

Vector Fields:

Df: A **vector field** X on a smooth mfd M is a smooth section of the tangent bundle TM ; i.e., a smooth map $X: M \rightarrow TM$.
Given how we've defined tangent vectors, this means a vector field is just a linear derivation on $C^\infty(M)$.

Note: If $\varphi: U \subseteq \mathbb{R}^n \rightarrow M$ is a coord. chart at $p \in M$, then

$$X(p) = \sum a_i(p) \frac{\partial}{\partial x_i}, \text{ where each } a_i: U \rightarrow \mathbb{R} \text{ is smooth \& } \{\frac{\partial}{\partial x_i}\} \text{ is the basis of } T_p M \text{ associated w/ } (U, \varphi).$$

• As a map $C^\infty(M) \rightarrow C^\infty(M)$, a vector field acts as

$$(Xf)(p) = \sum a_i(p) \frac{\partial f}{\partial x_i} \Big|_p$$

which notice really is a smooth function on M .

Df: If X & Y are smooth vector fields on M , the **Lie bracket** of X & Y is a vector field $[X, Y]$ defined by

$$[X, Y](f) := X(Yf) - Y(Xf)$$

In coords., if $X = \sum a_i \frac{\partial}{\partial x_i}$ & $Y = \sum b_j \frac{\partial}{\partial x_j}$, then

$$[X, Y]f = X(Yf) - Y(Xf) = X\left(\sum b_j \frac{\partial f}{\partial x_j}\right) - Y\left(\sum a_i \frac{\partial f}{\partial x_i}\right) = \sum_{i,j} a_j \left(\frac{\partial b_i}{\partial x_j} \frac{\partial f}{\partial x_i} + b_i \frac{\partial^2 f}{\partial x_j \partial x_i} \right) - \sum_{i,j} b_j \left(\frac{\partial a_i}{\partial x_j} \frac{\partial f}{\partial x_i} + a_i \frac{\partial^2 f}{\partial x_j \partial x_i} \right)$$

$$= \sum \left(a_j \frac{\partial b_i}{\partial x_j} - b_j \frac{\partial a_i}{\partial x_j} \right) \frac{\partial f}{\partial x_i} + \sum a_i b_j \left(\frac{\partial^2 f}{\partial x_i \partial x_j} - \frac{\partial^2 f}{\partial x_j \partial x_i} \right) \xrightarrow{0}$$

$$= \left(\sum_{i,j} a_j \frac{\partial b_i}{\partial x_j} - b_j \frac{\partial a_i}{\partial x_j} \right) \frac{\partial f}{\partial x_i}$$

local coord expression for $[X, Y]$

Prop: If X, Y, Z are smooth vector fields on M & $a, b \in \mathbb{R}$, $f, g \in C^\infty(M)$, then

$$\textcircled{1} [X, Y] = -[Y, X] \text{ (anti-commutativity)}$$

$$\textcircled{2} [aX + bY, Z] = a[X, Z] + b[Y, Z] \text{ (linearity)}$$

$$\textcircled{3} [[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0 \text{ (Jacobi identity)}$$

$$\textcircled{4} [fX, gY] = fg[X, Y] + f(Xg)Y - g(Yf)X$$

Prag: Exercise.

Ex: Consider $SO(n)$, then an element of $T_I SO(n)$ is a tangent vector; i.e., the tangent to a curve through I . Let

$\alpha: (-\varepsilon, \varepsilon) \rightarrow SO(n)$ s.t. $\alpha(0) = I$, then $\alpha(t)$ is an orthogonal matrix $\forall t \in (-\varepsilon, \varepsilon)$, so $\alpha(t)\alpha(t)^T = I$.

Differentiate: $\alpha'(t)\alpha(t)^T + \alpha(t)\alpha'(t)^T = 0$. At $t=0$, this reduces to $\alpha'(0) + \alpha'(0)^T = 0$, so $\alpha'(0) = -\alpha'(0)^T$, so

$\alpha'(0)$ is skew-symmetric. The converse is also true, so we can identify $T_I SO(n)$ w/ the set of skew-symmetric $n \times n$ matrices.

Also, note that if $\Delta \in T_I SO(n)$, then $e^\Delta \in SO(n)$ b/c $(e^\Delta)^T = e^{(\Delta^T)} = e^{-\Delta} = (e^\Delta)^{-1}$ & $\det(e^\Delta) = e^{\text{tr} \Delta} = e^0 = 1$.

You can prove that this map is actually surjective as well.

Now, if $Q \in SO(n)$ & we define $l_Q: SO(n) \rightarrow SO(n)$ by $l_Q(A) = QA$, then

$$(dl_Q)_I \Delta = Q\Delta \quad (\text{check this if you don't believe it!})$$

Since $(dl_Q)_I: T_I SO(n) \rightarrow T_I SO(n)$ is full rank it's surjective, so $T_Q SO(n)$ consists of matrices of the form $Q\Delta$ for Δ skew-symmetric.

Therefore, a vector field X on $SO(n)$ is given at each pt. $Q \in SO(n)$ by $X_Q = Q\Delta_Q$.

If $\Delta_Q = \Delta_I \forall Q \in SO(n)$ is called left-invariant, & the space of left-inv vf's on $SO(n)$ can then be identified w/ $T_I SO(n)$.

Now, the Lie bracket on left-inv vf's is especially nice: if X & Y are left-inv vf's w/ $X_I = \Delta_x$

& $Y_I = \Delta_y$, then $[X, Y]_I = \Delta_x \Delta_y - \Delta_y \Delta_x$ & $[X, Y]_Q = Q(\Delta_x \Delta_y - \Delta_y \Delta_x)$, so the Lie bracket

becomes a binary operation on $T_I SO(n)$. This makes $T_I SO(n)$ a Lie algebra isomorphic to $\mathfrak{so}(n)$.