Adaptive finite element methods for forward modeling in fluorescence enhanced frequency domain optical tomography

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Abstract: An adaptive finite element scheme for forward modeling in fluorescence optical tomography is implemented and the simulation results are compared with experimental data obtained from a tissue phantom by an area-illumination and area-detection scheme.

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1. Introduction

Fluorescence enhanced frequency domain optical tomography is an emerging functional imaging modality which involves the administration of a fluorescent contrast agent as opposed to radio-isotope as is used in conventional nuclear imaging techniques. NIR fluorescence enhanced imaging may be sensitive to targets with nano-molar concentrations of fluorophore making it ideal for molecular imaging applications [1]. Fluorescence enhanced optical tomography can provide images of fluorescent yield and lifetime within the tissue domain by utilizing the boundary measurements of photon energy resulting from the tissue stimulation via infrared light sources at the boundary. Tomography requires repeated solution of a system of coupled elliptic partial differential equations describing the time-dependent fluorescent light generation and transport within the tissue.

The finite element solver for the system of equations constitutes the bulk of computational cost of tomographic imaging. Since near infrared light attenuates rapidly in tissue, the light energy distribution within the tissue has steep gradients. To accurately predict energy distributions, the finite element mesh needs to be suitably refined near the light sources and boundaries. Traditionally this task has been performed *a-priori* with meshes optimally designed for given imaging geometries. In this contribution we propose the use of *a-posteriori* error estimates for adaptive mesh refinement to optimally model the strongly graded light distribution within tissues. Specifically we demonstrate this novel forward modeling scheme for fluorescence frequency domain measurements performed by the innovative use of area illumination and area detection on the surface of a tissue phantom [2, 3]. The use of an adaptive finite element meshing scheme removes the limitations of final image resolution problem imposed by the large scale inverse problem.

2. Background

In frequency-domain fluorescence optical tomography, the propagation of intensity modulated near infrared excitation light and the generation and propagation of emitted fluorescent light is described by the coupled diffusion equations:

$$-\nabla \bullet [D_{x}(\mathbf{r})\nabla \Phi_{x}(\mathbf{r},\omega)] + [\frac{i\omega}{c} + \mu_{axi}(\mathbf{r}) + \mu_{axf}(\mathbf{r})]\Phi_{x}(\mathbf{r},\omega) = 0$$

$$-\nabla \bullet [D_{m}(\mathbf{r})\nabla \Phi_{m}(\mathbf{r},\omega)] + [\frac{i\omega}{c} + \mu_{ami}(\mathbf{r}) + \mu_{amf}(\mathbf{r})]\Phi_{m}(\mathbf{r},\omega) = \frac{\phi(\mathbf{r})\mu_{axf}(\mathbf{r})}{1 - i\omega\tau(\mathbf{r})}\Phi_{x}(\mathbf{r},\omega)$$
...(1)

Where $\Phi_{x,m}$ (photons/cm²s) is the complex photon fluence of the excitation (subscript x) or emission (subscript m); $D_{x,m}$ (cm) is the optical diffusion coefficient; c is the velocity of light in the media; $\mu_{ax,mi,f}$ (cm⁻¹) is the absorption owing to the non fluorescing chromophores (subscript i) or exogenous fluorophores (subscript f); ω is the angular modulation frequency (rad/s); ϕ is the quantum efficiency of the fluorescent emission and τ is the lifetime(ns) of the fluorophores. System of equations (1) is solved with the Robin boundary conditions.

3.0 Finite Element Solution Scheme

We have employed the Galerkin finite element method for solving the system of equations (1). Although triangular and tetrahedral elements are popular in the optical tomography community, we have chosen eight node tri-linear hexahedral brick shaped elements since they allow efficient and computationally stable implementation of adaptive mesh refinement. After making the finite element approximation the system of equations (1) is transformed into a linear system of equations for each element which are then assembled into a global linear system. The unknowns of the global linear system are the nodal values of excitation and emission fluences:

$$K_{x}\overline{\Phi}_{x} = b_{x}$$

$$K_{m}\overline{\Phi}_{m} = B_{xm}\overline{\Phi}_{x} \qquad ..(2)$$

Where $K_{x,m}$ are the global stiffness matrices; b_x is the source vector for the excitation equation; B_{xm} is the coupling matrix resulting from the R.H.S of the emission diffusion equation. The number of unknowns in this system is on the order of 10^4 for fluorescence tomography applications in large tissue mimicking phantoms. Clearly optimal mesh generation is essential for accurate solution at a reasonable computational cost.

3.1 A-posteriori error estimation and adaptive mesh generation

The error in finite element solution scales with the maximum element size. Hence the accuracy of the solution increases with mesh refinement. Local mesh refinement within the regions associated with large variation of the excitation or emission fluence increases the accuracy of the solutions while keeping the degrees of freedom of the system in check. In this work the solution process is started with a coarse mesh and successive meshes are generated according to an a-posteriori error estimator. We have used the error estimator developed by Kelly [4]. Kelly's error estimator is a residual based energy norm estimator which refines the mesh, at locations where the gradient of the solution shows rapid spatial variation. After the solution on the coarse mesh, the error for each element is calculated by the following equation:

$$\varepsilon_K = \frac{h}{24} \left\| \left[\partial_n \Phi_{x,m} \right] \right\|_{\partial K}^2 \qquad ..(3)$$

Where \mathcal{E}_K is the error for K^{th} finite element; h is the element size measure; $[\partial_n \Phi_{x,m}]$ is the jump of normal derivative of the finite element solution across the element boundary ∂K . For our implementation we refine 70% of the elements with highest error values and coarsen 3% of the elements with lowest errors in each cycle. Some other elements are also refined to a lower degree to maintain numerical stability of the solution.

4.0 Forward Modeling For Area Illumination And Area Detection Schemes

The adaptive forward solver was used to predict the fluorescent frequency domain photon migration measurements from a tissue phantom containing a fluorescent target, by means of area illumination and area detection on the same surface. The phantom was an 8x8x8 cm³ container filled with 1% liposyn solution with a 1-ml



Fig-1: Instrumentation Details [2]

"target" containing 1-micromolar concentration of Indocyanine Green in 1% Liposyn suspended within the phantom at a depth of 1 cm from the surface. The tissue phantom was illuminated with an expanded laser beam of 785 nm excitation light. The excitation light was intensity modulated at 100 MHz. Area detection of frequency-domain parameters of amplitude and phase shift accomplished using a gain modulated image intensified charge coupled device. Experimental setup employed is detailed in Figure-1 [2]. The reader is referred to reference [2] for

the details of instrumentation and data acquisition scheme. The finite element simulation was started with a uniform coarse mesh with the discretization level of $16 \times 16 \times 16$ linear hexahedral elements. Three adaptive local mesh refinements were carried out to obtain a resolution of 0.0625×0.0625 cm at the detection surface which matched the measurement resolution of the image captured by the CCD. The simulated values of amplitude and phase shift for fluorescence were referenced with respect to the point on surface with maximum fluorescent amplitude and the referenced simulated and experimental measurements were compared to analyze the model match.

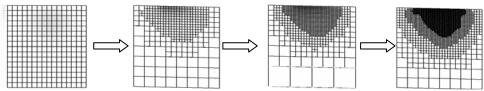


Fig-2: Evolution from initial coarse mesh to locally refined mesh in three steps Meshes at Cutting planes drawn at x = 4 are depicted

5.0 Results and Discussions

Figure-2 depicts the evolution of mesh with the three adaptive local refinements with a cut plane drawn at x = 4. The final mesh contained 147292 nodes. The total computer time taken for solution was 15 minutes on a dual processor Sun Sparc workstation. The mesh is refined in the regions with large gradients in the excitation and emission fields. Figures 3 and 4 show the fluorescent amplitude and phase on the detection area on the top surface for the experimentally measurements and the finite element simulation.

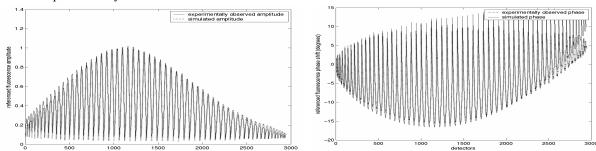


Fig-3: Model match for experimentally observed fluorescent amplitude(referenced) and phase shift

The average error between the measurement and prediction using the adaptive finite element predictor is 12.25% for fluorescent amplitude and 1.47° for fluorescent phase. The highest errors are observed at the edges of the detection area and are attributed to edge effects in the ICCD detection system.

6.0 Conclusions

We have demonstrated a novel approach for finite element based forward modeling in fluorescence enhanced optical tomography. Currently work is under progress for the application of adaptive mesh refinement techniques for the inverse problem of estimating the fluorescent yield distribution in the tissue domain by using an adaptive discretization of the unknown fluorescent yield.

7.0 References

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