

Math 670: Day 11

Remember that a k -form on M^n is a smooth section of $\Lambda^k(M) = \bigcup_{p \in M} \Lambda^k(T_p M)^*$. The space of k -forms on M is denoted $\Omega^k(M)$ & we let $\Omega(M) = \bigoplus_{k \geq 0} \Omega^k(M)$.

Let (U, φ) be a coord. chart in a atl of $p \in M$. For each $i=1, \dots, n$, define $x_i: \varphi(U) \rightarrow \mathbb{R}$ by $x_i(\varphi(a_1, \dots, a_n)) = a_i$.

Then $\{\frac{\partial}{\partial x_i}\}$ is the basis of $T_p M$ associated to φ & $\{dx_i\}$ gives a basis for the dual space $(T_p M)^* = \Lambda^1(T_p M)^*$,

since this is literally just the differential of the functions x_i & by definition of the differential, $dx_i(\frac{\partial}{\partial x_j}) = \frac{\partial}{\partial x_j}(x_i) = \delta_{ij}$.

Then of course it follows that $\{dx_{i_1} \wedge \dots \wedge dx_{i_k} : 1 \leq i_1 < i_2 < \dots < i_k \leq n\}$ gives a basis for $\Lambda^k((T_p M)^*)$ & hence every

$\omega \in \Omega^k(M)$ takes the local form $\omega_p = \sum a_I dx_I$ where $I = (i_1, \dots, i_k)$ & $dx_I = dx_{i_1} \wedge \dots \wedge dx_{i_k}$.

Ex: On $\mathbb{R}^2$ we have global coords, so every $\omega \in \Omega^1(\mathbb{R}^2)$ is of the form $\omega = f dx + g dy$ for $f, g \in C^0(\mathbb{R}^2)$. So if

$$\omega = f dx + g dy$$

$$\text{then } \omega \wedge \eta = (f dx + g dy) \wedge (h dx + m dy) = (fm - gh) dx \wedge dy$$

$$\eta = h dx + m dy$$

$$\text{so } \omega \wedge \eta(u, v) = \omega \wedge \eta\left(u, \frac{\partial}{\partial x} + u_2 \frac{\partial}{\partial y}, v, \frac{\partial}{\partial x} + v_2 \frac{\partial}{\partial y}\right)$$

$$= (fm - gh)(u_1 v_2 - u_2 v_1)$$

On $\mathbb{R}^3$, if $\omega_i \in \Omega^1(\mathbb{R}^3)$ w/ $\omega_i = a_i dx + b_i dy + c_i dz$, then

$$\omega_1 \wedge \omega_2 = (a_1 b_2 - a_2 b_1) dx \wedge dy + (a_1 c_2 - a_2 c_1) dx \wedge dz + (b_1 c_2 - b_2 c_1) dy \wedge dz$$

Also, if $\omega = a dx + b dy + c dz \in \Omega^1(\mathbb{R}^3)$ & $\eta = f dx \wedge dy + g dx \wedge dz + h dy \wedge dz$, then

$$\omega \wedge \eta = (ah - bg + cf) dx \wedge dy \wedge dz$$

Now, to define the exterior derivative, we need to talk about derivations.

Df: An endomorphism A of $\Lambda(V)$ is

• a derivation if $A(uv) = A u v + u A v$

• an **anti-derivation** if $A(uv) = Au \cdot v + (-1)^p u \wedge Av$ for $u \in \Lambda^p(V)$ ($\Rightarrow A(v_1 \wedge \dots \wedge v_k) = \sum_i (-1)^{i-1} v_1 \wedge \dots \wedge Av_i \wedge \dots \wedge v_k$)

• of **degree** k if $A: \Lambda^i(V) \rightarrow \Lambda^{i+k}(V)$ for all i .

This definition extends to **any** (graded) algebra by swapping in the multiplication in the algebra for $\wedge$ in the above.

Ex: We saw before that tangent vectors can be viewed as (ungraded) derivations on the algebra $C^\infty(M)$. No degree b/c ungraded.

Now, the point is that we can give a universal definition for the exterior derivative.

Df: The **exterior derivative** $d: \Omega^i(M) \rightarrow \Omega^{i+1}(M)$ is the unique anti-derivation of degree $+1$ s.t.

① $\forall f \in \Omega^0(M) = C^\infty(M)$, df is the differential of f .

② $d \circ d = 0$.

Prop: There is such a beast.

Idea: In local coords, $\omega_p = \sum f_I dx_I$, and we will define

$$(d\omega)_p = \sum (df_I) \wedge dx_I$$

Why? Well, assume there is an operator d satisfying ① & ②. Then $dx_i = d(x_i)$ is d of the 0-form (a.k.a.

function) x_i , so $d(dx_i) = (d \circ d)x_i$, which had better be zero if d satisfies the cocycle condition ②.

But then, if d is an anti-derivation we will have that $d(dx_I) = 0$ by applying the anti-derivation property iteratively:

$$d(dx_{i_1} \wedge \dots \wedge dx_{i_k}) = \cancel{d(dx_{i_1})} \wedge dx_{i_2} \wedge \dots \wedge dx_{i_k} - dx_{i_1} \wedge \cancel{d(dx_{i_2})} \wedge \dots \wedge dx_{i_k} + \dots + (-1)^{k-1} dx_{i_1} \wedge \dots \wedge \cancel{d(dx_{i_k})} = 0.$$

But then

$$(d\omega)_p = d(\sum f_I dx_I) = \sum (df_I) \wedge dx_I + f_I \cancel{d(dx_I)} = \sum (df_I) \wedge dx_I.$$

