

# The Metric.

Renzo's math 474

Given a point  $P$  of a regular surface  $S$ , we have identified the tangent plane  $T_P(S)$  with  $\mathbb{R}^2$  via the differential of a local parameterization near  $P$ . The tangent plane is a subspace of  $\mathbb{R}^3$ , and hence its vectors naturally have an inner product simply by restriction from the inner product in  $\mathbb{R}^3$ . We want to change our point of view, and instead think that we are assigning a non-standard inner product to  $\mathbb{R}^2$ . We start by reviewing the general notion of an inner product.

## 1 Inner Products

Given a real vector space  $V$ , an **inner product** on  $V$  is a function

$$\phi : V \times V \rightarrow \mathbb{R}$$

such that:

1.  $\phi$  is *bilinear*. For every  $\mathbf{x}, \mathbf{y}, \mathbf{z}$  in  $V$  and  $\lambda, \mu \in \mathbb{R}$ , it must be that

$$\phi(\lambda\mathbf{x} + \mu\mathbf{y}, \mathbf{z}) = \lambda\phi(\mathbf{x}, \mathbf{z}) + \mu\phi(\mathbf{y}, \mathbf{z}).$$

$$\phi(\mathbf{x}, \lambda\mathbf{y} + \mu\mathbf{z}) = \lambda\phi(\mathbf{x}, \mathbf{y}) + \mu\phi(\mathbf{x}, \mathbf{z}).$$

2.  $\phi$  is *symmetric*. For every  $\mathbf{x}, \mathbf{y} \in V$

$$\phi(\mathbf{x}, \mathbf{y}) = \phi(\mathbf{y}, \mathbf{x}).$$

3.  $\phi$  is *positive definite*. For every  $\mathbf{x} \neq 0 \in V$

$$\phi(\mathbf{x}, \mathbf{x}) > 0.$$

4.  $\phi$  is *non-degenerate*. If  $\mathbf{x} \in V$  is such that for every  $\mathbf{y} \in V$   $\phi(\mathbf{x}, \mathbf{y}) = 0$ , then  $\mathbf{x} = 0$ .

**Problem 1.** Make sure you are absolutely comfortable with the fact that the standard inner product in  $\mathbb{R}^n$  indeed satisfies all the above conditions.

If  $V$  is a finite dimensional vector space, after the choice of a basis, an inner product (in fact any bilinear form) is represented by a matrix  $G$ .

**Problem 2.** *How? What is the matrix that represents the standard inner product in  $\mathbb{R}^n$ ?*

Then conditions 2, 3, 4 impose conditions on the matrix  $G$ .

**Problem 3.** *Assume  $V$  is two dimensional (which is the case we will be concerned with). Figure out what these conditions are.*

We often denote an inner product with angle brackets or with a dot. If we want to stress that an inner product is nonstandard we may put a subscript indicating that (a subscript under a dot is kind of confusing in L<sup>A</sup>T<sub>E</sub>X but bear with it):

$$\phi(\mathbf{x}, \mathbf{y}) \triangleq \langle \mathbf{x}, \mathbf{y} \rangle_G \triangleq \mathbf{x} \cdot_G \mathbf{y}.$$

## 2 The Metric on Tangent Spaces

Let  $S$  be a regular surface, and  $\varphi : U \rightarrow S$  a local parameterization around a point  $P \in S$  such that  $\varphi(\underline{0}) = P$ . We proved that for every  $(\bar{u}, \bar{v}) \in U$ ,  $d\varphi|_{(\bar{u}, \bar{v})}$  gives an isomorphism between  $\mathbb{R}^2$  and  $T_q(S)$  for any point in the image of  $\varphi$ . We use this isomorphisms to define a family of inner products on  $\mathbb{R}^2$ . Denote  $e_1 = (1, 0)$  and  $e_2 = (0, 1)$  the standard basis vectors on the plane, then

$$\langle e_1, e_1 \rangle_{G_\varphi} := \left\langle \frac{\partial \varphi}{\partial u}|_{(u,v)}, \frac{\partial \varphi}{\partial u}|_{(u,v)} \right\rangle \triangleq \varphi_u(u, v) \cdot \varphi_u(u, v).$$

$$\langle e_1, e_2 \rangle_{G_\varphi} := \left\langle \frac{\partial \varphi}{\partial u}|_{(u,v)}, \frac{\partial \varphi}{\partial v}|_{(u,v)} \right\rangle \triangleq \varphi_u(u, v) \cdot \varphi_v(u, v).$$

$$\langle e_2, e_2 \rangle_{G_\varphi} := \left\langle \frac{\partial \varphi}{\partial v}|_{(u,v)}, \frac{\partial \varphi}{\partial v}|_{(u,v)} \right\rangle \triangleq \varphi_v(u, v) \cdot \varphi_v(u, v).$$

**Problem 4.** *What is the matrix  $G_\varphi(u, v)$  that represents this inner products?*

**Definition.** *The collection of ALL non-standard inner products  $G_\varphi$  on ALL possible local parameterizations of  $S$  is called a **metric** on  $S$ .*

To “understand” a metric on a surface, it is sufficient to understand it on a collection of local parameterizations that cover the surface.

**Problem 5.** *Describe the metric on the cylinder, using either of the two parameterizations we studied.*

**Problem 6.** *Consider a local parameterization for the sphere given by*

$$\varphi(u, v) = (\cos(u) \cos(v), \sin(u) \cos(v), \sin(v)).$$

*Describe the matrix  $G_\varphi$ .*

**Problem 7.** Give a collection of parameterizations that cover the torus and compute the metric on the torus.

**Problem 8.** Compute the metric for a regular surface  $S$  which is the graph of a differentiable function  $F : \mathbb{R}^2 \rightarrow \mathbb{R}$

### 3 Norm of Tangent Vectors and Measuring Angles

We can use the metric to define a non-standard norm on plane vectors. If  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^2$ , then:

$$|\mathbf{x}|_{G_\varphi} = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle_{G_\varphi}}.$$

Now we can use the formula:

$$\cos(\theta) = \frac{\langle \mathbf{x}, \mathbf{y} \rangle_{G_\varphi}}{|\mathbf{x}|_{G_\varphi} |\mathbf{y}|_{G_\varphi}}.$$

In both cases, what we are really talking about is the norms or the angle between the vectors  $d\varphi|_{(u,v)}(\mathbf{x})$  and  $d\varphi|_{(u,v)}(\mathbf{y})$ .

**Problem 9.** Compute a few norms and angles of the basis vectors  $e_1$  and  $e_2$  for the various examples of metrics studied in the previous section.

Recall that the **local coordinate lines** of a local parameterization  $\varphi$  are the images of the lines  $u = \text{const.}$ ,  $v = \text{const.}$  via  $\varphi$ .

**Problem 10.** Under what condition on the metric do local coordinate lines (that intersect) intersect at right angles?

A parameterization is called **orthogonal** if all coordinate lines (that intersect) intersect at right angles.

**Problem 11.** Which of the parameterizations in the previous section are orthogonal?

### 4 Measuring Lengths and Areas

We can use the metric to compute lengths of curves on a surface, and areas on the surface as integrals in the plane rather than in three-dimensional space.

Let  $\alpha(t) = (x(t), y(t), z(t)) : [0, 1] \rightarrow \mathbb{R}^3$  a parameterized curve whose trace lives inside a regular surface  $S$ . To make our statements simpler let us assume that the image of  $\alpha$  is contained in a local chart  $(U, \varphi)$ . Denote by  $\beta(t) = (u(t), v(t))$  the composition  $b = \varphi^{-1} \circ \alpha$ .

Then the length of the trace of  $\alpha$  is:

$$L(\alpha) = \int_0^1 |\beta'(t)|_{G_\varphi} dt = \int_0^1 \sqrt{Eu'^2 + 2Fu'v' + Gv'^2} dt, \quad (1)$$

where for rather irrelevant historical reasons the letters  $E, F, G$  are used to denote the entries of the matrix  $G_\varphi$  (up to you to figure out which is which).

**Problem 12.** *Understand formula (1).*

**Problem 13.** *Play with the examples of Section 2 and compute some lengths of some natural curves on such surfaces.*

Now suppose  $R$  is a bounded region inside a local chart  $(U, \varphi)$  in a regular surface. Let  $Q = \varphi^{-1}(R)$ . We compute the area of  $R$ :

$$A(R) = \int_Q |e_1|_{G_\varphi} |e_2|_{G_\varphi} |\sin(\theta_{G_\varphi})| dudv, \quad (2)$$

where  $\theta_{G_\varphi}$  is the angle between  $e_1$  and  $e_2$  computed using the metric  $G_\varphi$ .

**Problem 14.** *Understand (2) and then derive an expression in terms of the entries of the metric  $E, F, G$ .*

**Problem 15.** *Use your formula to compute some areas of some of the examples in Section 2.*