

# The Symplectic Geometry of Polygon Space

Clayton Shonkwiler and Jason Cantarella

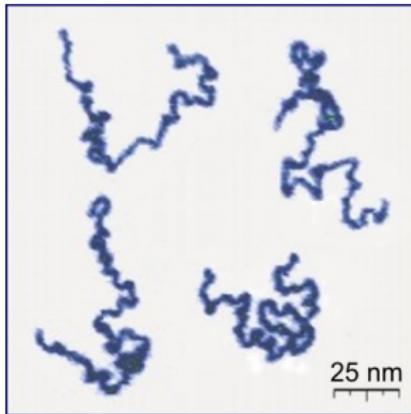
University of Georgia

Workshop on Geometric Knot Theory  
Oberwolfach  
April 29, 2013

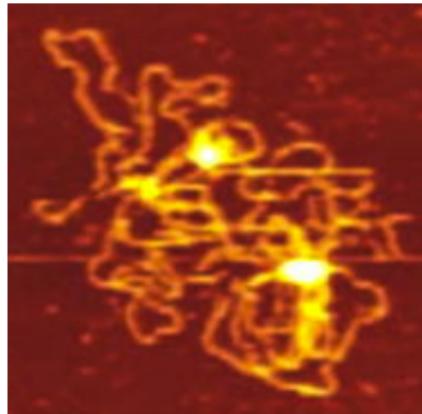
# Random Polygons (and Polymer Physics)

## Physics Question

*What is the average shape of a polymer in solution?*



Protonated P2VP  
Roiter/Minko  
Clarkson University



Plasmid DNA  
Alonso-Sarduy, Dietler Lab  
EPF Lausanne

# Random Polygons (and Polymer Physics)

## Physics Question

*What is the average shape of a polymer in solution?*

## Physics Answer

*Modern polymer physics is based on the analogy between a polymer chain and a random walk.*

*—Alexander Grosberg, NYU.*

# Random Polygons (and Mathematics)

## Math Question

*How can we construct random samples drawn from the space of closed space  $n$ -gons? More generally, how should we (numerically) integrate over the space of closed polygons?*



Illustration of crankshaft algorithm of Vologoskii et. al.  
Benham/Mielke

Exploit the (symplectic) geometric structure of polygon space to find good sampling algorithms for random polygons, to compute expected values, and to establish a framework for proving theorems.

Let  $\widetilde{\text{Pol}}(n; \vec{r})$  be the moduli space of closed polygons in  $\mathbb{R}^3$  with edgelenhs given by the vector  $\vec{r} = (r_1, \dots, r_n)$  up to translation.

### Proposition

$\widetilde{\text{Pol}}(n; \vec{r})$  is the codimension-three submanifold of  $\text{Arm}(n, \vec{r}) = \prod_{i=1}^n S^2(r_i)$  determined by the linear equation

$$\sum_{i=1}^n \vec{e}_i = \vec{0}$$

where  $\vec{e}_i$  is the  $i$ th edge of the polygon.

The geometry of this space seems difficult to get our hands on.

## Theorem (Kapovich–Millson, 1996)

$\text{Pol}(n; \vec{r})$  is the symplectic reduction of  $\prod_{i=1}^n S^2(r_i)$  by the (Hamiltonian) diagonal  $SO(3)$  action.

*In particular,  $\text{Pol}(n; \vec{r})$  is a  $(2n - 6)$ -dimensional symplectic manifold.*

*Moreover, the Liouville measure induced by the symplectic structure agrees with standard measure.*

# Symplectic Geometry Review

Recall that a symplectic manifold  $(M^{2n}, \omega)$  consists of an even-dimensional manifold together with a closed 2-form  $\omega$  such that  $\omega^n \neq 0$ . A *symplectomorphism* is a diffeomorphism which preserves the symplectic form.

A torus  $T^k$  which acts by symplectomorphisms on  $M$  so that the action is Hamiltonian induces a *moment map*  $\mu : M \rightarrow \mathbb{R}^k$  where the action preserves the fibers.

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**Theorem (Atiyah, Guillemin–Sternberg, 1982)**

*The image of  $\mu$  is a convex polytope in  $\mathbb{R}^k$  called the moment polytope.*

**Theorem (Duistermaat–Heckman, 1982)**

*The pushforward of Liouville measure to the moment polytope is piecewise polynomial. If  $k = n$  the manifold is called a toric symplectic manifold and the pushforward measure is a constant multiple of Lebesgue measure.*

# A Down-to-Earth Example

Let  $(M, \omega)$  be the 2-sphere with the standard area form. Let  $T^1 = S^1$  act by rotation around the  $z$ -axis. Then the moment polytope is the interval  $[-1, 1]$ .

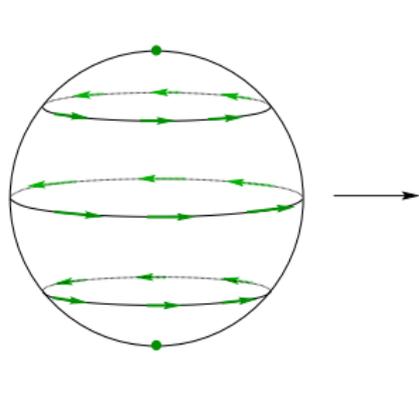


Illustration by Holm.

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**Theorem (Archimedes, Duistermaat–Heckman)**

*The pushforward of the standard measure on the sphere to the interval is  $2\pi$  times Lebesgue measure.*

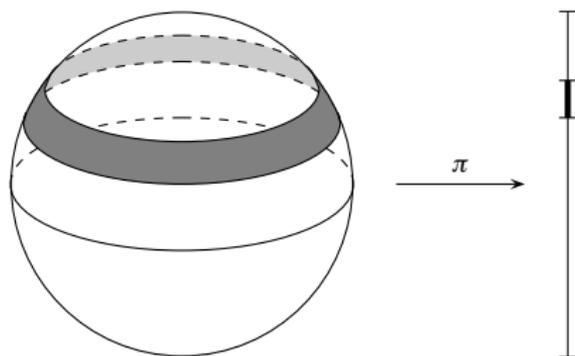


Illustration by Kuperberg.

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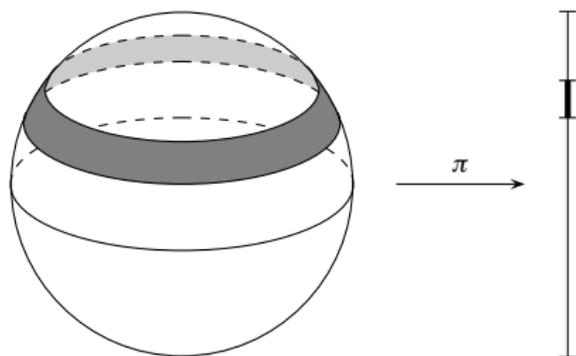


Illustration by Kuperberg.

We can sample uniformly on  $S^2$  by choosing  $z$  and  $\theta$  coordinates independently and uniformly.

# A Sampling Algorithm for Toric Symplectic Manifolds

More generally, if  $M^{2n}$  is a toric symplectic manifold with moment polytope  $P \subset \mathbb{R}^n$ , then the inverse image of each point in  $P$  is an  $n$ -torus. This yields

$$\alpha : P \times T^n \rightarrow M$$

which parametrizes a full-measure subset of  $M$  by so-called “action-angle coordinates”.

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## Proposition

*The map  $\alpha : P \times T^n \rightarrow M$  is measure-preserving.*

Therefore, we can sample  $M$  with respect to Liouville measure by sampling  $P$  and  $T^n$  independently and uniformly.

# A Toric Structure on the Space of Arms

The torus  $T^n$  acts on  $\widetilde{\text{Arm}}(n; \vec{r}) = \prod_{i=1}^n S^2(r_i)$ , the space of open polygons in space up to translation, by spinning each factor around the  $z$ -axis. This action is Hamiltonian, with moment polytope the hypercube

$$\prod_{i=1}^n [-r_i, r_i]$$

which records the  $z$ -coordinate  $z_i$  of each edge  $\vec{e}_i$ .

## Proposition (with Cantarella)

Let  $p \in \widetilde{\text{Arm}}(n; \vec{r})$ . Then the length  $\ell \in [0, \sum r_i]$  of the failure-to-close vector  $\vec{e}_1 + \dots + \vec{e}_n$  has pdf

$$\phi(\ell) = -2\ell f'_n(\ell),$$

where

$$f_n(x) = \frac{1}{\prod_{i=1}^n 2r_i} \frac{1}{\sqrt{n}} \text{SA}(x, r_1, \dots, r_n)$$

is the pdf of the sum of uniform random variates  $z_1 + \dots + z_n$ .

Here  $\text{SA}(x, r_1, \dots, r_n)$  is the volume of the slice of the hypercube  $\prod_{i=1}^n [-r_i, r_i]$  by the plane  $\sum_{i=1}^n x_i = x$ .

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## Corollary (Pólya, 1912)

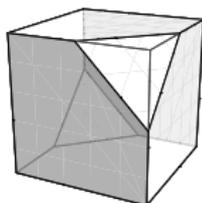
$$\phi(\ell) = \frac{2\ell}{\pi} \int_0^\infty y \sin \ell y \text{sinc}^n y \, dy$$

## Proposition (with Cantarella)

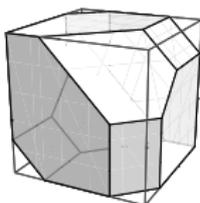
A polygon  $p \in \text{Arm}(n; \vec{1})$  is confined to a slab of width  $h$  if and only if the vector  $\vec{z} = (z_1, \dots, z_n)$  of action variables lies in the parallelotope determined by the inequalities

$$-1 \leq \langle \vec{z}, \vec{x}_i \rangle \leq 1, \quad -h \leq \langle \vec{z}, \vec{w}_{ij} \rangle \leq h$$

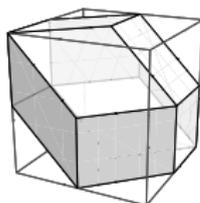
where  $\vec{w}_{ij} = \sum_{k=1}^j \vec{e}_k$ . Hence, such arms can be uniformly sampled using the sampling algorithm for toric manifolds.



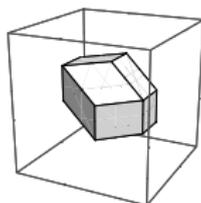
$$h = 2$$



$$h = \frac{3}{2}$$



$$h = 1$$

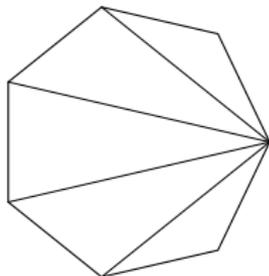


$$h = \frac{1}{2}$$

# A Toric Structure on Polygon Space

## Theorem (Kapovich and Millson, 1996)

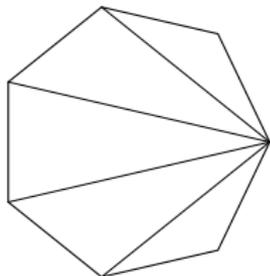
*Any triangulation  $T$  of the standard  $n$ -gon yields a Hamiltonian action of  $T^{n-3}$  on  $\text{Pol}(n; \vec{r})$  where the angle  $\theta_i$  acts by folding the polygon around the  $i$ th diagonal of the triangulation.*



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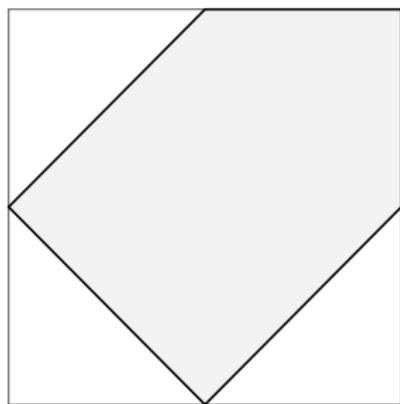
*The moment map  $\mu : \text{Pol}(n; \vec{r}) \rightarrow \mathbb{R}^{n-3}$  records the lengths  $d_i$  of the diagonals of the triangulation.*

*The portion of  $\text{Pol}(n; \vec{r})$  in the inverse image of the interior of the moment polytope is an (open) toric symplectic manifold.*

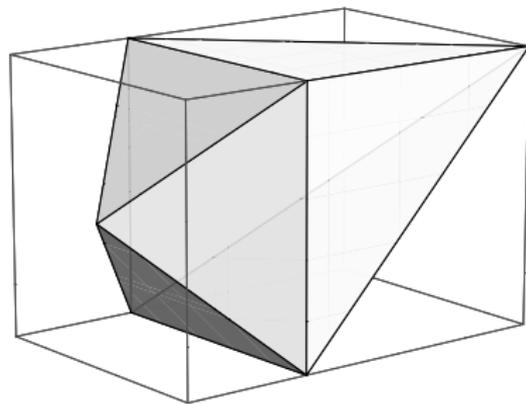
The moment polytope corresponding to a fan triangulation is determined by the “fan triangulation inequalities”

$$0 \leq d_1 \leq r_1 + r_2 \quad r_{i+2} \leq d_i + d_{i+1} \quad 0 \leq d_{n-3} \leq r_n + r_{n-1}$$

$$|d_i - d_{i+1}| \leq r_{i+2}$$



Moment polytope for  $\text{Pol}(5; \vec{1})$



Moment polytope for  $\text{Pol}(6; \vec{1})$

# The Volume of the Moment Polytope

Theorem (Takakura, 2001, Khoi, 2005)

*The fan triangulation polytope for  $\text{Pol}(n; \vec{r})$  has volume*

$$\frac{-1}{2(n-3)!} \sum_I (-1)^{n-|I|} \left( \sum_{i \in I} r_i - \sum_{j \notin I} r_j \right)^{n-3},$$

*where the outer sum is over all multindices  $I = (i_1, \dots, i_p)$  for  $p \leq n$  so that the term in parentheses is positive.*

Corollary

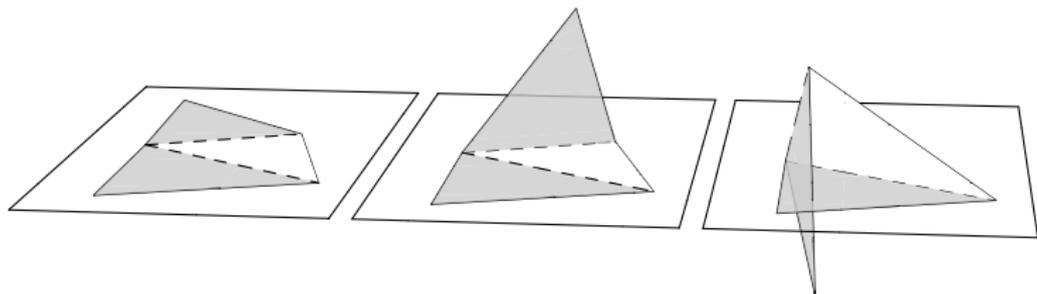
*The fan triangulation polytope for  $\text{Pol}(n; \vec{1})$  has volume*

$$\frac{-1}{2(n-3)!} \sum_{k=0}^{\lfloor n/2 \rfloor} (-1)^k \binom{n}{k} (n-2k)^{n-3}.$$

# Sampling Fixed Edgelenh Pentagons

## Proposition (with Cantarella)

*Polygons in  $\text{Pol}(n; \vec{r})$  are sampled according to the standard measure if and only if the diagonal lengths  $(d_1, \dots, d_{n-3})$  are uniformly sampled from the moment polytope and the dihedral angles are sampled independently and uniformly in  $[0, 2\pi)$ .*

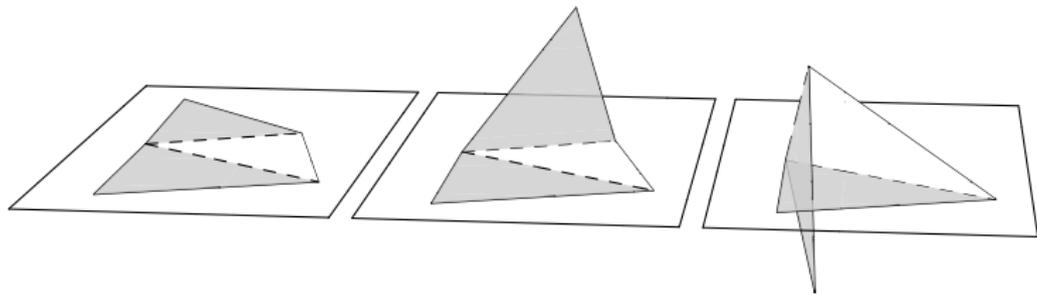


Polygons in the fiber over  $(d_1, d_2) = (1.15, 0.75)$  in the moment polytope. The middle and right pentagons correspond to bending angles  $(0, 2.2)$  and  $(2.15, 2.2)$ , respectively.

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**Note:** This gives criteria for evaluating the quality of polygon sampling algorithms!

## Definition

A polygon  $p \in \text{Pol}(n; \vec{r})$  is in *rooted spherical confinement* of radius  $r$  if each diagonal length  $d_i \leq r$ . Such a polygon is contained in a sphere of radius  $r$  centered at the first vertex.

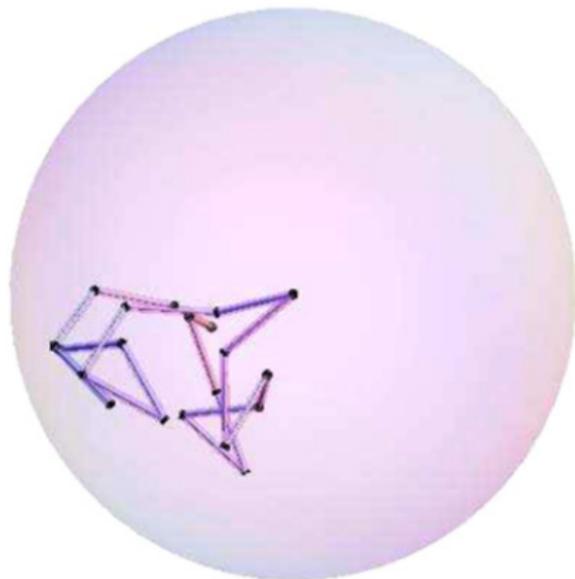


Illustration by Diao et al.

## Proposition (with Cantarella)

*Polygons in  $\text{Pol}(n; \vec{r})$  are sampled according to the standard measure on rooted sphere-confined polygons in a sphere of radius  $r$  if and only if the diagonal lengths  $(d_1, \dots, d_{n-3})$  are uniformly sampled from the polytope determined by both the fan triangulation inequalities*

$$0 \leq d_1 \leq r_1 + r_2 \quad r_{i+2} \leq d_i + d_{i+1} \quad 0 \leq d_{n-3} \leq r_n + r_{n-1} \\ |d_i - d_{i+1}| \leq r_{i+2}$$

*and the additional linear inequalities*

$$d_i \leq r$$

*and the dihedral angles **around those diagonals** are sampled independently and uniformly in  $[0, 2\pi)$ .*

## Definition

Let  $\text{ChordLength}(k, n; \vec{r})$  be the length of the chord skipping the first  $k$  edges in a polygon sampled according to the standard measure on  $\text{Pol}(n; \vec{r})$ .

## Proposition (with Cantarella and Deguchi, Millett and Zirbel, 2012)

*The second moment of the random variable  $\text{ChordLength}(k, n; \vec{1})$  is  $\frac{k(n-k)}{n-1}$ . This implies the expected squared radius of gyration of an equilateral  $n$ -gon is  $\frac{n+1}{12}$ .*

## Proposition (with Cantarella)

*The  $p$ th moment of  $\text{ChordLength}(k, n; \vec{1})$  is given by the  $(k-1)$ st coordinate of the  $p$ th center of mass of the equilateral fan polytope.*

# ChordLength( $k, n; \vec{1}$ ) for Small $n$

Expected Value of ChordLength( $k, n; \vec{1}$ ) for various values of  $n$  and  $k$  computed using `polymake`

$n$	$k$							
	2	3	4	5	6	7	8	
4	1							
5	$\frac{17}{15}$	$\frac{17}{15}$						
6	$\frac{7}{6}$	$\frac{5}{4}$	$\frac{7}{6}$					
7	$\frac{461}{385}$	$\frac{46}{35}$	$\frac{46}{35}$	$\frac{461}{385}$				
8	$\frac{73}{60}$	$\frac{1,307}{960}$	$\frac{7}{5}$	$\frac{1,307}{960}$	$\frac{73}{60}$			
9	$\frac{112,121}{91,035}$	$\frac{42,353}{30,345}$	$\frac{133,337}{91,035}$	$\frac{133,337}{91,035}$	$\frac{42,353}{30,345}$	$\frac{112,121}{91,035}$		
10	$\frac{6,091}{4,900}$	$\frac{111,499}{78,400}$	$\frac{1,059}{700}$	$\frac{24,197}{15,680}$	$\frac{1,059}{700}$	$\frac{111,499}{78,400}$	$\frac{6,091}{4,900}$	

# Hit-and-Run Sampling for Convex Polytopes

Suppose  $P \subset \mathbb{R}^n$  is a convex polytope given as the intersection of a collection of linear inequalities. The hit-and-run algorithm for sampling  $P$  is the following:

- Given  $\vec{p}_i \in P$ , choose a random line  $\ell$  through  $\vec{p}_i$ .
- Sample  $\ell \cap P$  uniformly to find  $\vec{p}_{i+1}$ .
- Iterate.

## Proposition (Lovász, 1999)

*After appropriate preprocessing, hit-and-run produces an approximately uniformly distributed sample point on an arbitrary convex polytope in time  $O^*(n^3)$ . The constant depends on the square of the ratio of the inradius and circumradius.*

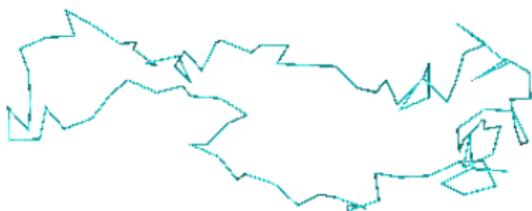
# A Moment Polytope Sampling Algorithm

To sample fixed edgelenh (confined or not)  $n$ -gons, we can

- Generate points in the  $(n - 3)$ -dimensional moment polytope using hit-and-run.
- Pair each such point with  $n - 3$  independent uniform dihedral angles and construct the associated polygon.

Optimizations are probably possible. For example, permuting edges between steps of hit-and-run seems to speed things up a lot.

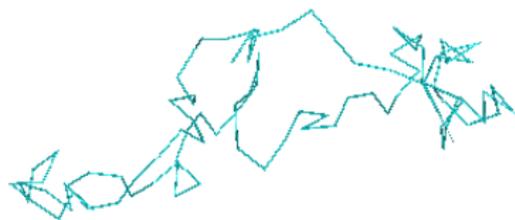
# Unconfined 100-gons



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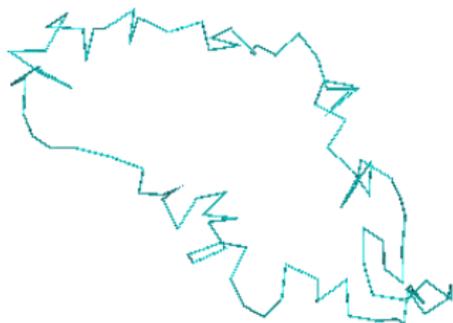
# 50-confined 100-gons



# 50-confined 100-gons



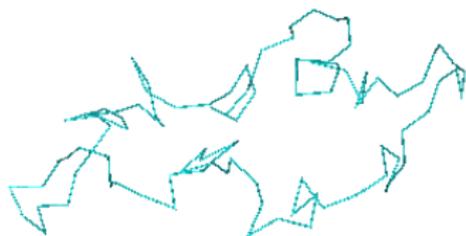
# 50-confined 100-gons



# 50-confined 100-gons



# 20-confined 100-gons



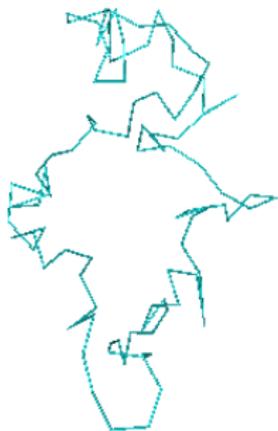
# 20-confined 100-gons



# 20-confined 100-gons



# 20-confined 100-gons



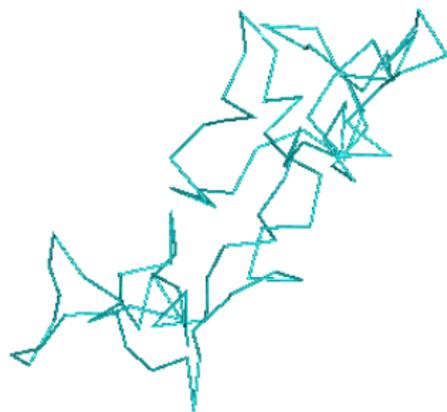
# 10-confined 100-gons



# 10-confined 100-gons



# 10-confined 100-gons



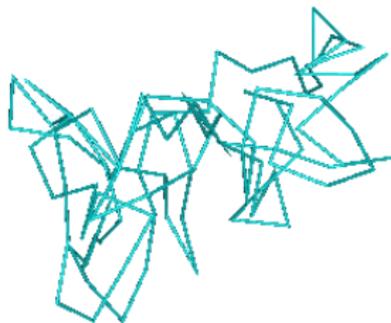
# 10-confined 100-gons



# 5-confined 100-gons



# 5-confined 100-gons



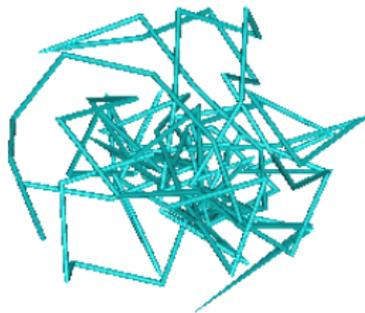
# 5-confined 100-gons



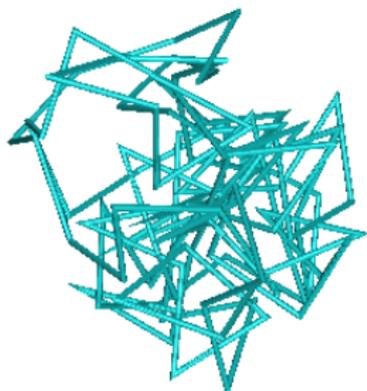
# 5-confined 100-gons



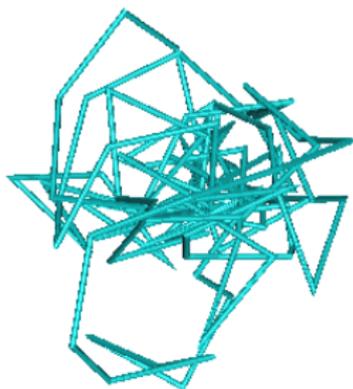
## 2-confined 100-gons



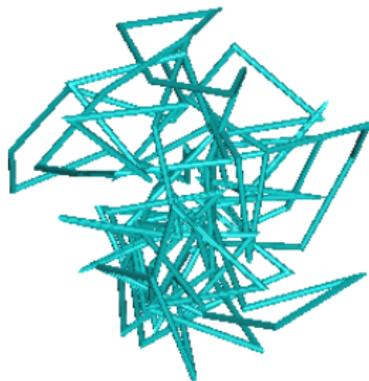
## 2-confined 100-gons



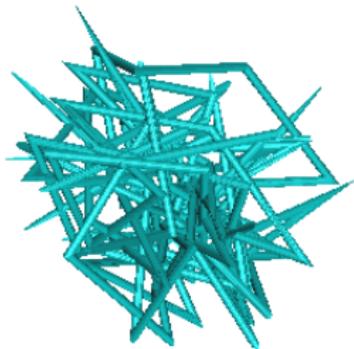
## 2-confined 100-gons



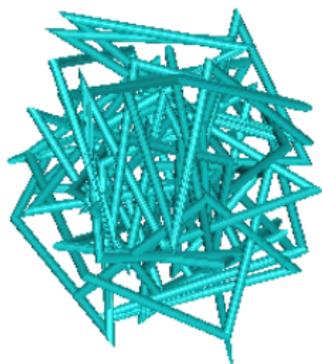
## 2-confined 100-gons



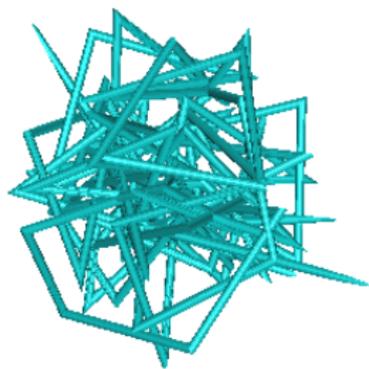
# 1.1-confined 100-gons



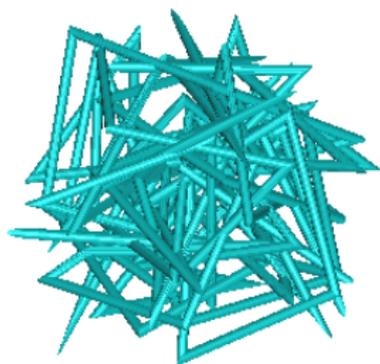
# 1.1-confined 100-gons



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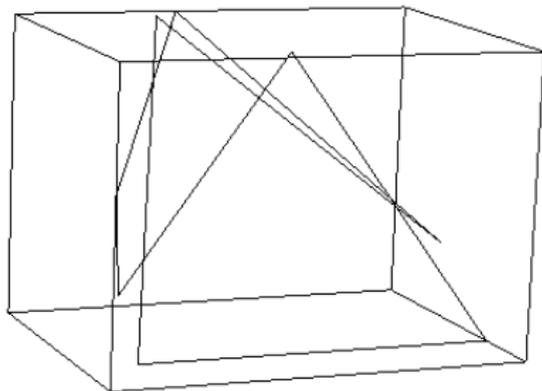


# 1.1-confined 100-gons

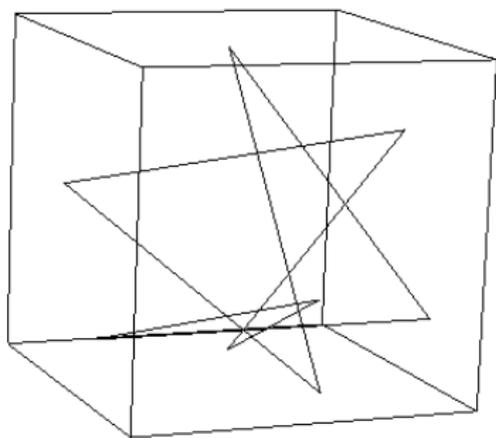


- Can we find bounds on the volume of the space of slab-confined arms? Does this give bounds on the energy required to confine a polymer?
- Can we find bounds on the volume of the space of confined closed polygons? Can such bounds be used to bound the probability of rare knots?
- Is there a combinatorial description of the fan triangulation polytope? This would give a direct sampling algorithm for fixed edgelenhth polygons.
- Can we compute expected values of the sedimentation coefficient or of other quantities related to moments of chordlengths?

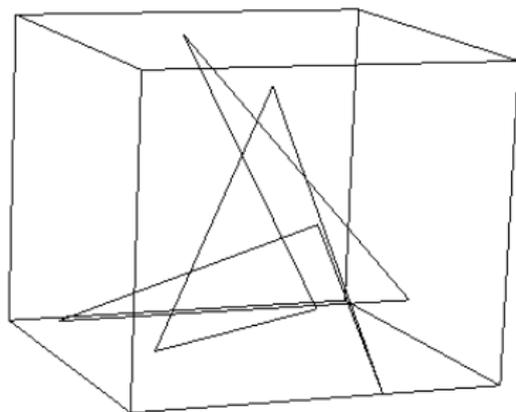
# Equilateral 8-edge $5_2$



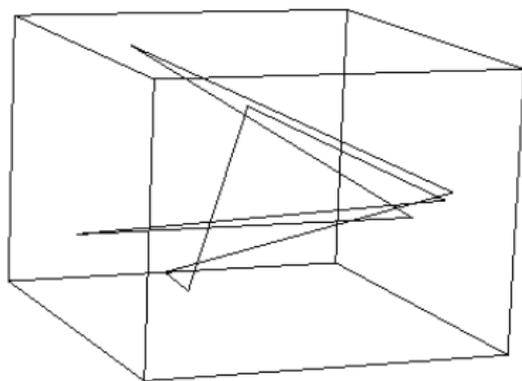
# Equilateral 8-edge $5_2$



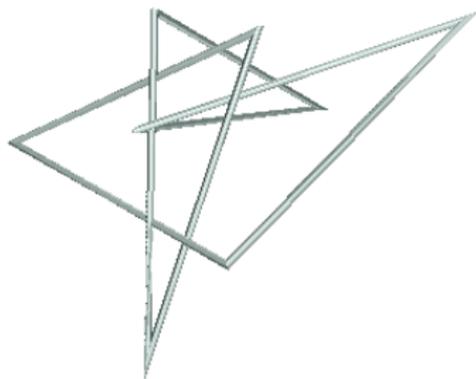
# Equilateral 8-edge $5_2$



# Equilateral 8-edge $5_2$



# Equilateral 8-edge $6_2$



- Can we find bounds on the volume of the space of slab-confined arms? Does this give bounds on the energy required to confine a polymer?
- Can we find bounds on the volume of the space of confined closed polygons? Can such bounds be used to bound the probability of rare knots?
- Is there a combinatorial description of the fan triangulation polytope? This would give a direct sampling algorithm for fixed edgelenhth polygons.
- Can we compute expected values of the sedimentation coefficient or of other quantities related to moments of chordlengths?

Thank you!

Thank you for inviting me!

- *Probability Theory of Random Polygons from the Quaternionic Viewpoint*  
Jason Cantarella, Tetsuo Deguchi, and Clayton Shonkwiler  
arXiv:1206.3161  
To appear in *Communications on Pure and Applied Mathematics*.
- *The Expected Total Curvature of Random Polygons*  
Jason Cantarella, Alexander Y. Grosberg, Robert Kusner,  
and Clayton Shonkwiler  
arXiv:1210.6537.
- *Symplectic Methods for Random Equilateral Polygons and the Moment Polytope Sampling Algorithm*  
Jason Cantarella and Clayton Shonkwiler  
In preparation.