

# Math 474 HW #6

Due 2:00 PM Friday, Dec. 11

1. The goal of this problem is to determine which surfaces of revolution have constant Gaussian curvature. Suppose the surface of revolution  $\Sigma$  has parametrization

$$\vec{x}(u, v) = (\phi(v) \cos u, \phi(v) \sin u, \psi(v)),$$

where the template curve  $\alpha(s) = (\phi(s), 0, \psi(s))$  is parameterized by arclength (which of course means that  $(\phi')^2 + (\psi')^2 = 1$ ). The goal is to solve for  $\phi$  and  $\psi$  so that  $\Sigma$  has constant Gaussian curvature  $K$ .

- (a) Prove that  $\phi$  and  $\psi$  satisfy

$$\phi''(v) + K\phi(v) = 0 \quad \text{and} \quad \psi(v) = \int_0^v \sqrt{1 - (\phi'(t))^2} dt.$$

- (b) Now assume  $K = 1$  and show that, assuming the initial condition  $\phi'(0) = 0$ , the solutions of the equations from (a) are

$$\phi(v) = C \cos v \quad \text{and} \quad \psi(v) = \int_0^v \sqrt{1 - C^2 \sin^2 t} dt,$$

where  $C$  is a constant. Obviously,  $\psi(v)$  is not defined for all  $v$ ; find the domain of  $\psi(v)$  (which depends on  $C$ ) and sketch the curve  $\alpha(s) = (\phi(s), 0, \psi(s))$  for  $C < 1$ ,  $C = 1$ , and  $C > 1$  (feel free to use Mathematica, Maple, Matlab, Wolfram Alpha, etc. for this). Show that only the  $C = 1$  surface can be rotated around the  $z$ -axis to get a compact regular surface.

- (c) Now assume  $K = -1$  and show that  $\phi$  and  $\psi$  satisfy one of the following set of equations:

$$\phi(v) = C \cosh v \quad \text{and} \quad \psi(v) = \int_0^v \sqrt{1 - C^2 \sinh^2 t} dt \quad (1)$$

$$\phi(v) = C \sinh v \quad \text{and} \quad \psi(v) = \int_0^v \sqrt{1 - C^2 \cosh^2 t} dt \quad (2)$$

$$\phi(v) = e^v \quad \text{and} \quad \psi(v) = \int_0^v \sqrt{1 - e^{2t}} dt. \quad (3)$$

In each case, determine the domain of  $\psi(v)$  and sketch the resulting surface.

- (d) Finally, assume  $K = 0$ . Prove that the only solutions are the cylinder, the cone, and the plane.

2. Show that if  $F = 0$  then the Gaussian curvature  $K$  of a surface  $\Sigma$  is given by

$$K = -\frac{1}{2\sqrt{EG}} \left[ \frac{\partial}{\partial v} \left( \frac{E_v}{\sqrt{EG}} \right) + \frac{\partial}{\partial u} \left( \frac{G_u}{\sqrt{EG}} \right) \right].$$

3. Let  $\Sigma$  be an oriented regular surface and let  $\alpha(s)$  be an arclength parametrized curve on  $\Sigma$ . Since  $\alpha$  lies on  $\Sigma$ , we know that  $\alpha'(s) = T(s) \in T_{\alpha(s)}\Sigma$ , and in particular  $T(s)$  is perpendicular to the surface normal  $N_{\Sigma}(s)$ .

The *Darboux frame* of  $\alpha$  is defined to be the triple of vectors

$$(T(s), V(s) = N_{\Sigma}(s) \times T(s), N_{\Sigma}(s)).$$

Like the Frenet frame, this frame's derivatives give information about the local geometry of  $\alpha$ , but now that information relates also to how  $\alpha$  lies in  $\Sigma$ .

- (a) Show that the Darboux frame satisfies a system of equations vaguely similar to the Frenet equations:

$$\begin{aligned} T' &= a(s)V(s) + b(s)N_{\Sigma}(s) \\ V' &= -a(s)T + c(s)N_{\Sigma}(s) \\ N'_{\Sigma} &= -b(s)T - c(s)V(s) \end{aligned}$$

for some coefficient functions  $a(s)$ ,  $b(s)$ , and  $c(s)$ , which interpret in the following parts.

- (b) Show that  $c(s) = -\langle N'_{\Sigma}, V \rangle$ . In particular,  $\alpha$  is a line of curvature if and only if  $c(s) = 0$ . The function  $-c(s)$  is called the *geodesic torsion* for obvious reasons.
- (c) Show that  $b(s)$  is the normal curvature  $\kappa_n$  of  $\alpha$ .
- (d) Show that  $a(s)$  is the geodesic curvature  $\kappa_g$  of  $\alpha$ .

4. Let  $\Sigma$  be the hyperboloid of revolution

$$\vec{x}(u, v) = (\cosh v \cos u, \cosh v \sin u, \sinh v),$$

which can also be described implicitly by the equation  $x^2 + y^2 - z^2 = 1$ . Suppose  $\alpha(s)$  is a geodesic on  $\Sigma$  which makes the angle  $\phi(s)$  with the  $\vec{x}_u$  direction at the point  $\alpha(s) = \vec{x}(u(s), v(s))$  and that the angle  $\phi(s)$  satisfies

$$\cos(\phi(s)) = \frac{1}{\cosh(v(s))}.$$

Show that the geodesic  $\alpha$  spirals asymptotically into the circle  $v = 0$ .