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Time allowed:

50 minutes.

Calculators are not allowed.

M369 Linear Algebra (section 3) : Solutions to 2nd Midterm Exam

Problem	T/F	2	3	4	5	6	7	Total
Score								
Maximum	21	15	12	10	15	15	12	100

F If $\langle \mathbf{v}, \mathbf{w} \rangle = 0$ then \mathbf{v} and \mathbf{w} must be linearly dependent.

If the inner product is zero the vectors are orthogonal; so they could only be linearly dependent if one of the vectors is zero.

F Let A be an $n \times n$ matrix. The column space and the row space of A must be orthogonal complements.

For example, let $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$. The row and column spaces are both spanned by $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$, which is certainly not orthogonal to itself.

T An actual solution of $A\mathbf{x} = \mathbf{b}$ must also be a least squares solution.

A least squares solution is a minimizer of $\|A\mathbf{x} - \mathbf{b}\|$. If $A\mathbf{x} = \mathbf{b}$ then $\|A\mathbf{x} - \mathbf{b}\| = 0$, which is certainly a minimum.

T Let S be a subspace of \mathbb{R}^n . If \mathbf{p} is the projection of a vector $\mathbf{v} \in \mathbb{R}^n$ onto S , then \mathbf{p} must be orthogonal to $\mathbf{v} - \mathbf{p}$.

The projection \mathbf{p} lies in S , and is uniquely defined by requiring that $\mathbf{v} - \mathbf{p}$ be orthogonal to S . In particular, \mathbf{p} and $\mathbf{v} - \mathbf{p}$ must be orthogonal.

T If Q is an $n \times n$ matrix which is orthogonal then Q must be invertible.

In fact $Q^{-1} = Q^T$, so Q^{-1} exists.

F If an $n \times n$ matrix A is diagonalizable then A must have n distinct eigenvalues.

A diagonalizable matrix can have an eigenvalue with multiplicity, provided the dimension of the corresponding eigenspace equals the multiplicity of the eigenvalue.

F If \mathbf{x}_1 and \mathbf{x}_2 are both eigenvectors of A corresponding to the eigenvalue 2, then $\mathbf{x}_1 + \mathbf{x}_2$ must be an eigenvector of A corresponding to the eigenvalue 4.

Eigenvectors corresponding to the eigenvalue 2 form a subspace, so if we add \mathbf{x}_1 and \mathbf{x}_2 we get another eigenvector with eigenvalue 2.

2. a) Find a basis for the subspace $S = \{\mathbf{x} \in \mathbb{R}^3 | x_1 + x_2 + x_3 = 0\}$ of \mathbb{R}^3 .

The solution space (S) is given by $x_1 = -x_2 - x_3$, thus

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{pmatrix} = x_2 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

and a basis for S is $\{\mathbf{v}_1, \mathbf{v}_2\} = \{(-1, 1, 0)^T, (-1, 0, 1)^T\}$.

b) Apply the Gram-Schmidt process to find an orthonormal basis for S .

First we normalize \mathbf{v}_1 to get

$$\mathbf{u}_1 = \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} = \begin{pmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{pmatrix}.$$

Next we project \mathbf{v}_2 onto \mathbf{u}_1 to get

$$\mathbf{p}_1 = \langle \mathbf{v}_2, \mathbf{u}_1 \rangle \mathbf{u}_1 = \frac{1}{\sqrt{2}} \mathbf{u}_1 = \begin{pmatrix} -1/2 \\ 1/2 \\ 0 \end{pmatrix}.$$

Thus

$$\mathbf{v}_2 - \mathbf{p}_1 = \begin{pmatrix} -1/2 \\ -1/2 \\ 1 \end{pmatrix}.$$

Finally we normalize to get

$$\mathbf{u}_2 = \frac{\mathbf{v}_2 - \mathbf{p}_1}{\|\mathbf{v}_2 - \mathbf{p}_1\|} = \begin{pmatrix} -1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \end{pmatrix}.$$

c) Use the orthonormal basis to find the point in S which is closest to $\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$.

The closest vector is given by projecting $\mathbf{w} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ onto S , and this projection is given by

$$\langle \mathbf{w}, \mathbf{u}_1 \rangle \mathbf{u}_1 + \langle \mathbf{w}, \mathbf{u}_2 \rangle \mathbf{u}_2 = \frac{1}{\sqrt{2}} \mathbf{u}_1 + \frac{3}{\sqrt{6}} \mathbf{u}_2 = \begin{pmatrix} -1/2 \\ 1/2 \\ 0 \end{pmatrix} + \begin{pmatrix} -1/2 \\ -1/2 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}.$$

3. a) Let $\mathbf{v} = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$ and $\mathbf{w} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$. Find $\|\mathbf{v}\|$ and $\|\mathbf{w}\|$.

$$\|\mathbf{v}\| = \sqrt{1^2 + 1^2 + 2^2} = \sqrt{6}$$

and

$$\|\mathbf{w}\| = \sqrt{1^2 + 0^2 + 1^2} = \sqrt{2}$$

.

b) Find $\langle \mathbf{v}, \mathbf{w} \rangle$.

$$\langle \mathbf{v}, \mathbf{w} \rangle = 1 \cdot 1 + 1 \cdot 0 + 2 \cdot 1 = 3.$$

c) Find the angle θ between \mathbf{v} and \mathbf{w} .

$$\theta = \cos^{-1} \left(\frac{\langle \mathbf{v}, \mathbf{w} \rangle}{\|\mathbf{v}\| \cdot \|\mathbf{w}\|} \right) = \cos^{-1} \left(\frac{3}{\sqrt{6} \cdot \sqrt{2}} \right) = \cos^{-1} \left(\frac{\sqrt{3}}{2} \right) = \frac{\pi}{6}.$$

d) Find the projection of \mathbf{w} onto \mathbf{v} .

The projection is

$$\mathbf{p} = \frac{\langle \mathbf{w}, \mathbf{v} \rangle}{\langle \mathbf{v}, \mathbf{v} \rangle} \mathbf{v} = \frac{3}{6} \mathbf{v} = \begin{pmatrix} 1/2 \\ 1/2 \\ 1 \end{pmatrix}.$$

4. Find all least squares solutions of the system of equations

$$\begin{aligned}x_1 + 2x_2 &= 0, \\x_1 + 2x_2 &= 1, \\x_1 + 2x_2 &= 5.\end{aligned}$$

The normal equations $A^T A \mathbf{x} = A^T \mathbf{b}$ look like

$$\begin{pmatrix} 3 & 6 \\ 6 & 12 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 6 \\ 12 \end{pmatrix}.$$

The reduced row echelon form for this system of equations is

$$\left(\begin{array}{cc|c} 1 & 2 & 2 \\ 0 & 0 & 0 \end{array} \right)$$

so x_2 is the free variable and

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2 - 2x_2 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} -2 \\ 1 \end{pmatrix}.$$

5. Let A be a 7×5 matrix of rank 4 and let \mathbf{b} be a non-zero vector in $N(A^T)$.

a) What are the dimensions of $R(A)$, $N(A)$, $R(A^T)$, and $N(A^T)$?

Both the column space $R(A)$ and the row space $R(A^T)$ have dimension equal to the rank of A , namely 4. By the Rank-Nullity Theorem

$$\dim N(A) = n - \text{rank} A = 5 - 4 = 1$$

and

$$\dim N(A^T) = m - \text{rank} A^T = 7 - 4 = 3.$$

b) How many solutions of $A\mathbf{x} = \mathbf{b}$ will there be? Explain your answer.

We are told that \mathbf{b} lies in $N(A^T)$, which is the orthogonal complement to $R(A)$. The only vector which lies in $R(A)$ and $R(A)^\perp$ is the zero vector, but we are also told that \mathbf{b} is non-zero. Therefore \mathbf{b} does not lie in the column space $R(A)$. This means that $A\mathbf{x} = \mathbf{b}$ cannot have a solution.

c) Explain why $\hat{\mathbf{x}} = \mathbf{0}$ is a least squares solution of $A\mathbf{x} = \mathbf{b}$.

Since \mathbf{b} lies in $N(A^T)$, we have $A^T\mathbf{b} = \mathbf{0}$. Therefore the normal equations are $A^T A\hat{\mathbf{x}} = A^T\mathbf{b} = \mathbf{0}$. Clearly $\hat{\mathbf{x}} = \mathbf{0}$ is a solution to the normal equations, and therefore a least squares solution of $A\mathbf{x} = \mathbf{b}$.

d) Are there other least squares solutions of $A\mathbf{x} = \mathbf{b}$? Explain your answer.

Any solution to the normal equations $A^T A\hat{\mathbf{x}} = \mathbf{0}$ is a least squares solution. For example, if $\hat{\mathbf{x}}$ lies in the null-space $N(A)$ then $A\hat{\mathbf{x}} = \mathbf{0}$ and hence $A^T A\hat{\mathbf{x}}$ is also $\mathbf{0}$. Since $N(A)$ is one-dimensional, this gives a one-dimensional space of least squares solutions (i.e., infinitely many solutions).

6. Let $C[0, 1]$ be the space of continuous functions on the interval $[0, 1]$ with the standard inner product

$$\langle f(x), g(x) \rangle = \int_0^1 f(x)g(x)dx.$$

a) Apply the Gram-Schmidt process to $\{1, x\}$ to find an orthonormal basis for the subspace of linear functions.

First we normalize 1. Since $\|1\| = \left(\int_0^1 1^2 dx\right)^{1/2} = 1$ we find

$$\mathbf{u}_1 = \frac{1}{\|1\|} = 1.$$

Next we project x onto $\mathbf{u}_1 = 1$ to get

$$\mathbf{p}_1 = \langle x, 1 \rangle 1 = \left(\int_0^1 x dx\right) 1 = \frac{1}{2}.$$

Thus $x - \mathbf{p}_1 = x - \frac{1}{2}$. Finally we use

$$\|x - \frac{1}{2}\| = \left(\int_0^1 (x - \frac{1}{2})^2 dx\right)^{1/2} = \dots = \sqrt{\frac{1}{12}}$$

to normalize $x - \frac{1}{2}$, obtaining

$$\mathbf{u}_2 = \frac{x - \frac{1}{2}}{\|x - \frac{1}{2}\|} = \sqrt{12}\left(x - \frac{1}{2}\right) = \sqrt{3}(2x - 1).$$

b) Use the orthonormal basis to find the best approximation to $\ln(x + 1)$ on $[0, 1]$ by a linear function.

$$[\text{Hint: } \int_0^1 \ln(x + 1)dx = 2\ln 2 - 1 \quad \text{and} \quad \int_0^1 x \ln(x + 1)dx = \frac{1}{4} \quad]$$

The best approximation is given by projecting $f = \ln(x + 1)$ onto $\text{Span}(1, x) = \text{Span}(\mathbf{u}_1, \mathbf{u}_2)$. This is given by the formula

$$\begin{aligned} \langle f, \mathbf{u}_1 \rangle \mathbf{u}_1 + \langle f, \mathbf{u}_2 \rangle \mathbf{u}_2 &= \langle \ln(x + 1), 1 \rangle 1 + \langle \ln(x + 1), \sqrt{3}(2x - 1) \rangle \sqrt{3}(2x - 1) \\ &= (2\ln 2 - 1)1 + (2\langle \ln(x + 1), x \rangle - \langle \ln(x + 1), 1 \rangle)3(2x - 1) \\ &= (2\ln 2 - 1)1 + \left(\frac{1}{2} - (2\ln 2 - 1)\right)3(2x - 1) \\ &= \dots \\ &= \left(8\ln 2 - \frac{11}{2}\right) + (9 - 12\ln 2)x. \end{aligned}$$

7. a) One of the eigenvalues of the matrix

$$A = \begin{pmatrix} -1 & 6 \\ -1 & 4 \end{pmatrix}$$

is $\lambda_1 = 1$, with corresponding eigenvector $\mathbf{x}_1 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$. Find the second eigenvalue and corresponding eigenvector.

The characteristic equation is

$$\begin{aligned} \det(A - \lambda I) &= \begin{vmatrix} -1 - \lambda & 6 \\ -1 & 4 - \lambda \end{vmatrix} \\ &= (\lambda + 1)(\lambda - 4) + 6 \\ &= \lambda^2 - 3\lambda + 2 \\ &= (\lambda - 1)(\lambda - 2) \end{aligned}$$

and therefore the other eigenvalue is $\lambda_2 = 2$. The 2-eigenspace is the null space of

$$A - 2I = \begin{pmatrix} -3 & 6 \\ -1 & 2 \end{pmatrix}$$

which has reduced row echelon form

$$\left(\begin{array}{cc|c} 1 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right).$$

Therefore $\mathbf{x}_2 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ (or any non-zero multiple of \mathbf{x}_2) is an eigenvector with eigenvalue 2.

b) Find a matrix X which diagonalizes A .

We can form the matrix X whose columns are the eigenvectors of A . Thus

$$X = (\mathbf{x}_1, \mathbf{x}_2) = \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix}$$

and then

$$X^{-1}AX = D = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}.$$