

Name: P. Diddy

Time allowed: 50 minutes.  
Calculators are not allowed.

**M369 Linear Algebra (section 1) : Solutions to practise for 1st Midterm Exam**

1. Solve the system of equations

$$\begin{aligned} -3x_1 + 2x_2 + x_3 &= 0 \\ 2x_1 + x_2 - 3x_3 &= 0 \\ x_1 - 3x_2 + 2x_3 &= 0 \end{aligned}$$

and write down a basis for the solution space.

The coefficient matrix and reduced row echelon form are

$$\begin{pmatrix} -3 & 2 & 1 \\ 2 & 1 & -3 \\ 1 & -3 & 2 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix}.$$

So  $x_3$  is the free variable and the solution space is

$$\left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mid x_1 = x_3, x_2 = x_3 \right\} \quad \text{which is the same as} \quad \left\{ \begin{pmatrix} x_3 \\ x_3 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}.$$

Thus a basis for the solution space is  $\left[ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right]$ .

2. Let  $A$  be the  $3 \times 3$  matrix

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{pmatrix}.$$

a) Write down the reduced row echelon form  $U$  of  $A$ .

$$U = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

b) Use  $U$  to write down a basis for the row space of  $A$ .

$A$  and  $U$  have the same row space, and a basis is  $\{(1, 0, -1), (0, 1, 2)\}$ .

c) Use  $U$  to write down a basis for the column space of  $A$ .

The column spaces of  $A$  and  $U$  are different. However, a basis for the column space of  $U$  is

given by its first two columns. Therefore the first two columns of  $A$  also give a basis for the column space of  $A$ . Thus a basis is  $\left[ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right]$ .

3. Determine whether the following subsets of vectors in  $\mathbb{R}^2$  are vector subspaces.

a) all vectors  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$  such that  $x_1 + x_2 = 0$ ;

*Yes. The condition  $x_1 + x_2 = 0$  is linear.*

b) all vectors  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$  such that  $x_1 - x_2 = 0$ ;

*Yes. Once again the condition  $x_1 - x_2 = 0$  is linear.*

c) all vectors  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$  such that  $x_1^2 - x_2^2 = 0$ .

*No. The condition  $x_1^2 - x_2^2$  is quadratic, not linear. For example, the vectors  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$  lie in the subset, but their sum  $\begin{pmatrix} 2 \\ 0 \end{pmatrix}$  does not.*

4. Determine which of the following are linear transformations.

a)  $L : \mathbb{R}^2 \rightarrow \mathbb{R}^1$  defined by  $L(\mathbf{x}) = x_1x_2$ ;

*Not a linear transformation. For example  $L\begin{pmatrix} 2 \\ 2 \end{pmatrix} = 4 \neq 2 = 2L\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .*

b)  $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $L(\mathbf{x}) = \begin{pmatrix} x_1 + 2x_2 + 3x_3 \\ 4x_1 + 5x_2 + 6 \end{pmatrix}$ .

*Not a linear transformation. Notice that the last term of the second component is just 6, not  $6x_3$ . Thus  $L\begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 14 \end{pmatrix} \neq \begin{pmatrix} 2 \\ 20 \end{pmatrix} = 2L\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ .*

5. Write down the transition matrix for the change of basis from  $[2x - 1, 1 - 3x]$  to  $[2, 1 - x]$  in  $P_2$ .

*The transition matrix from  $[2x - 1, 1 - 3x]$  to the standard basis  $[x, 1]$  is  $V = \begin{pmatrix} 2 & -3 \\ -1 & 1 \end{pmatrix}$  and the transition matrix from  $[2, 1 - x]$  to the standard basis  $[x, 1]$  is  $U = \begin{pmatrix} 0 & -1 \\ 2 & 1 \end{pmatrix}$ . Therefore*

the required transition matrix is

$$S = U^{-1}V = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -2 & 0 \end{pmatrix} \begin{pmatrix} 2 & -3 \\ -1 & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & -2 \\ -4 & 6 \end{pmatrix}.$$

6. For each of the following sets of vectors determine whether they are linearly independent, whether they span, and whether they form a basis for the given vector space.

a)  $[\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] = \left[ \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \right]$  in  $\mathbb{R}^3$ ;

The determinant of the corresponding  $3 \times 3$  matrix is  $-2$ . Since this is non-zero, the three vectors are linearly independent, span  $\mathbb{R}^3$ , and hence are a basis.

b)  $[\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] = \left[ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right]$  in  $\mathbb{R}^4$ ;

Three vector in  $\mathbb{R}^4$  cannot span; they cannot be a basis either. They are linearly independent.

c)  $[\mathbf{v}_1, \mathbf{v}_2] = \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right]$  in  $\mathbb{R}^2$ .

Any set of vectors which contains the zero vector must be linearly dependent. They span the subspace  $\{x_1 = x_2\}$ , not all of  $\mathbb{R}^2$ . They do not form a basis.

7. Let  $A$  be an  $m \times n$  matrix whose columns are linearly dependent. Suppose that  $\mathbf{b}$  belongs to the column space of  $A$ . Prove that  $A\mathbf{x} = \mathbf{b}$  has infinitely many solutions.

Since the columns are linearly dependent, there is a non-trivial linear combination

$$y_1 \begin{pmatrix} a_{11} \\ \vdots \\ a_{m1} \end{pmatrix} + \dots + y_n \begin{pmatrix} a_{1n} \\ \vdots \\ a_{mn} \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix},$$

i.e. a non-trivial solution  $\mathbf{y}$  to  $A\mathbf{y} = \mathbf{0}$ . Since  $\mathbf{b}$  is in the column space there is a linear combination

$$z_1 \begin{pmatrix} a_{11} \\ \vdots \\ a_{m1} \end{pmatrix} + \dots + z_n \begin{pmatrix} a_{1n} \\ \vdots \\ a_{mn} \end{pmatrix} = \mathbf{b},$$

i.e. a solution  $\mathbf{z}$  to  $A\mathbf{z} = \mathbf{b}$ . Therefore for every real number  $\lambda$ ,

$$A(\mathbf{z} + \lambda\mathbf{y}) = A\mathbf{z} + \lambda A\mathbf{y} = \mathbf{b} + \lambda\mathbf{0} = \mathbf{b},$$

i.e.  $\mathbf{x} = \mathbf{z} + \lambda\mathbf{y}$  is a solution to  $A\mathbf{x} = \mathbf{b}$ , and this gives infinitely many solutions.

8. Let  $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be the linear transformation defined by

$$L(\mathbf{x}) = x_2\mathbf{b}_1 + (x_1 + x_2)\mathbf{b}_2 + x_1\mathbf{b}_3$$

where  $F = [\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3]$  is the basis

$$\mathbf{b}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad \mathbf{b}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \mathbf{b}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

of  $\mathbb{R}^3$ .

a) Find the matrix  $A$  which represents  $L$  with respect to the basis  $E = [\mathbf{u}_1, \mathbf{u}_2] = \left[ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right]$  of  $\mathbb{R}^2$  and the basis  $F$  of  $\mathbb{R}^3$ .

We calculate the columns of  $A$ :

$$\mathbf{a}_1 = [L(\mathbf{u}_1)]_F = [L \begin{pmatrix} 1 \\ 1 \end{pmatrix}]_F = \mathbf{b}_1 + 2\mathbf{b}_2 + \mathbf{b}_3 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \quad \text{wrt the basis } F,$$

$$\mathbf{a}_2 = [L(\mathbf{u}_2)]_F = [L \begin{pmatrix} 2 \\ 1 \end{pmatrix}]_F = \mathbf{b}_1 + 3\mathbf{b}_2 + 2\mathbf{b}_3 = \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix} \quad \text{wrt the basis } F.$$

Therefore

$$A = \begin{pmatrix} 1 & 1 \\ 2 & 3 \\ 1 & 2 \end{pmatrix}.$$

b) Using the matrix  $A$ , find the coordinates of  $L(\mathbf{u}_1 + \mathbf{u}_2)$  with respect to the basis  $F$ .

The coordinates of  $\mathbf{u}_1 + \mathbf{u}_2$  wrt the basis  $E$  are  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ , and

$$A \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 5 \\ 3 \end{pmatrix}.$$

This gives the coordinates of  $L(\mathbf{u}_1 + \mathbf{u}_2)$  with respect to the basis  $F$ , i.e.

$$L(\mathbf{u}_1 + \mathbf{u}_2) = 2\mathbf{b}_1 + 5\mathbf{b}_2 + 3\mathbf{b}_3.$$