

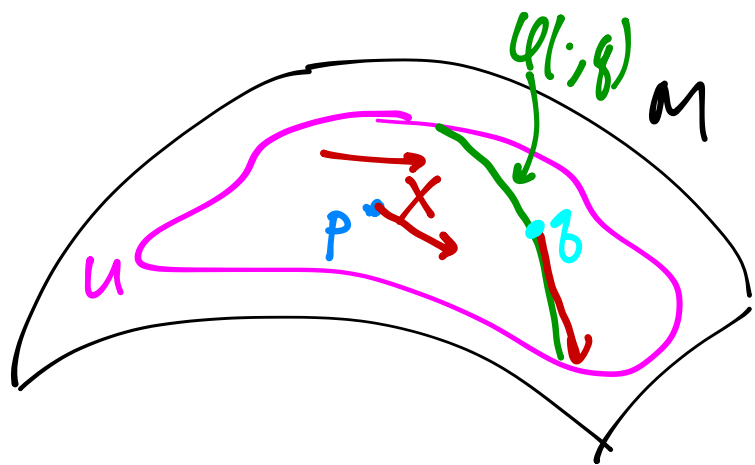
Math 670: Day 6

Def: let X be a v.f. on M . A curve $\alpha: (a,b) \rightarrow M$ is called an **integral curve** (or **trajectory**) for X if $\alpha'(t) = X_{\alpha(t)} \forall t \in (a,b)$.

Prop: let X be a v.f. on M & let $p \in M$. Then $\exists$ nbd U of p , $\delta > 0$, & a map $\varphi: (-\delta, \delta) \times U \rightarrow M$ s.t. $t \mapsto \varphi(t, q)$

is the unique smooth curve satisfying $\frac{\partial \varphi}{\partial t} = X_{\varphi(t,q)}$ & $\varphi(0, q) = q$.

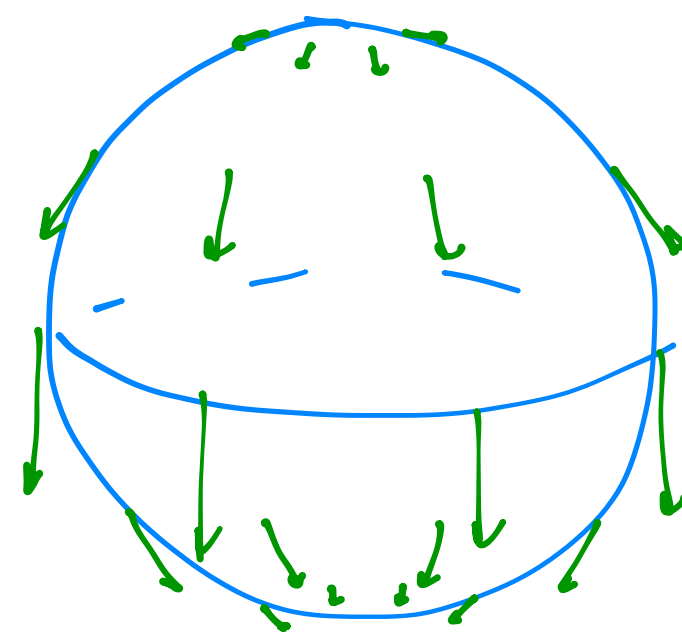
Proof: Since M is locally diffeo. to $\mathbb{R}^n$, this follows from the fundamental theorem on existence & uniqueness of solutions to ODEs. $\square$



often denote $\varphi_t(q) = \varphi(t, q)$ & call it the **local flow** of X .

Ex: $M = S^2$, $X_{(x,y,z)} = (zx, zy, z^2 - 1)$

then the local flow pushes the mass of the sphere down towards the south pole.



Note: This is the image under the differential of the stereographic projection of the v.f. $(-x, -y)$ on $\mathbb{R}^2$.

This is an example of a **complete** v.f. since the local flow exists for all time at all points.

If the mfd were instead the sphere w/ the antipodal circle removed, the v.f. would not be complete.

Now, we can interpret the Lie bracket $[X, Y] \ni$ a sort of derivative of Y along the trajectories of X .

Prop: let X & Y be smooth vector fields on M , let $p \in M$ & let φ_t be the local flow of X in a nbd of p . Then

$$[X, Y]_p = \lim_{t \rightarrow 0} \frac{Y_{\varphi_t(p)} - d\varphi_t(Y_p)}{t}$$

Proof: For f a differentiable function in a nbd of p , the goal is to show that

$$\lim_{t \rightarrow 0} \frac{Y_{\varphi_t(p)}(f) - d\varphi_t(Y_p)(f)}{t} = ((XY - YX)f)(p).$$

Notice that, by definition of the differential, $(d\varphi_t(Y)f)(\varphi_t(p)) = Y(f \circ \varphi_t)(p)$, so the LHS is

$$\lim_{t \rightarrow 0} \frac{Y(f \circ \varphi_t)(p) - Y(f)(p)}{t}$$

If we could set $\lim_{t \rightarrow 0} \frac{(Yf)(\varphi_t(p)) - (Yf)(p)}{t} = \frac{d(Yf \circ \varphi_t)}{dt} \Big|_{t=0} = X(Yf)(p)$ to show up, we would be in business.

To that end, define $h(t, g) := f(\varphi_t(g)) - f(g)$ $\forall g$ in the domain of f & all t sufficiently small.

Claim: $\exists$ smooth function g s.t. $t g(t, g) = h(t, g)$; in particular, $g(0, g) = \frac{\partial h(t, g)}{\partial t} \Big|_{t=0}$

Assuming the claim is true, we have that

$$(f \circ \varphi_t)(g) = f(g) + t g(t, g) \quad \& \quad g(0, g) = X f(g).$$

But then

$$((\varphi_t^* Y) f)(\varphi_t(p)) = (Y(f \circ \varphi_t))(p) = (Yf)(p) + t (Yg(t, \cdot))(p)$$

&

$$\begin{aligned} \lim_{t \rightarrow 0} \frac{(Yf)(\varphi_t(p)) - (Yf)(p)}{t} &= \lim_{t \rightarrow 0} \frac{(Yf)(\varphi_t(p)) - ((Yf)(p) + t(Yg(t, \cdot))(p))}{t} \\ &= \lim_{t \rightarrow 0} \frac{(Yf)(\varphi_t(p)) - (Yf)(p)}{t} - (Yg(0, \cdot))(p) \\ &= (X(Yf))(p) - (Y(Xf))(p) \\ &= ([X, Y]f)(p), \end{aligned}$$

as desired. □

Proof of Claim: Write $g(t, g) = \int_0^1 \frac{\partial h(ts, g)}{\partial (ts)} ds$. Then let $u = ts$, $du = t ds$, so

$$g(t, g) = \frac{1}{t} \int_0^1 \frac{\partial h(ts, g)}{\partial (ts)} t ds = \frac{1}{t} \int_0^t \frac{\partial h(u, g)}{\partial u} du = \frac{1}{t} h(t, g). \quad \square$$