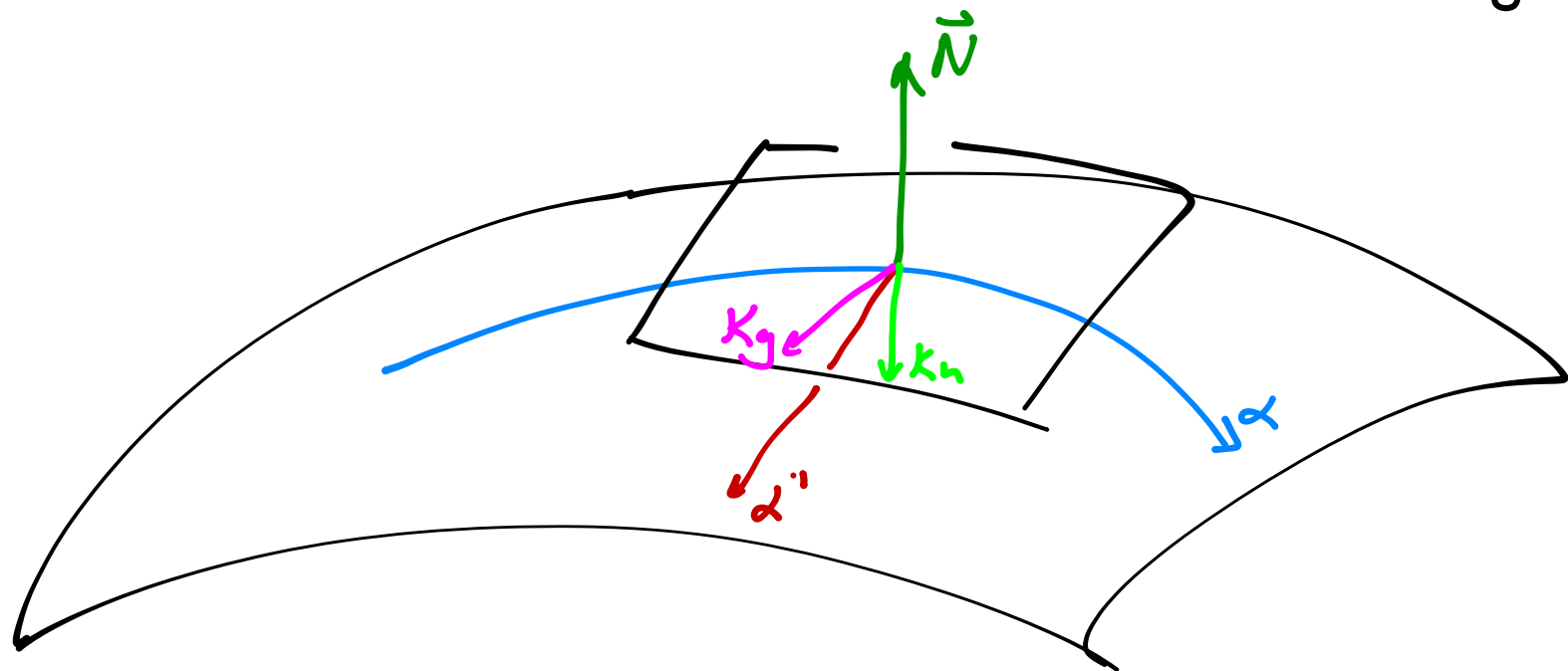


Geodesics

The goal now is to describe geodesics on a surface, which are the (locally) distance-minimizing curves on the surface.



Def: Given a curve $\alpha(s)$ on a surface Σ , we have

$$\alpha''(s) = \kappa_n \vec{N} + \kappa_g \vec{V}$$

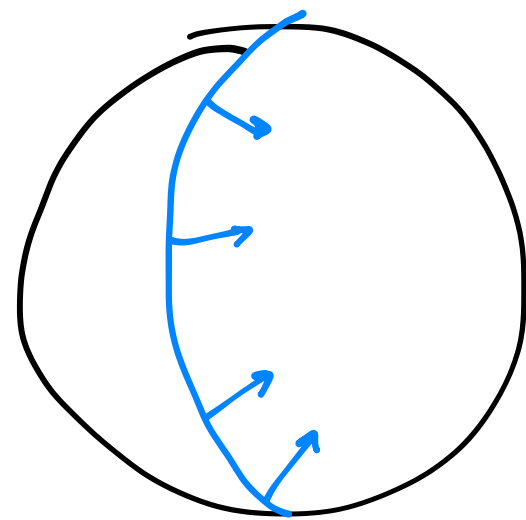
where $\vec{N}$ is the surface normal at $\alpha(s)$ & $\vec{V}$ is some vector in $T_{\alpha(s)}\Sigma$.

The number κ_g is the geodesic curvature of α .

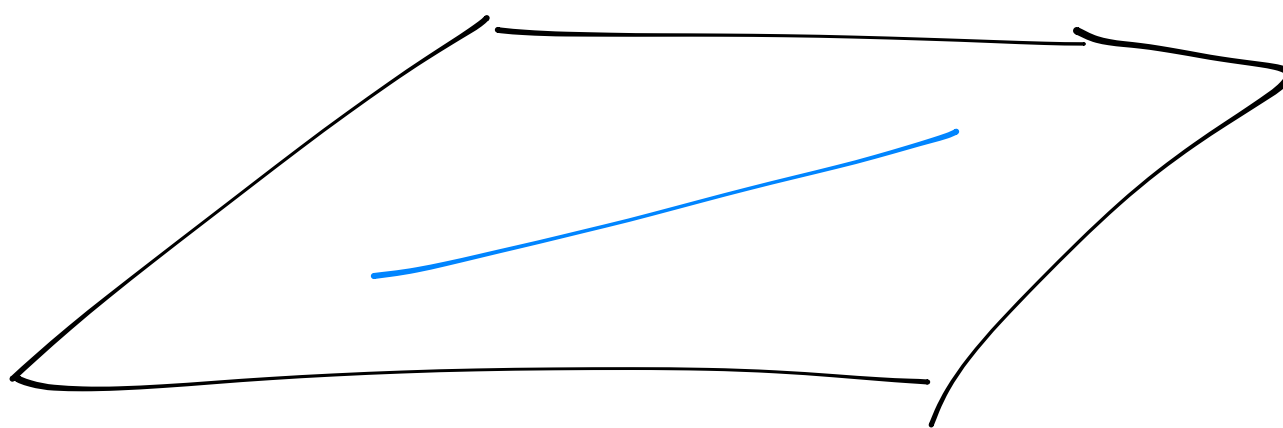
κ_n is the normal curvature of α .

Def: $\alpha(s)$ is a geodesic if $\kappa_g(s) \equiv 0$.

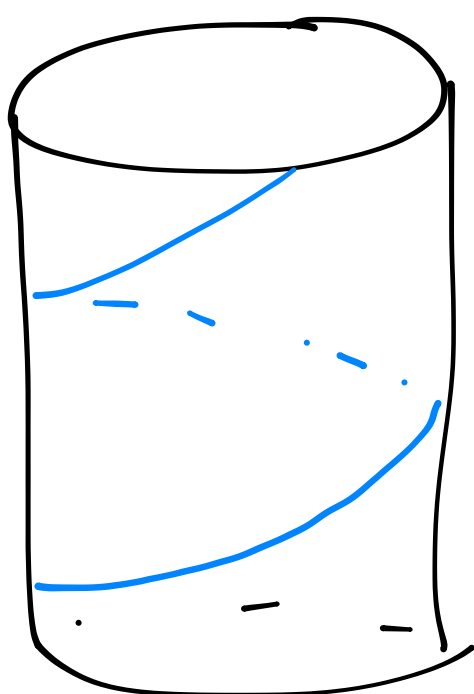
Ex: Σ the sphere, $\alpha(s)$ a great circle, since α is a normal section (& hence $\kappa \equiv \kappa_n$)



Ex: Σ a plane, $\alpha(s)$ a straight line, since $\alpha''(s) = 0$



Ex: Σ a cylinder, $\alpha(s)$ a helix.



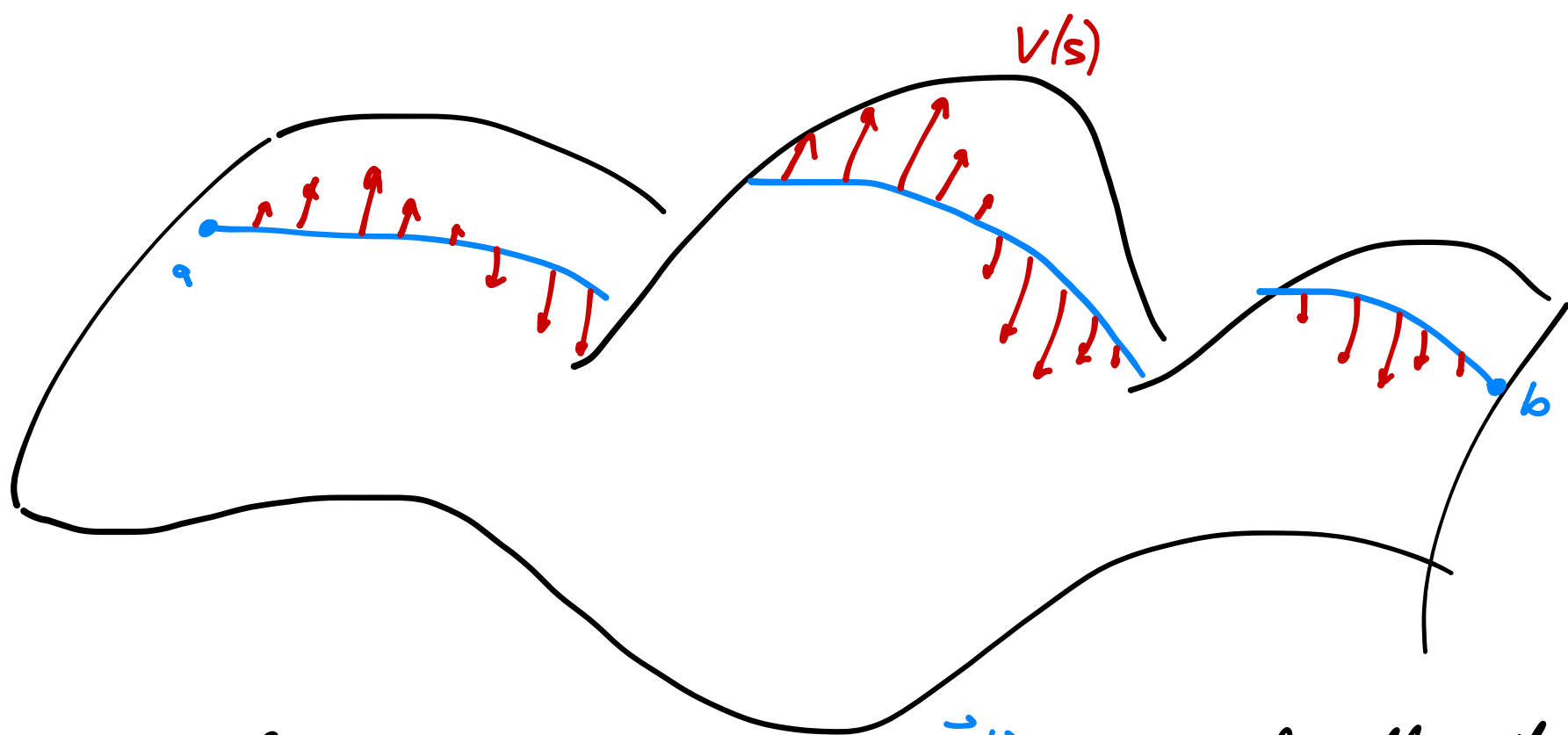
Why?

Well, if $\alpha(s) = (\cos(ks), \sin(ks), s)$ w/ $k^2 + 1 = 1$, then

$$\alpha'(s) = (-k \sin(ks), k \cos(ks), 1)$$

$$\alpha''(s) = (-k^2 \cos(ks), -k^2 \sin(ks), 0), \text{ which is normal to } \Sigma.$$

Geodesics are the appropriate generalization of lines b/c they are locally critical for length in the following sense.



Def: If $V(s)$ is a differentiable map $\mathbb{R} \rightarrow \mathbb{R}^3$ so that $\vec{V}(s) \in T_{\alpha(s)}\Sigma$ for all s , then V is a **vector field** on $\alpha(s)$.

The **variation of length** of α under $\vec{V}$ is

$$\left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} \text{length}(\alpha(s) + \varepsilon \vec{V}(s)) =: D_{\vec{V}} \text{len}(\alpha).$$

Prop: We have $D_{\vec{V}} \text{len}(\alpha) = 0$ $\forall$ v.f. $\vec{V}$ on α with $\vec{V}(a) = \vec{V}(b) = \vec{0} \Leftrightarrow \alpha$ is a **geodesic** joining $\alpha(a)=a$ & $\alpha(b)=b$.

Proof: First of all,

$$\text{len}(\alpha(s) + \varepsilon \vec{V}(s)) = \int_0^L |\alpha'(s) + \varepsilon \vec{V}'(s)| ds,$$

so differentiating under the integral gives

$$\begin{aligned} D_{\vec{V}} \text{len}(\alpha) &= \int_0^L \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} |\alpha'(s) + \varepsilon \vec{V}'(s)| ds \\ &= \int_0^L \frac{\langle \alpha'(s) + \varepsilon \vec{V}'(s), \vec{V}'(s) \rangle}{\|\alpha'(s) + \varepsilon \vec{V}'(s)\|} ds \\ &= \int_0^L \langle \alpha'(s), \vec{V}'(s) \rangle ds \end{aligned}$$

Now integrate by parts: since $\frac{d}{ds} \langle \alpha'(s), \vec{v}(s) \rangle = \langle \alpha'(s), \vec{v}'(s) \rangle + \langle \alpha''(s), \vec{v}(s) \rangle$, we know

$$D_{\vec{V}} \text{len}(\alpha) = \langle \alpha'(s), \vec{v}(s) \rangle \Big|_0^L - \int_0^L \langle \alpha''(s), \vec{v}(s) \rangle ds = - \int_0^L \langle \alpha''(s), \vec{v}(s) \rangle ds$$

($\Leftarrow$) Now, if α is a geodesic, then $\alpha'' \perp T_{\alpha(s)}\Sigma$. Since $\vec{v}(s) \in T_{\alpha(s)}\Sigma$, we see that $\langle \alpha''(s), \vec{v}(s) \rangle = 0$ $\forall s$, so $D_{\vec{V}} \text{len}(\alpha) = 0$.

($\Rightarrow$) OTOH, suppose $D_{\vec{V}} \text{len}(\alpha) = 0$ for all $\vec{V}$ satisfying the boundary conditions. Then for γ such $\vec{V}$ we have $\int_0^L \langle \alpha''(s), \vec{v}(s) \rangle ds = 0$.

But this will mean $\alpha''(s) \perp T_{\alpha(s)}\Sigma$. After all, if it weren't then we could choose $\vec{v}(s)$ to agree w/ the projection of $\alpha''(s)$ to $T_{\alpha(s)}\Sigma$ so that $\vec{v}(s) = \vec{0}$ outside a nbd of $\alpha(s)$. But then $\int_0^L \langle \alpha''(s), \vec{v}(s) \rangle ds > 0$, a contradiction. $\square$