

Math 369: Day 7

So far we've just been thinking of matrices as ways of encoding systems of equations, but another way to look at them is as **transformations**.

Suppose A is an $m \times n$ matrix. Then we know that we can multiply A by an n -dimensional vector $\vec{v} \in \mathbb{R}^n$ & get a new vector $A\vec{v}$ which is m -dimensional.

In other words, A induces a mapping $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ where $T_A(\vec{v}) = A\vec{v}$ it's a machine for turning n -dim vectors into m -dim vectors.

This mapping has nice properties:

- ① $T_A(\vec{0}) = \vec{0}$ b/c $A\vec{0} = \vec{0}$
- ② $T_A(c\vec{v}) = cT_A(\vec{v})$ b/c $A(c\vec{v}) = cA\vec{v}$
- ③ $T_A(\vec{v} + \vec{w}) = T_A(\vec{v}) + T_A(\vec{w})$ b/c $A(\vec{v} + \vec{w}) = A\vec{v} + A\vec{w}$

Together, these mean that T_A is a **linear transformation**.

What does T_A do to a vector $\vec{v}$?

As an algebraic expression, this is kind of obvious: you get whatever formula you get for $A\vec{v}$.

Ex: $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$. Then if $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$, $T_A(\vec{v}) = A\vec{v} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_1 + 2v_2 \\ 3v_1 + 4v_2 \end{bmatrix}$

What does this mean? Well, notice that $\begin{bmatrix} v_1 + 2v_2 \\ 3v_1 + 4v_2 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + v_2 \begin{bmatrix} 2 \\ 4 \end{bmatrix}$, so T_A sends $\vec{v}$ to the linear combination of the columns of A with coefficients given by the entries of $\vec{v}$.

So another way to look at an equation like $A\vec{x} = \vec{b}$ is to say that this says $\vec{b}$ can be written as a linear combination of the columns of A .

So for example if we solve $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 11 \end{bmatrix}$, we see that $x_1 = 1$, $x_2 = 2$, & so $\begin{bmatrix} 5 \\ 11 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 2 \begin{bmatrix} 2 \\ 4 \end{bmatrix}$.

So now we might ask questions like: is there some linear combination of the vectors $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ & $\begin{bmatrix} 2 \\ 4 \end{bmatrix}$ that produces the vector $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$?

Well, if there were, we'd have $\begin{bmatrix} -1 \\ 3 \end{bmatrix} = x \begin{bmatrix} 1 \\ 3 \end{bmatrix} + y \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ for some x & y , so

$$\begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} x+2y \\ 3x+4y \\ 5x+6y \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix},$$

so it boils down to solving $\begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 3 \end{pmatrix}$.

If $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}$ were invertible, we'd know there is a solution, namely $\bar{x} = A^{-1} \begin{pmatrix} -1 \\ -1 \\ 3 \end{pmatrix}$. But A isn't a square matrix so it can't be invertible, & need to solve another way:

$$\leadsto \left[\begin{array}{cc|c} 1 & 2 & -1 \\ 3 & 4 & -1 \\ 5 & 6 & 3 \end{array} \right] \xrightarrow{\substack{[2] \rightarrow [2] + (-3)[1] \\ [3] \rightarrow [3] + (-5)[1]}} \left[\begin{array}{cc|c} 1 & 2 & -1 \\ 0 & -2 & 4 \\ 0 & -4 & 8 \end{array} \right] \Rightarrow \begin{cases} -2x_2 = 4 \\ -4x_2 = 8 \end{cases} \Rightarrow x_2 = -2 \Rightarrow \begin{aligned} x_1 + 2x_2 &= -1 \\ \text{so } x_1 + 2(-2) &= -1 \\ x_1 - 4 &= -1 \\ x_1 &= 3 \end{aligned}$$

so $x_1 = 3$, $x_2 = -2$ work, & indeed we see that $3 \begin{pmatrix} 1 \\ 3 \\ 5 \end{pmatrix} - 2 \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 3 \end{pmatrix}$

In terms of the transformation T_A , a vector $\bar{b} \in \mathbb{R}^m$ can either be in the **range** of T_A or not, accordingly to whether $A\bar{x} = \bar{b}$ is solvable or not or, equivalently, to whether $\bar{b}$ can be written as a linear combination of the columns of A or not.

If A is invertible, then $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^n$ & $A\bar{x} = \bar{b}$ is always solvable, so the range of T_A is **all** of $\mathbb{R}^n$.