

Chapter 1

Numerical decomposition of the rank-deficiency set of a matrix of multivariate polynomials

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Abstract Let A be a matrix whose entries are algebraic functions defined on a reduced quasiprojective algebraic set X , e.g., multivariate polynomials defined on $X := \mathbb{C}^N$. The sets $\mathcal{S}_k(A)$, consisting of $x \in X$ where the rank of the matrix function $A(x)$ is at most k , arise in a variety of contexts. For example, in the description of both the singular locus of an algebraic set and its fine structure; in the description of the degeneracy locus of maps between algebraic sets; and in the computation of the irreducible decomposition of the support of coherent algebraic sheaves, e.g., supports of finite modules over polynomial rings. In this article we present a numerical algorithm to efficiently compute the sets $\mathcal{S}_k(A)$.

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Introduction

Let A be an $m \times n$ matrix with polynomial entries, i.e.,

$$A(x) := \begin{bmatrix} p_{1,1}(x) & \cdots & p_{1,n}(x) \\ \vdots & \ddots & \vdots \\ p_{m,1}(x) & \cdots & p_{m,n}(x) \end{bmatrix} \quad (1.1)$$

with $p_{i,j}(x) \in \mathbb{C}[x_1, x_2, \dots, x_N]$ for $1 \leq i \leq m$, $1 \leq j \leq n$; and where $x := (x_1, x_2, \dots, x_N) \in \mathbb{C}^N$.

The main contribution of this article is an efficient numerical algorithm to decompose the algebraic sets

$$\mathcal{S}_k(A) := \{x \in \mathbb{C}^N \mid \text{rank}A(x) \leq k\} \quad (1.2)$$

for each k from 0 to $\min\{m, n\}$. By computing the sets $\mathcal{S}_k(A)$, we also compute the algebraic subsets of \mathbb{C}^N where the rank of $A(x)$ equals k , i.e., $\mathcal{S}_k(A) \setminus \mathcal{S}_{k-1}(A)$. By taking adjoints and relabeling if necessary, we may assume that $m \geq n$. By convention, $\mathcal{S}_{-1}(A) := \emptyset$.

We work in the general setting of finding the irreducible decompositions of sets of the form $\mathcal{S}_k(A_{V(f)})$, where f is a system of polynomials defined on \mathbb{C}^N ; $V(f)$ denotes the common zeros of f ; and $A_{V(f)}$ denotes the restriction of the matrix of polynomials in Eq. 1.1 to $V(f)$. One advantage of this generality is that many related problems may be restated in this context. For example, given a matrix $\widehat{A}(x)$ of homogeneous polynomials on \mathbb{P}^N with degrees of entries compatible with the rank of $\widehat{A}(x)$ being well defined for each $x \in \mathbb{P}^N$, the irreducible components of $\mathcal{S}_k(\widehat{A})$ may be computed by regarding \widehat{A} as a matrix of polynomials on \mathbb{C}^{N+1} with $f(x)$ a single linear equation on \mathbb{C}^{N+1} having general coefficients.

In §1.1, we present background material. Besides reviewing the general setup of Numerical Algebraic Geometry, we highlight several results we will use in the article. In §1.2 we give a description of random coordinate patches on Grassmannians. This is a useful generalization of random coordinate patches for projective space [18], see also [30, §3.7]. The generalization applies more broadly to rational homogeneous manifolds.

The strategy of the algorithm presented in §1.3 is to work with the system

$$\begin{bmatrix} f(x) \\ A(x) \cdot \xi \end{bmatrix} = 0, \quad (1.3)$$

where

$$f(x) := \begin{bmatrix} f_1(x) \\ \vdots \\ f_m(x) \end{bmatrix} \quad (1.4)$$

is a system of polynomials on \mathbb{C}^N and where

$$A(x) \cdot \xi \quad (1.5)$$

is a parameterized family of ξ -linear equations with

$$\xi := \begin{bmatrix} \xi_1 \\ \vdots \\ \xi_n \end{bmatrix} \in \mathbb{P}^{n-1}.$$

This is a standard construct which has been used multiple times in numerical algebraic geometry, though in cases much weaker information was sought. For example, systems which include terms of the form $A(x) \cdot \xi = 0$, have occurred for deflation [15] and [30]; and for the degeneracy set of a map from a curve to \mathbb{C} , [16] and [2].

Using Eq. 1.5, one can compute the components of the set $\mathcal{S}_{n-1}(A)$ as the images of the irreducible components of the reduced solution set of Eq. 1.3: this is straightforward using the numerical irreducible decomposition available in Bertini [1] or PHC [32]. The computation of the components of the remaining $\mathcal{S}_k(A)$ is more subtle.

A natural approach to computing the structure of the sets $\mathcal{S}_k(A)$ would be to decompose the projection map $V(A(x) \cdot \xi) \rightarrow \mathbb{C}^N$ into sets of constant dimension. This can be done using fiber products [31]. However, since the fibers of the map $V(A(x) \cdot \xi) \rightarrow \mathbb{C}^N$ are linear subspaces of \mathbb{C}^N , it is natural to use Grassmannians to parameterize fibers of a given dimension. This leads to a considerably simpler and more efficient algorithm than the general fiber product approach.

Let $\text{Grass}(a, b)$ be the Grassmannian of a -dimensional vector subspaces of \mathbb{C}^b ; and let

$$\mathbb{T}(n; k, N) := \mathbb{C}^N \times \text{Grass}(n-k, n),$$

where n denotes the number of columns of $A(x)$. We consider the algebraic subset

$$\mathcal{E}_k(A) := \{(x, y) \in \mathbb{T}(n; k, N) \mid A(x) \cdot y = 0\}.$$

Let $\pi : \mathbb{C}^N \times \text{Grass}(n-k, n) \rightarrow \mathbb{C}^N$ be the map obtained by restricting the product projection from $\mathbb{C}^N \times \text{Grass}(n-k, n)$ to \mathbb{C}^N . The irreducible components of $\mathcal{S}_k(A)$ that are not irreducible components of $\mathcal{S}_{k-1}(A)$ are precisely the images under π

of irreducible components of $\mathcal{E}_k(A)$ on which π is generically one-to-one. Thus, the problem reduces to setting up a polynomial system to compute $\mathcal{E}_k(A)$.

To set up this system we construct a coordinate system on a Zariski open set $U \subset \text{Grass}(n-k, n)$ such that every irreducible component of $\mathcal{S}_k(A)$ that is not an irreducible component of $\mathcal{S}_{k-1}(A)$ is the closure of the image of an irreducible component of $\mathcal{E}_k(A)$ under the product projection π . This construction uses the random coordinate patches described in §1.2 and leads to the system

$$A(x) \cdot B \cdot \begin{bmatrix} I_{n-k} \\ \Xi \end{bmatrix} = 0, \quad (1.6)$$

where B is a generic $n \times n$ unitary matrix; I_{n-k} is the $(n-k) \times (n-k)$ identity matrix; and where

$$\Xi := \begin{bmatrix} \xi_{1,1} & \cdots & \xi_{1,n-k} \\ \vdots & \ddots & \vdots \\ \xi_{k,n-k} & \cdots & \xi_{k,n-k} \end{bmatrix},$$

is an element of $\mathbb{C}^{k \times (n-k)}$. The solution components of the reduced solution set of Eq. 1.6 give the desired decomposition of $\mathcal{E}_k(A)$.

The system

$$\begin{bmatrix} f(x) \\ A(x) \cdot B \cdot \begin{bmatrix} I_{n-k} \\ \Xi \end{bmatrix} \end{bmatrix} = 0 \quad (1.7)$$

allows us to compute the decomposition of $\mathcal{S}_k(A(x)_{V(f)})$.

In §1.4, we discuss several generalizations. For example, we may compute the decomposition of $\mathcal{S}_k(A(x)_X)$, where X is an irreducible component of $V(f)$. We also show how to deal with more general $A(x)$, e.g., $A(x)$ having entries that are algebraic functions on algebraic sets, or when $A(x)$ is a map between vector bundles.

In §1.5, we present several applications. For example, if $f(x)$ is a system of polynomials on \mathbb{C}^N , then applying the algorithm of §1.3 to the Jacobian

$$Jf(x) := \begin{bmatrix} \frac{\partial f_1}{\partial x_1}(x) & \cdots & \frac{\partial f_1}{\partial x_N}(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1}(x) & \cdots & \frac{\partial f_m}{\partial x_N}(x) \end{bmatrix} \quad (1.8)$$

computes the decomposition of the singular set of the solution set $f^{-1}(0)$ of f . Note in this case that $n = N$. We use $f^{-1}(0)$ to denote the solution set of $f(x) = 0$ with its induced scheme-theoretic structure, i.e., the scheme-theoretic fiber of $f: \mathbb{C}^N \rightarrow \mathbb{C}^m$. If a component Z of $V(f)$ occurs with multiplicity at least two, then Z is contained in the singular set of $f^{-1}(0)$.

In §1.6, we give implementation details and computational results in the context of several specific examples.

In appendix 1.7, we show how to compute the singular set, $\text{Sing}(V(f))$, of the reduced algebraic set $V(f)$, i.e., of the solution set of the radical of the ideal gen-

erated by $f(x)$. We first recall in §1.7.1 that given an irreducible component Z of a solution set $V(f)$ of a system of polynomials, there is a classical prescription, e.g., given in [19], to construct a system of polynomials g with $Z = V(g)$. Then in §1.7.2, a modified version of this construction is combined with the algorithm in §1.3 to give an algorithm to compute the singular set of $V(f)$.

1.1 Background Material

We work over the complex numbers. By an algebraic set we mean a possibly nonreduced quasiprojective algebraic set X . The reduction of X is denoted by X_{red} .

Let f be a system of polynomials

$$f(x) := \begin{bmatrix} f_1(x) \\ \vdots \\ f_{N-k}(x) \end{bmatrix} = 0 \quad (1.9)$$

on \mathbb{C}^N . By $f^{-1}(0)$ we denote the solution set of f with its possibly nonreduced structure. By $V(f)$ we denote the reduced algebraic set $f^{-1}(0)_{\text{red}}$.

An algebraic set X is irreducible if it has no embedded components and if the smooth points of its reduction X_{red} are connected. By the dimension of X , we mean the maximum of the dimensions of the connected components of the set of smooth points of X_{red} . We say that an algebraic set is *pure dimensional* if it has no embedded components and if the connected components of the set of smooth points of X_{red} all have the same dimension. Given a function $G : A \rightarrow B$ between sets, we denote the restriction of G to a subset $C \subset A$ by G_C .

The main approach of Numerical Algebraic Geometry is to use intersections with generic affine linear spaces to reduce problems about positive dimensional algebraic sets to finding isolated solutions by homotopy continuation.

The use of intersections with affine linear spaces has been a standard tool in algebraic geometry for well over a century, e.g., see [3]. Affine slices, e.g., lifting fibers, have been used in related ways in symbolic work, e.g., [9, 10, 14]. For further discussion of this, see [29, §2.3]

The book [30] is a good reference for on Numerical Algebraic Geometry.

1.1.1 Genericity and Randomness

A major source of efficiency in Numerical Algebraic Geometry is the use of randomness. Typically, there is an irreducible algebraic set Q , which serves as a parameter space, and some property \mathcal{P} for an object corresponding to a point in Q . We need to choose a point $q \in Q$ for which \mathcal{P} is true, though it might not hold for all pa-

parameter values. We say the property \mathcal{P} holds generically if it is true for a nonempty Zariski open set \mathcal{U} of Q .

For example, the polynomial $f(x, q) := qx - 1$ may be regarded as a family of polynomials in the variable x with parameter q in the parameter space $Q := \mathbb{C}$. The property that “ $f(x, q) = 0$ has a solution” is true except when $q = 0$. Thus, this property holds generically.

Some algorithms depend on choosing $q \in \mathcal{U}$. We typically do this using a random number generator, and refer to the object depending on the parameter chosen, e.g., a coordinate patch, as random or generic, e.g., a random coordinate patch. If our random number generator truly determines a random complex number, the probability of choosing a point in Q for which the property and the algorithm fails would be zero, and hence such algorithms are called *probability-one algorithms*. Of course, the numbers available on a computer are finite, but with error checking and use of high precision arithmetic, such algorithms may be designed to work very well. These matters are discussed further in [30].

The parameter spaces Q which we use are usually defined over \mathbb{C} , but there are times when we restrict our choice of a random point $q \in Q$ to lie in a special subset. For example, we might have a property \mathcal{P} that holds generically for points in the parameter space $\mathbb{C}^* := \mathbb{C} \setminus \{0\}$, but for reasons of numerical stability, we might prefer to choose q to be of absolute value 1. Since the subset of $S^1 := \{q \in \mathbb{C}^* \mid |q| = 1\}$, for which \mathcal{P} fails, is closed and has Lebesgue measure zero, choosing q randomly from S^1 is justified. A slight generalization of this situation, which occurs in this article, is when the parameter space Q is $\mathrm{GL}(n, \mathbb{C})$. Here, for reasons of numerical stability, we choose $q \in \mathrm{U}(n)$, the unitary group acting on \mathbb{C}^n . Since the intersection of $\mathrm{U}(n)$ with any proper algebraic subset X of $\mathrm{GL}(n, \mathbb{C})$, is a closed set of Lebesgue measure zero, choosing q randomly from $\mathrm{U}(n)$ is justified.

Remark 1.1.1. Note that if a complex semisimple group G is our parameter space, as it is in Remark 1.2.2, we could, for similar reasons, choose q randomly in a maximal compact subgroup of G .

1.1.2 The Numerical Irreducible Decomposition

Given a system of polynomials $f(x)$ as in Eq. 1.9, the *irreducible decomposition* of $V(f)$ is the decomposition

$$V(f) = \bigcup_{i=1}^{\dim V(f)} Z_i = \bigcup_{i=1}^{\dim V(f)} \bigcup_{j \in \mathcal{J}_i} Z_{i,j},$$

where Z_i is a pure i -dimensional algebraic set; each set \mathcal{J}_i is finite; and the $Z_{i,j}$ are irreducible algebraic sets with the property that $Z_{i,j} \subset Z_{a,b}$ if and only if $(i, j) = (a, b)$. The *Numerical Irreducible Decomposition* of $V(f)$ is the collection of

1. linear equations $L_1(x), \dots, L_n(x)$ general with respect to all the $Z_{i,j}$;

2. the sets $W_{i,j}$ consisting of the $\deg Z_{i,j}$ smooth points $V(L_1, \dots, L_i) \cap Z_{i,j}$ of $Z_{i,j}$ for each nonnegative integer $i \leq \dim V(f)$ and each $j \in \mathcal{J}_i$.

The elements of the $W_{i,j}$ are called witness points for $Z_{i,j}$. This decomposition is developed in [23, 24, 25, 26]. See also [30]. The programs Bertini [1] and PHC [27, 32] compute this decomposition. As an algorithm, we have

Algorithm *NumIrredDecomp*

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N .

Output: The dimension $d = \dim V(f)$;

the dimensions $\dim_{i,j}$ and degrees $\deg_{i,j}$ of the irreducible components

$Z_{i,j}$ of $V(f)$ for $j \in \mathcal{J}_i$ with nonnegative integers $i \leq d$;

linear equations $L_1(x), \dots, L_n(x)$ general with respect to all the $Z_{i,j}$; and

witness sets $W_{i,j}$ consisting of the $\deg Z_{i,j}$ smooth points $V(L_1, \dots, L_i) \cap Z_{i,j}$ of $Z_{i,j}$ for each nonnegative integer $i \leq \dim V(f)$ and each $j \in \mathcal{J}_i$.

The algorithm as implemented also outputs auxiliary information needed for further computation, e.g., deflated systems, as discussed following Algorithm 1, which is needed to track paths on components whose multiplicity is greater than one.

By varying the linear equations, it is computationally inexpensive to generate additional points on each $Z_{i,j}$.

The membership test from [24, 25] gives a computation of the multiplicity of a point on the reduction of an irreducible algebraic set. Since a smooth point is precisely one of multiplicity one, this gives a criterion for a point to be a smooth point of the reduction of an algebraic set. Since we need this criterion in this article, let us state it as an algorithm.

Algorithm 1. *CheckSmoothness*

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N ;

and a point x^* on an irreducible component Z of $V(f)$.

Output: The multiplicity μ of x^* on Z_{red} .

Compute a set W of witness points $w_1, \dots, w_{\deg Z_{\text{red}}}$ for linear equations

$L := \{L_1, \dots, L_{\dim Z}\}$ general with respect to Z .

Choose a system of linear equations $\hat{L} := \{\hat{L}_1, \dots, \hat{L}_{\dim Z}\}$ satisfying

$\hat{L}_i(x^*) = 0$ and which other than this are general with respect to the choices made in previous steps.

Choose a general complex number γ satisfying $|\gamma| = 1$.

Compute the limits $\hat{W} := \{\hat{w}_1, \dots, \hat{w}_{\deg Z_{\text{red}}}\}$ of the paths

$Z \cap V(tL(x) + \gamma(1-t)\hat{L}(x))$ starting at W and traced as t goes from 1 to 0.

Set μ equal to the number of points of \hat{W} equal to x^* .

There are a number of numerical issues that must be dealt with in implementations of this algorithm. If Z is not generically reduced, then tracking must be done using a deflated system. Deflation for isolated points was developed in [15]: see also

[8, 14, 20, 21]. For the deflation of irreducible components and the use of it for tracking paths see [30, §13.3.2 and §15.2.2]. Another numerical issue is how to decide equality. These matters are discussed in [30].

We need to compute generic fiber dimensions in the main algorithm of this article; the following suffices.

Algorithm *FiberDimension*

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N ;
a polynomial map $\Phi : \mathbb{C}^N \rightarrow \mathbb{C}^s$ with $\Phi(x) = (\Phi_1(x), \dots, \Phi_s(x))$;
and a point $x^* \in V(f)$.

Output: The dimension at x^* of the fiber of $\Phi_{V(f)}$ containing x^* .

This is a simple consequence of having *NumIrredDecomp*. First compute

$$\text{NumIrredDecomp}(f_1(x), \dots, f_m(x), \Phi_1(x) - \Phi_1(x^*), \dots, \Phi_s(x) - \Phi_s(x^*)).$$

Now do a membership test using the witness sets from this computation to find which components of the Irreducible Decomposition of

$$V(f_1(x), \dots, f_m(x), \Phi_1(x) - \Phi_1(x^*), \dots, \Phi_s(x) - \Phi_s(x^*))$$

contain x^* . The maximum of the dimensions $\dim_{i,j}$ among these components gives the desired dimension.

1.1.3 Images of Algebraic Sets

What is required for the numerical irreducible decomposition is data that allows us to carry out homotopy continuation. Often this is a system of equations on the Euclidean space which contains the algebraic set, but this is not necessary.

With deflation of a multiple k -dimensional component Z of a system $f(x) = 0$ [30, §13.3.2 and §15.2.2], we have a system of the form

$$\mathcal{D}(f, Z) := \begin{bmatrix} f(x) \\ A(x) \cdot \begin{bmatrix} 1 \\ \xi \end{bmatrix} \\ c \cdot \xi - 1 \end{bmatrix} = 0$$

with $x \in \mathbb{C}^N$; $\xi \in \mathbb{C}^n$; $A(x)$ is a $s \times (n+1)$ matrix of polynomials; and c a $(n+N-s-k) \times n$ matrix of constants. The key property of the system $\mathcal{D}(f, Z)$ is that there is a multiplicity one component Z' of $\mathcal{D}(f, Z)^{-1}(0)$ which maps generically one-to-one onto Z under the product projection $(x, \xi) \rightarrow x$. To carry out operations such as tracking a path on Z as a complementary linear space \mathcal{L} moves, it suffice to track the path cut out on Z' as the pullback of \mathcal{L} to \mathbb{C}^{N+n} moves.

Similarly, assume that we have a system of polynomials

$$\mathcal{F}(x_1, \dots, x_N; \xi_1, \dots, \xi_n) = 0$$

on \mathbb{C}^{N+n} . Let $\pi : \mathbb{C}^{N+n} \rightarrow \mathbb{C}^n$ denote the product projection. Let Z be an irreducible component of $V(\mathcal{F})$. Given this information, it is straightforward to numerically work with the closure $\overline{\pi(Z)}$ of the image of Z by lifting computations to Z .

This is the special situation that occurs in this article, assuming that each fiber of π_Z is a linear space but with possibly varying dimensions. Using *FiberDimension*, compute the dimension v of the fiber of π_Z containing a witness point of Z . Now choose v general linear equations L_1, \dots, L_v in the x variables. There is a unique component Z' of $Z \cap V(L_1, \dots, L_v)$ which maps generically one-to-one onto $\pi(Z)$. For numerical continuation this is as good as having the equations for $\overline{\pi(Z)}$.

In several algorithms we will manipulate irreducible components of an algebraic set. Numerically we always use the Numerical Irreducible Decomposition, but with the possibility that the equations are defined on an auxiliary space as above.

1.2 Random Coordinate Patches on Grassmannians

The Grassmannian $\text{Grass}(a, b)$ parameterizes all a -dimensional vector subspaces of \mathbb{C}^b . When $a = 1$, this is the usual $(b - 1)$ -dimensional projective space, \mathbb{P}^{b-1} . An a -dimensional vector subspace S of \mathbb{C}^b is specified uniquely by a linearly independent vectors v_1, \dots, v_a in \mathbb{C}^b . It is convenient to regard these as forming a $b \times a$ matrix

$$[v_1 \cdots v_a]. \quad (1.10)$$

Note that if v'_1, \dots, v'_a is a second basis of S , then there is an invertible $a \times a$ matrix T of complex numbers such that

$$[v'_1 \cdots v'_a] = [v_1 \cdots v_a] \cdot T.$$

$\text{Grass}(a, b)$ is an $a(b - a)$ -dimensional projective manifold on which the group $\text{GL}(b)$ of invertible $b \times b$ matrices g acts homogeneously under the action

$$[v_1 \cdots v_a] \rightarrow g \cdot [v_1 \cdots v_a].$$

More details on Grassmannians may be found in [12, 13].

Random Coordinate Patches

A basic numerical trick, first exploited in [18] to find isolated solutions in \mathbb{C}^N or \mathbb{P}^N , is to carry out all computation on a random Euclidean coordinate patch on \mathbb{P}^N . The advantage of this trick is that, with probability one, all solutions of the system

are now finite, and so for the purposes of computation, points at infinity may be treated as finite (albeit such points are often highly singular). Though no patch can contain a positive dimensional solution component at infinity, a general coordinate patch meets every irreducible component of a solution set in a Zariski open set of the given component. For this reason, this same trick is widely used in Numerical Algebraic Geometry [30].

In this article, we have need of a random patch on a Grassmannian $\text{Grass}(a, b)$ of linear vector subspaces $\mathbb{C}^a \subset \mathbb{C}^b$. A straightforward generalization of the above trick is to embed $\text{Grass}(a, b)$ in $P := \mathbb{P}^{\binom{b}{a}-1}$ and pullback a random patch from P . This patch is complicated to work with because of the number of variables involved and because of the nonlinearity of the conditions for a point to be on the patch.

There is a much better way to choose a random patch, which is particularly efficient for numerical computation. We present the approach and justification for choosing the patch in the following paragraphs.

Let B be a $b \times b$ unitary matrix. Then for a coordinate patch we take

$$B \cdot \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \\ \xi_{1,1} & \cdots & \xi_{1,a} \\ \vdots & \ddots & \vdots \\ \xi_{b-a,1} & \cdots & \xi_{b-a,a} \end{bmatrix}. \quad (1.11)$$

We often abbreviate this as

$$B \cdot \begin{bmatrix} I_a \\ \Xi \end{bmatrix}$$

where I_a denotes the $a \times a$ identity matrix.

Theorem 1.2.1. *Let W be an arbitrary algebraic set and let \mathcal{T} denote an algebraic subset of $W \times \text{Grass}(a, b)$. Given a unitary matrix B , let U_B denote the Zariski open set of $\text{Grass}(a, b)$ for which*

$$B \cdot \begin{bmatrix} I_a \\ \Xi \end{bmatrix}$$

are coordinates. There is an open dense subset \mathcal{U} of the unitary matrices $U(n)$ such that the Lebesgue measure of $U(n) \setminus \mathcal{U}$ is zero and such that for $B \in \mathcal{U}$, $(W \times U_B) \cap \mathcal{T}$ is a non-empty Zariski open subset of \mathcal{T} .

Proof. By the discussion in §1.1.1, it suffices to show this for generic B in the general linear group, $\text{GL}(n, \mathbb{C})$. For the closure of $(W \times U_B) \cap \mathcal{T}$ to not contain a component C of \mathcal{T} is an algebraic condition, i.e., a condition picking out an algebraic subset of the General linear group. Let D_C denote this algebraic subset of $\text{GL}(n, \mathbb{C})$. The set, D_C , is a proper subset due to the fact that U_B may be chosen to contain any particular point of $\text{Grass}(a, b)$. Let \mathcal{C} denote the set of components of \mathcal{T} . Since \mathcal{T} has finitely many components, any invertible matrix B in the complement of $\cup_{C \in \mathcal{C}} D_C$ will suffice.

Remark 1.2.2. Let \mathcal{X} be a rational homogeneous projective manifold. The Borel-Remmert characterization [5, 22] of such manifolds is that they are the compact Kähler manifolds \mathcal{X} with a complex semisimple group G as biholomorphism group, and such that there is a parabolic subgroup P of G with \mathcal{X} biholomorphic to G/P with its natural complex structure. Thus \mathcal{X} possesses a conjugation with fixed points a maximal compact subgroup K with $\dim_{\mathbb{R}} K = \dim_{\mathbb{C}} \text{Aut}(\mathcal{X})$. The analogous notion of a random coordinate patch would be the set gU , where g is a general element of K and U is any dense Bruhat Cell. More details on parabolic subgroups and Bruhat decompositions may be found in [6, §3 and §11]

1.3 Finding Rank-Dropping Sets

Let A be an $m \times n$ matrix with polynomial entries as in Eq. 1.1 and let $f(x)$ denote the system as in Eq. 1.9. By taking adjoints and relabeling if necessary, we may assume without loss of generality that $m \geq n$. Let $\mathcal{S}_k(A) := \{x \in \mathbb{C}^N \mid \text{rank}A(x) \leq k\}$. Since the rank of $A(x)$ can be at most n , we may restrict ourselves to computing $\mathcal{S}_k(A)$ for $k \leq n$.

For each k , $\mathcal{S}_k(A_{V(f)})$ is algebraic since it is the solution set of the system comprised of $f_1(x), \dots, f_n(x)$ plus the determinants of all $k \times k$ subminors of A . The irreducible components Z of $\mathcal{S}_k(A)$, with the property that $\text{rank}A(x^*) = k$ for a general point $x^* \in Z$, are precisely the irreducible components of $\mathcal{S}_k(A)$, which are not components of $\mathcal{S}_{k-1}(A)$.

The sets $\mathcal{S}_k(A_{V(f)})$ may theoretically be computed via Gröbner basis techniques by solving each of these systems with software such as CoCoA, Macaulay, or Singular [7, 17, 11]. However, for many applications, the system of determinants of all $k \times k$ subminors of A is impractically large and complex. Such systems consist of $\binom{m}{k} \binom{n}{k}$ equations with degrees considerably larger than those of the entries of A . As a result, this approach will only work when both the size of A and the degrees of the entries of A are relatively small. We follow an alternative approach.

Our starting point is the system

$$\begin{bmatrix} p_{1,1}(x) & \cdots & p_{1,n}(x) \\ \vdots & \ddots & \vdots \\ p_{m,1}(x) & \cdots & p_{m,n}(x) \end{bmatrix} \cdot \begin{bmatrix} \xi_1 \\ \vdots \\ \xi_n \end{bmatrix} = 0 \quad (1.12)$$

where $[\xi_1, \dots, \xi_n]$ is a set of homogeneous coordinates on \mathbb{P}^{n-1} . We let $\mathcal{T}(A)$ denote the solution set of Eq. 1.12. Let $\pi: \mathcal{T}(A) \rightarrow \mathbb{C}^N$ and $\sigma: \mathcal{T}(A) \rightarrow \mathbb{P}^{n-1}$ denote the maps induced by the product projections of $\mathbb{C}^N \times \mathbb{P}^{n-1}$.

We let $\mathcal{T}(A)_y \subset \mathbb{P}^{n-1}$ denote the solution set of the fiber of $\mathcal{T}(A)$ over y regarded as a subset of \mathbb{P}^{n-1} , i.e., $\mathcal{T}(A)_y = \sigma(\pi^{-1}(y))$. In this setting, we have

$$y \in \mathcal{S}_k(A) \quad \text{if and only if} \quad \dim \mathcal{T}(A)_y \geq n - 1 - k.$$

While computing the irreducible decomposition of $\mathcal{T}(A)$ provides a great deal of information, it does not allow for the full determination of the sets

$$\mathcal{S}_k(A) = \{y \in \mathbb{C}^N \mid \dim \mathcal{T}(A)_y \geq n - 1 - k\}.$$

One could completely determine these sets by applying the fiber product algorithm as developed in [31]. However, since we want to find fibers of π that are points in $\text{Grass}(n-k, n)$, there is a different approach which has the advantage of being computationally more efficient.

The approach is to consider the system

$$\mathcal{F}_k(f) := \left[\begin{array}{c} f(x) \\ A(x) \cdot B \cdot \begin{bmatrix} I_{n-k} \\ \Xi \end{bmatrix} \end{array} \right] = 0 \quad (1.13)$$

where B is a random $n \times n$ unitary matrix; I_{n-k} is the $(n-k) \times (n-k)$ identity matrix; and Ξ is an $k \times (n-k)$ matrix of indeterminates $\xi_{i,j}$. The discussion in §1.2 gives the following result.

Theorem 1.3.1. *Let A be an $m \times n$ matrix with polynomial entries in Eq. 1.1 and let $f(x)$ denote the system as in Eq. 1.9. Assume that $m \geq n$. For a generic B in the $n \times n$ unitary group, and a nonnegative integer k between 0 and n , let $\mathcal{F}_k(f)$ denote the system in Eq. 1.13. Let \mathcal{A}_k denote the set of the irreducible components of $\mathcal{S}_k(A_{V(f)})$, which are not irreducible components of $\mathcal{S}_{k-1}(A_{V(f)})$. Let \mathcal{B}_k denote the set made up of the closures of the images under π of the irreducible components Z of $V(\mathcal{F}_k(f))$, such that the generic fiber of the projection from Z to \mathbb{C}^N is zero dimensional, i.e., such that $A(x)$ is of rank k at the image under π of a witness point of Z . The sets in \mathcal{A}_k are the maximal elements under set inclusion of the elements of \mathcal{B}_k .*

Note we can use a membership test to determine inclusion relations.

Algorithm 2. *RankDropSet*

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N ;

a matrix of polynomials $A(x) := \begin{bmatrix} p_{1,1}(x) & \cdots & p_{1,n}(x) \\ \vdots & \ddots & \vdots \\ p_{m,1}(x) & \cdots & p_{m,n}(x) \end{bmatrix}$ on \mathbb{C}^N ; and

a nonnegative integer k .

Output: The Numerical Irreducible Decomposition of the set $\mathcal{S}_k(A_{V(f)})$.

Choose a random unitary matrix $B \in U(n)$.

Compute *NumIrredDecomp* of the system in Eq. 1.13.

Use *FiberDimension* to pick out the set \mathcal{Z} of irreducible components Z with fibers having generic fiber dimension zero.

Output the projection of the components $Z \in \mathcal{Z}$ in $\mathbb{C}^N \times \mathbb{C}^{k(n-k)}$ to \mathbb{C}^N under the product projection.

In line with the discussion of §1.1.3, we have not explicitly given the details of the standard steps to compute the full witness sets for the components output in the last line of the algorithm. For the convenience of the reader, we give a brief discussion of steps involved.

Fix an a -dimensional component $Z \in \mathcal{L}$ with fiber dimension zero. Let $\widehat{\mathcal{L}}$ denote the generic a -codimensional affine linear subspace of $\mathbb{C}^{N+k(n-k)}$ with $W_Z := \widehat{\mathcal{L}} \cap Z$ the witness points of Z .

Under the product projection, $\mathbb{C}^N \times \mathbb{C}^{k(n-k)}$, Z has, as image in \mathbb{C}^N , a dense constructible subset A of an algebraic subset B of \mathbb{C}^N . Choose a generic a -codimensional affine linear subspace $\mathcal{L} \subset \mathbb{C}^N$. A contains a dense Zariski open subset \mathcal{O} of B , see for example [30, Lemma 12.5.8 and 12.5.9]. \mathcal{L} meets \mathcal{O} in $\deg B$ points. The witness points $\mathcal{L} \cap B$ for B may be simply computed from the known witness points W_Z of Z .

To do this, pull back \mathcal{L} to an a -codimensional affine linear subspace \mathcal{L}' of $\mathbb{C}^{N+k(n-k)}$. Using a homotopy deforming $\widehat{\mathcal{L}}$ to \mathcal{L}' , we can, starting with the points W_Z find the set of points $W' := \mathcal{L}' \cap Z$. The images in \mathbb{C}^N , of the points W' , are the witness points $\mathcal{L} \cap B$.

1.4 Generalizations

Theorem 1.3.1 and the corresponding algorithm are stated for a matrix of polynomials on \mathbb{C}^N . These results hold much more generally.

Using Open Zariski Subsets

Since we work with witness points, we can replace \mathbb{C}^N with a nontrivial Zariski open set U . Indeed, either

1. U meets a d -dimensional component Z of $V(f) \subset \mathbb{C}^N$ in a nontrivial Zariski open set; or
2. $U \cap Z$ is empty.

In the first case, a generic $N - d$ dimensional linear space that meets Z in $\deg Z$ points will with probability one meet $Z \cap U$ in $\deg Z$ points.

Restriction of A to an Irreducible Set

Let f and A be as in §1.3. Let X be an irreducible component of $V(f)$. It is straightforward to find $\mathcal{S}_k(A_X)$. We have found that each component Z of $\mathcal{S}_k(A_{V(f)})$ is the closure of the image of an irreducible set Z' from $V(f) \times \text{Grass}(n-k, n)$ under the product projection π with general fiber dimension zero. Using [28], we can find the irreducible components Z'' of the sets $Z' \cap [X \times \text{Grass}(k, N)]$. The set $\mathcal{S}_k(A_X)$

is precisely the union of the closures of the images under π of the components Z'' with general fiber dimension under π equal to zero.

Algebraic Functions instead of Polynomials

The results of §1.3 hold for the restriction of $A(x)$, made up of algebraic functions defined on a Zariski open set \mathcal{U} of \mathbb{C}^N , to the solution set of a system of polynomials $f(x) = 0$ defined on \mathbb{C}^N . For example, $A(x)$ is a matrix of rational functions on \mathbb{C}^N and \mathcal{U} is the complement on \mathbb{C}^N of the union of the pole sets of the entries of $A(x)$. By clearing the denominators, we have reduced to a polynomial matrix.

Algebraic Vector Bundle Maps

Let \mathcal{F} and \mathcal{G} be algebraic vector bundles of ranks n and m , respectively, defined on a quasiprojective manifold Y . Let A be an element of $\text{Hom}(\mathcal{F}, \mathcal{G})$, i.e., an algebraic section of $\mathcal{F}^* \otimes_{\mathbb{C}} \mathcal{G}$. Let F be a section of an algebraic vector bundle \mathcal{H} on Y and let $X \subset Y$ be an algebraic subset of the set of zeroes of F . For each integer $k \geq 0$, the set $\mathcal{S}_k(A)$ of points $y \in Y$ where $\text{rank}(A) \leq k$ is an algebraic subset of Y . The set $\mathcal{S}_k(A_X)$ is also algebraic. By convention, $\mathcal{S}_{-1}(A) = \emptyset$.

We wish to decompose $\mathcal{S}_k(A_X)$ into irreducible components. Since algebraic vector bundles are locally free in the Zariski topology, this general situation may be reduced to finding $\mathcal{S}_k(A_{V(f)}) \cap U$ for a matrix A of polynomials on some Zariski open set U of \mathbb{C}^N and a system of polynomials $f(x) = 0$.

The only practical case of this generalization is the case where f is a system of homogeneous polynomials on \mathbb{P}^N and $A(x)$ is a matrix of homogeneous polynomials whose degrees are compatible with the rank drop loci being considered to lie in \mathbb{P}^N .

To be explicit, let $\mathcal{O}_{\mathbb{P}^N}(k)$ denote the sheaf of algebraic sections of the k -th power of the hyperplane section bundle on \mathbb{P}^N , i.e., the rank one locally free coherent algebraic sheaf whose sections are the homogeneous polynomials of degree k . Consider an $\mathcal{O}_{\mathbb{P}^N}$ linear mapping A of the form

$$A : \bigoplus_{i=1}^m \mathcal{O}_{\mathbb{P}^N}(a_i) \rightarrow \bigoplus_{j=1}^n \mathcal{O}_{\mathbb{P}^N}(b_j). \quad (1.14)$$

A is represented by a matrix of homogeneous polynomials with $\deg A_{i,j}(x) = b_j - a_i$. For a matrix of this form, the rank of $A(x)$ is well defined for any given point in projective space. Choosing a generic Euclidean coordinate patch $U \approx \mathbb{C}^N$ on \mathbb{P}^N , U meets each irreducible component of each $\mathcal{S}_k(A)$ in a Zariski open dense set.

To set up the equations, regard A as a matrix of homogeneous polynomials on \mathbb{C}^{N+1} and f as a system of homogeneous polynomials on \mathbb{C}^{N+1} . Let $c \cdot x - 1$ be a general linear equation on \mathbb{C}^{N+1} with $\mathbb{P}^N \setminus U$ defined by $c \cdot x = 0$. The system for $\mathcal{S}_k(A_{V(f)})$ is

$$\begin{bmatrix} f(x) \\ A(x) \cdot B \cdot \begin{bmatrix} I_{n-k} \\ \Xi \end{bmatrix} \\ c \cdot x - 1 \end{bmatrix} = 0 \quad (1.15)$$

where we regard A as an $m \times n$ matrix of polynomials on \mathbb{C}^{N+1} (thus x is a vector of $N+1$ indeterminates); B is a random $n \times n$ unitary matrix; I_{n-k} is the $(n-k) \times (n-k)$ identity matrix; Ξ is a $k \times (n-k)$ matrix of indeterminates $\xi_{i,j}$; and c is a generic unit vector on \mathbb{C}^{N+1} .

1.5 Applications

We present three applications of our algorithm:

1. the numerical irreducible decomposition of the support of a finite module over a ring of algebraic functions, i.e., of a coherent algebraic sheaf on an algebraic set;
2. the decomposition into sets where the differential of an algebraic map is of constant rank: one special case of this is the computation of the singular set of an algebraic set; and
3. the singular set of an algebraic set.

In each of the following applications we work over \mathbb{C}^N . Generalizations, e.g., to quasiprojective manifolds, follow from the ideas outlined in §1.4.

1.5.1 Support of a Module

Let $\mathcal{O}_{\text{alg},U}$ denote the sheaf of algebraic functions on a Zariski open set $U \subset \mathbb{C}^N$. A finitely generated coherent algebraic sheaf \mathcal{F} is the quotient sheaf of an $\mathcal{O}_{\text{alg},U}$ -linear map

$$\bigoplus_{i=1}^n \mathcal{O}_{\text{alg},U} \rightarrow \bigoplus_{i=1}^m \mathcal{O}_{\text{alg},U}.$$

Such a map is given by an $m \times n$ matrix of algebraic functions $A(x)$. Entries $A_{i,j}(x)$ of $A(x)$ are rational functions, which must be of the form $\frac{p_{i,j}(x)}{q_{i,j}(x)}$ for polynomials $p_{i,j}(x)$ and $q_{i,j}(x)$ with the solution set of $q_{i,j}(x) = 0$ contained in $\mathbb{C}^N \setminus U$. Decomposing the support of \mathcal{F} is the same as computing the sets $\mathcal{S}_k(A)$.

1.5.2 Degeneracy Sets of the Differential of a Map

Let X denote the solution set of a system of polynomials $f(x) = 0$ (as in Eq. 1.9) defined on \mathbb{C}^N . Let $Jf(x)$ denote its Jacobian matrix as in Eq. 1.16. For simplicity, let $\pi_X : X \rightarrow \mathbb{C}^M$ be the restriction to $X \subset \mathbb{C}^N$ of a surjective linear projection from $\pi : \mathbb{C}^N \rightarrow \mathbb{C}^M$. Let $n := N - M$ and let R denote an $N \times n$ matrix of orthonormal vectors spanning the n -dimensional vector subspace of \mathbb{C}^N , which is the fiber of π containing the origin of \mathbb{C}^N . If X is irreducible and $\pi(X)$ is dense in \mathbb{C}^M , then the degeneracy for the map π_X is the set of points $x^* \in X$ where the rank of the $(m \times n)$ -matrix

$$Jf(x^*) \cdot R$$

is less than n .

1.5.3 Singular Sets

The special case in §1.5.2 when $M = 0$ is of special interest. For simplicity assume that we are trying to find the singular set of a possibly nonreduced pure k -dimensional algebraic set X defined by a system of $N - k$ polynomials on \mathbb{C}^N as in Eq. 1.9, with Jacobian matrix

$$Jf(x) := \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_N} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_{N-k}}{\partial x_1} & \cdots & \frac{\partial f_{N-k}}{\partial x_N} \end{bmatrix}. \quad (1.16)$$

The singular set consists of those points $x^* \in X$ such that

$$\text{rank}_{x^*} Jf(x) < N - k.$$

The results apply immediately to this situation. We codify this for use in the Appendix. For a matrix A , we denote the transpose by A^T .

Algorithm 3. *FindSchemeTheoreticSingularSet*

Input: A system of polynomials $\{f_1(x), \dots, f_{N-k}(x)\}$ on \mathbb{C}^N ; with $V(f)$ pure k -dimensional.

Output: $\text{RankDropSet}(f, (Jf)^T, N - k - 1)$.

Note that it may well turn out that the set produced by the previous algorithm is the singular set of $V(f) = f^{-1}(0)_{\text{red}}$. It is simple to check this. Given a witness point x^* on a component Z of $\text{FindSchemeTheoreticSingularSet}(f)$, we have that with probability one, $Z \subset \text{Sing}(V(f))$ if either x^* is contained in more than one

irreducible component of $V(f)$ or x^* is contained in a single component X of $V(f)$ and $\text{CheckSmoothness}(f, X, x^*) > 1$.

1.6 Implementation Details and Computational Results

The computational examples discussed here were run on an Opteron 250 processor running Linux using the numerical irreducible decomposition [23] implemented in the Bertini software package [1], which is under development by the first, second and fourth authors and Charles Wampler of GM Research and Development. The beta version of Bertini was used for the following examples.

1.6.1 Singular Set for a Matrix

Consider the matrix

$$A(a, b, c, d, e, f) = \begin{bmatrix} 0 & a & b & c \\ -a & 0 & d & e \\ -b & -d & 0 & f \\ -c & -e & -f & 0 \end{bmatrix}$$

Clearly, $\mathcal{S}_0(A) = \{(0, 0, 0, 0, 0, 0)\}$. One can compute $\mathcal{S}_1(A) = \mathcal{S}_0(A)$ and

$$\mathcal{S}_2(A) = \mathcal{S}_3(A) = \{(a, b, c, d, e, f) : af + cd - be = 0\}.$$

It should be noted that $\det(A) = (af + cd - be)^2$.

Bertini identified the components numerically for $\mathcal{S}_0(A)$ in 0.03s, $\mathcal{S}_1(A)$ in 6.47 seconds, $\mathcal{S}_2(A)$ in 5.77 seconds, and $\mathcal{S}_3(A)$ in 0.40 seconds.

1.6.2 Singular Set for a Hessian Matrix

For a given polynomial $g : \mathbb{C}^N \rightarrow \mathbb{C}$, consider computing the singular set of its Hessian matrix $H_g(x)$ where

$$H_g(x)_{ij} = \frac{\partial^2 g}{\partial x_i \partial x_j}(x).$$

In particular, consider the polynomial $g(x, y, z) = x^3 + x^2 + 2xy^2 - y^3 + 3yz^2 + z^3$ which has the Hessian matrix

$$H_g(x, y, z) = \begin{bmatrix} 6x+2 & 4y & 0 \\ 4y & 4x-6y & 6z \\ 0 & 6z & 6y+6z \end{bmatrix}.$$

By inspection, $\mathcal{S}_0(H_g) = \emptyset$. One can compute

$$\mathcal{S}_1(H_g) = \left\{ (0, 0, 0), \left(-\frac{1}{3}, 0, -\frac{2}{9}\right), \left(-\frac{1}{3}, 0, 0\right) \right\}$$

and

$$\mathcal{S}_2(H_g) = \{(x, y, z) : \det(H_g(x, y, z)) = 0\}.$$

Bertini identified the components numerically for $\mathcal{S}_0(A)$ in 0.01 seconds, $\mathcal{S}_1(A)$ in 0.30 seconds, $\mathcal{S}_2(A)$ in 0.18 seconds.

1.6.3 Singular Solutions for a Polynomial System

Consider computing the singular solutions of the cyclic-4 system [4] given by

$$f(x_1, x_2, x_3, x_4) = \begin{bmatrix} x_1 + x_2 + x_3 + x_4 \\ x_1x_2 + x_2x_3 + x_3x_4 + x_4x_1 \\ x_1x_2x_3 + x_2x_3x_4 + x_3x_4x_1 + x_4x_1x_2 \\ x_1x_2x_3x_4 - 1 \end{bmatrix}.$$

It is well-known that $V(f) = \{(x_1, x_2, x_3, x_4) : f(x_1, x_2, x_3, x_4) = 0\}$ has two irreducible quadric curve components given by $\{(x_1, x_2, -x_1, -x_2) : x_1x_2 = 1\}$ and $\{(x_1, x_2, -x_1, -x_2) : x_1x_2 = -1\}$. Denoting the Jacobian of f as Jf , for this system $\text{Sing}(V(f)) = V(f) \cap \mathcal{S}_2(Jf)$ is the set of solutions of f with exceptional rank. The polynomial system that defines $\text{Sing}(V(f))$ consists of 12 polynomials in 8 variables. Bertini performed a full numerical irreducible decomposition on this system in 4.45 minutes to discover that $\text{Sing}(V(f))$ consists of 8 isolated points, namely

$$\text{Sing}(V(f)) = \left\{ \left(a, \frac{1}{a}, -a, \frac{1}{a}\right), \left(a, -\frac{1}{a}, -a, \frac{1}{a}\right) : a = \pm 1, \pm\sqrt{-1} \right\}.$$

1.7 The Singular Set of the Reduction of an Algebraic Set

Let $f := \{f_1(x), \dots, f_m(x)\}$ denote a system of polynomials on \mathbb{C}^N . In this section we give an algorithm *FindSingularSet*, which starting with the input f , outputs a system of polynomials \mathcal{S} satisfying $\text{Sing}(V(f)) = V(\mathcal{S})$. Combined with *DefiningEquations* from §1.7.1, this constructs the singular set of any algebraic subset of \mathbb{C}^N . Repetition of *FindSingularSet* on its output \mathcal{S} while $\dim V(\mathcal{S}) \geq 0$ finds the sequence of sets $\text{Sing}(V(f)), \text{Sing}(\text{Sing}(V(f))_{\text{red}}), \dots$

1.7.1 Equations Defining an Algebraic Set

In [23], the membership test for whether a solution x^* of a polynomial system $f(x)$ on \mathbb{C}^N as in Eq. 1.9 was based on the construction using interpolation of polynomials of appropriate polynomials vanishing on irreducible components of $V(f)$. Using such polynomials as we do here is classical, e.g., [19].

Let us recall the construction. Let Z be a k -dimensional irreducible degree d component of $V(f)$ and let $S \subset \mathbb{C}^N$ be a finite set of points not contained in Z . Given a general projection $\pi: \mathbb{C}^N \rightarrow \mathbb{C}^{k+1}$, π_Z is generically one-to-one and $\pi(Z)$ is a degree d hypersurface not containing $\pi(S)$. There is a degree d polynomial p_π on \mathbb{C}^{k+1} , unique up to multiplication by a non-zero complex number, with $V(p_\pi) = \pi(Z)$. Thus composition $p_\pi(\pi(x))$ yields a degree d polynomial on \mathbb{C}^N that vanishes on Z but not at any point of S .

Now let us construct a system of polynomials $g(x)$ such that $Z = V(g)$. We follow the convention that the dimension of the empty set is -1 .

Algorithm 4. Defining Equations

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N ;
and an irreducible component Z of $V(f)$.

Output: A system \mathcal{F} of polynomials on \mathbb{C}^N with the property that
 $Z = V(\mathcal{F})$.

Set K equal to the maximum dimension of the set of irreducible components of $V(f)$ other than Z .

Set $j = 0$.

Set $\mathcal{F}_j := \{f_1, \dots, f_m\}$.

while $K \geq 0$ do

Set S equal a finite set consisting of one witness point from each component of $V(\mathcal{F}_j)$ except Z .

Set p equal to a degree d polynomial vanishing on Z , but not at any point of S .

Increment j by 1.

Set $\mathcal{F}_j := \mathcal{F}_{j-1} \cup \{p\}$.

Set K equal to the maximum dimension of the set of irreducible components of $V(\mathcal{F}_j)$ other than Z .

To see why the algorithm works, note that Z is still a component of $V(\mathcal{F}_j)$, and therefore if $K \neq -1$, p is a nontrivial polynomial vanishing on Z and not identically zero on any other component of $V(\mathcal{F}_j \cup \{p\})$. Thus it follows that the maximum dimension of the set of irreducible components of $V(\mathcal{F}_j)$ other than Z is strictly less than the maximum dimension of the set of irreducible components of $V(\mathcal{F}_{j-1})$.

We have the following classical result [19].

Lemma 1.7.1. *Given a pure k -dimensional algebraic subset $Z \subset \mathbb{C}^N$, and a point $x^* \in Z \setminus \text{Sing}(Z)$, it follows that there are $n - k$ degree d polynomials*

$$p_{x^*,1}(x), \dots, p_{x^*,n-k}(x)$$

such that:

1. Z is a component of $V(p_{x^*,1}(x), \dots, p_{x^*,n-k}(x))$; and
2. the Jacobian matrix

$$\begin{bmatrix} \frac{\partial p_{x^*,1}}{\partial x_1}(x) & \dots & \frac{\partial p_{x^*,1}}{\partial x_N}(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial p_{x^*,n-k}}{\partial x_1}(x) & \dots & \frac{\partial p_{x^*,n-k}}{\partial x_N}(x) \end{bmatrix}$$

evaluated at x^* has rank $N - k$.

The proof proceeds by noting that $N - k$ general projections $\pi_1(x) = c_1 \cdot x, \dots, \pi_{N-k} := c_{N-k} \cdot x$ from $\mathbb{C}^N \rightarrow \mathbb{C}^{k+1}$ give embeddings of Z in a Zariski open neighborhood of x^* and the matrix

$$\begin{bmatrix} c_1 \\ \vdots \\ c_{N-k} \end{bmatrix}$$

has rank $N - k$. For each $i = 1, \dots, N - k$, letting p_i denote a polynomial of degree d vanishing on $\pi_i(Z)$, the polynomials $p_{x^*,i} := p_i(\pi_i(x))$ satisfy the conclusions of Lemma 1.7.1.

Combining *DefiningEquations* with the procedure outlined following Lemma 1.7.1, we have the following algorithm.

Algorithm 5. *NormalCoordinates*

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N ;
an irreducible component Z of $V(f)$;
and a smooth point $x^* \in Z$.

Output: A system \mathcal{F} of polynomials on \mathbb{C}^N with the properties that
 Z is an irreducible component of $V(\mathcal{F})$ and $\mathcal{F}^{-1}(0)$ is reduced at x^* .

1.7.2 Computing the Singular Set of the Reduction of an Algebraic Set

Algorithm 6. *FindSingularSet*

Input: A system of polynomials $\{f_1(x), \dots, f_m(x)\}$ on \mathbb{C}^N ;
and a general point x^* on a k -dimensional irreducible component Z of $V(f)$.

Output: A system \mathcal{F} of equations with $\text{Sing}(V(f)) = V(\mathcal{F})$.

Set $K := \dim Z$.

Set $j = 0$.

Set $\mathcal{F}_j := \text{DefiningEquations}(f, Z)$.

Set $\mathcal{B} := \{Z\}$.
 Set \mathcal{B}' equal to a set with one point x^* , where x^* is a witness point of Z .
 While $K \geq -1$ do
 Increment j to $j + 1$.
 Set $\mathcal{F}_j := \mathcal{F}_{j-1} \cup_{x^* \in \mathcal{B}'} \text{NormalCoordinates}(\mathcal{F}, Z, x^*)$
 Compute $\mathcal{A} := \text{FindSchemeTheoreticSingularSet}(\mathcal{F}_j)$.
 Use *CheckSmoothness* to find the set \mathcal{B} of components \mathcal{A} not
 contained in $\text{Sing}(Z)$.
 Set \mathcal{B}' equal to a set with exactly one witness point for each
 component of \mathcal{B} .
 Set $K := \max_{X \in \mathcal{B}} \dim X$.
 Output \mathcal{F}_j .

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