_{j-1}}, \dots, \frac{x_{j-1}}{x_{j-1}}, \frac{1}{x_{j-1}}, \frac{x_j}{x_{j-1}}, \dots, \frac{x_{j-2}}{x_{j-1}}, 1, \frac{x_i}{x_{j-1}}, \dots, \frac{x_n}{x_{j-1}}\right] \\ &= \left(\frac{x_1}{x_{j-1}}, \dots, \frac{x_{j-1}}{x_{j-1}}, \frac{1}{x_{j-1}}, \frac{x_j}{x_{j-1}}, \dots, \frac{x_{j-2}}{x_{j-1}}, \frac{x_i}{x_{j-1}}, \dots, \frac{x_n}{x_{j-1}}\right)\end{aligned}$$

So $\varphi_i^{-1} \circ \varphi_j$ is clearly smooth.

Df: Let M, N^n be mfd. A cont. map $f: M \rightarrow N$ is differentiable at $p \in M$ if, given a chart $\psi: V \subset \mathbb{R}^n \rightarrow N$ containing $f(p) \exists$ chart $\varphi: U \subset \mathbb{R}^m \rightarrow M$ at p s.t. $f(\varphi(U)) \subset \psi(V)$ and

$$\psi^{-1} \circ f \circ \varphi: U \subset \mathbb{R}^m \rightarrow \mathbb{R}^n$$

is differentiable at $\varphi^{-1}(p)$. The map f is diffble on an open set if it is diffble at all pts in the set.

Target Vectors

To define target vectors on a mfd, we need to think about vectors in $\mathbb{R}^n$ in a slightly different way than you might be used to. Specifically, we're going to identify a vector $v \in \mathbb{R}^n$ w/ the gradient on differentiable (or smooth) functions which gives the directional derivative with respect to v of the function.

More precisely, if $\alpha: (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$ is a smooth map (i.e., a smooth curve) with $\alpha(0) = p$, then write

$$\alpha(t) = (x_1(t), \dots, x_n(t)), \quad t \in (-\varepsilon, \varepsilon), \quad (x_1, \dots, x_n) \in \mathbb{R}^n$$

Then $\alpha'(0) = (x_1'(0), \dots, x_n'(0)) = v \in \mathbb{R}^n$. Suppose f is differentiable in a nbd of p . Then, restricting f to the image of α , the directional derivative w.r.t. v of f is

$$\left. \frac{d(f \circ \alpha)}{dt} \right|_{t=0} = \sum_{i=1}^n \left. \frac{\partial f}{\partial x_i} \right|_{t=0} \frac{dx_i}{dt} \Big|_{t=0} = \left(\sum_i x_i'(0) \frac{\partial}{\partial x_i} \right) f.$$

Notice that this operator giving the directional deriv. w.r.t. v depends uniquely on v and is a *linear derivation*

meaning that ① $v(f + \lambda g) = v(f) + \lambda v(g)$ $\forall f, g$ diffble in a nbd of p & $\lambda \in \mathbb{R}$

$$\text{② } v(fg) = f(p)v(g) + g(p)v(f)$$

Def: Let M^n be a mfd. A smooth path $\alpha: (-\varepsilon, \varepsilon) \rightarrow M$ is a (smooth) *curve* in M . Suppose $\alpha(0) = p \in M$ and let $\mathcal{D}$ be the set of functions on M which are differentiable at p . The *target vector* to the curve α at $t=0$ is a function $\alpha'(0): \mathcal{D} \rightarrow \mathbb{R}$ given by

$$\alpha'(0)f = \left. \frac{d(f \circ \alpha)}{dt} \right|_{t=0}$$

A *target vector* at p is the target vector at $t=0$ of some curve $\alpha: (-\varepsilon, \varepsilon) \rightarrow M$ w/ $\alpha(0) = p$.

The set of all target vectors at p is the *target space* to M at p , denoted $T_p M$.

If (U, φ) is a coord. chart at the point p s.t. $p = \varphi(0)$, then

$$f \circ \varphi(g) = f(x_1, \dots, x_n), \quad g = (x_1, \dots, x_n) \in U$$

and

$$\varphi^{-1} \circ \alpha(t) = (x_1(t), \dots, x_n(t))$$

so

$$\begin{aligned} \alpha'(0)f &= \left. \frac{d}{dt} (f \circ \alpha) \right|_{t=0} = \left. \frac{d}{dt} f(x_1(t), \dots, x_n(t)) \right|_{t=0} \\ &= \sum_{i=1}^n x_i'(0) \frac{\partial f}{\partial x_i} = \left(\sum_i x_i'(0) \left(\frac{\partial}{\partial x_i} \right)_0 \right) f \end{aligned}$$

In other words, we can write the vector $\alpha'(0)$ in local coords as

$$\alpha'(0) = \sum_i x_i'(0) \left(\frac{\partial}{\partial x_i} \right)_0$$

The $\left(\frac{\partial}{\partial x_i} \right)_0$ give the basis of $T_p M$ associated to the chart (U, φ) .

Def: The **target bundle** of a manifold M^n , denoted TM , is the union of the target spaces:

$$TM := \bigcup_{p \in M} T_p M$$