

## The Navier Stokes Equations

In preparation for considering the N-S equations, we introduce some new definitions and recall some old ones.

### Vector Valued Functions of $t$

Let  $X$  denote a Banach space and, for  $T > 0$ , let  $C[0, T; X]$  denote continuous functions of  $t$ ,  $0 \leq t \leq T$ , with values in  $X$ . That is,

$$\|f(t_n) - f(t)\|_X \rightarrow 0 \text{ as } t_n \rightarrow t \in [0, T].$$

$C[0, T; X]$  is complete for the norm  $\|f\|_{C[0, T; X]} = \max_{0 \leq t \leq T} \|f(t)\|_X$ .

For  $1 \leq p < \infty$ , let  $L^p[0, T; X]$  denote measurable functions of  $t$ ,  $0 \leq t \leq T$ , with values in  $X$  such that

$$\|f\|_{L^p[0, T; X]} = \left( \int_0^T \|f(t)\|_X^p dt \right)^{1/p} < \infty.$$

$L^p[0, T; X]$  is complete for this norm and completing the space  $C[0, T; X]$  in this norm produces  $L^p[0, T; X]$ ; i.e.,  $C[0, T; X]$  is dense in  $L^p[0, T; X]$ .

For  $1 \leq p < \infty$ , let  $W^{1,p}[0, T; X]$  denote functions  $f(t) \in L^p[0, T; X]$  such that for some  $g(t)$  in  $L^p[0, T; X]$ ,

$$f(t) = f(0) + \int_0^t g(s) ds, \quad t \in [0, T].$$

Then it is a classic measure theoretic result that the function  $f$  is strongly differentiable with

$$f'(t) = \lim_{h \rightarrow 0} \left[ \frac{f(t+h) - f(t)}{h} \right] = g(t),$$

and since weak (distributional) and strong derivatives coincide,  $W^{1,p}[0, T; X]$  consists of functions  $f(t) \in L^p[0, T; X]$  such that  $f'(t) \in L^p[0, T; X]$ .

We can define a norm on  $W^{1,p}[0, T; X]$  by

$$\|f\|_{W^{1,p}[0, T; X]} = \left( \int_0^T \{ \|f(t)\|_X^p + \|f'(t)\|_X^p \} dt \right)^{1/p}$$

and  $W^{1,p}[0, T; X]$  is complete in this norm and completing the space  $C[0, T; X]$  in this norm produces  $W^{1,p}[0, T; X]$ ; i.e.,  $C[0, T; X]$  is dense in  $W^{1,p}[0, T; X]$ .

Let  $V$  denote a Banach space continuously, and densely embedded in a Hilbert space  $H$  which is identified with its dual,  $H = H'$ . Then we have  $V \subset H \subset V'$  so that the duality pairing on  $V \times V'$  is realized by extending the inner product on  $H$ ,

$$\langle f, v \rangle_{V \times V'} = (f, v)_H \quad \forall v \in V.$$

Now for  $1 < p < \infty$ , we define

$$W_p(0, T) = \{f(t) \in L^p[0, T; V] \text{ such that } f'(t) \in L^q[0, T; V']\}$$

with

$$\|f\|_{W_p(0, T)} = \|f\|_{L^p} + \|f'\|_{L^q}, \quad \frac{1}{p} + \frac{1}{q} = 1.$$

Then it is an extension of a previous result that,

- i)  $W_p(0, T)$  is contained in  $C[0, T; H]$ ; i.e., there exists a constant  $C > 0$  such that  $\forall f \in W_p(0, T)$

$$\|f\|_{C[0, T; H]} \leq C \|f\|_{W_p(0, T)}$$

- ii)  $\|u(\bullet)\|_H^2$  is absolutely continuous on  $[0, T]$  and

$$\frac{d}{dt} \|u(t)\|_H^2 = 2(u'(t), u(t))_H \quad a.e. \ t \in [0, T]$$

- iii)  $\forall f, g \in W_p(0, T)$   $(f(\bullet), g(\bullet))_H$  is absolutely continuous on  $[0, T]$  and

$$\frac{d}{dt} (f(t), g(t))_H = (f'(t), g(t))_H + (f(t), g'(t))_H \quad a.e. \ t \in [0, T]$$

- iv) If  $V, V'$  are reflexive, and the embeddings  $V \subset H, H \subset V'$  are compact and continuous, respectively, then the inclusion of  $W_p(0, T)$  into  $L^p[0, T; H]$  is compact.

We are going to consider the evolution N-S equations where the solutions will belong to  $L^p[0, T; V]$  and the equation is understood to hold in the space  $L^q[0, T; V']$ . It follows from the result i) above that the solution  $u(t)$  is absolutely continuous with values in  $H$  (not just in  $V'$ ) so the initial conditions are attained in  $H$ .

### Linearized N-S Equations

In order to prepare for considering the nonlinear evolution N-S equations, we will first consider the linearized version.

$$\begin{aligned} \partial_t \vec{u}(x, t) - \nu \nabla^2 \vec{u}(x, t) + \nabla p &= \vec{f}(x, t) & (x, t) \in U \times (0, T) = U_T \\ \operatorname{div} \vec{u}(x, t) &= 0 & \text{in } U_T \\ \vec{u} &= \vec{0} & (x, t) \in \partial U \times (0, T) = \partial U_T \\ \vec{u}(x, 0) &= \vec{u}_0(x) & x \in U \end{aligned}$$

Now recall

$K = \{\vec{\phi} \in C_c^\infty(U)^n : \operatorname{div} \vec{\phi} = 0\} =$  divergence free vector test functions

$H =$  completion of  $K$  in the norm of  $L^2(U)^n = \{\vec{u} \in L^2(U)^n : \operatorname{div} \vec{u} = 0, T\vec{u} = 0\}$

$V =$  completion of  $K$  in the norm of  $H_0^1(U)^n = \{\vec{u} \in H_0^1(U)^n : \operatorname{div} \vec{u} = 0\}$

and

$$\forall \vec{u}, \vec{v} \in H, \quad ((\vec{u}, \vec{v}))_0 = \int_U \vec{u} \cdot \vec{v} dx = (\vec{u}, \vec{v})_H$$

$$\|\vec{u}\|_0^2 = \int_U \vec{u} \cdot \vec{u} dx = \|\vec{u}\|_H^2.$$

$$\forall \vec{u}, \vec{v} \in V, \quad [[\vec{u}, \vec{v}]] = \sum_{i=1}^n \int_U \partial_i \vec{u} \cdot \partial_i \vec{v} dx = (\vec{u}, \vec{v})_V$$

$$\|\vec{u}\|_V^2 = \sum_{i=1}^n \int_U \partial_i \vec{u} \cdot \partial_i \vec{u} dx = \|\nabla \vec{u}\|_H^2.$$

It follows from the Poincare inequality that for  $U$  bounded,  $\|\vec{u}\|_V$  defines a norm on  $V$  that is equivalent to the  $H^1(U)^n$ -norm. Then  $V, V'$  are reflexive, and the embeddings  $V \subset H, H \subset V' = H^{-1}(U)^n$  are compact and continuous, respectively.

For  $\vec{u} \in V$ , fixed, define  $F(\vec{v}) = [[\vec{u}, \vec{v}]]$  for  $\vec{v} \in V$ . Then  $F \in V'$  and we can use the notation  $F = A\vec{u}$  to indicate the dependence of  $F$  on  $\vec{u}$ ; i.e.,  $A : V \rightarrow V'$ . Then

$$[[\vec{u}, \vec{v}]] = F(\vec{v}) = \langle A\vec{u}, \vec{v} \rangle_{V \times V'} = (A\vec{u}, \vec{v})_H \quad \forall \vec{v} \in V.$$

Then we can say that  $\vec{u}(t) \in L^2[0, T; V]$  is a solution of the linearized N-S system if

$$\begin{aligned} (\vec{u}'(t), \vec{v})_H + \nu [[\vec{u}(t), \vec{v}]] &= (\vec{f}(t), \vec{v})_H \quad \forall \vec{v} \in V, \text{ a.e. in } (0, T). \\ \vec{u}(0) &= \vec{u}_0 \end{aligned}$$

or, equivalently, if

$$\begin{aligned} \vec{u}'(t) + \nu A\vec{u}(t) &= P\vec{f}(t), \quad \text{in } V' \text{ a.e. in } (0, T) \\ \vec{u}(0) &= \vec{u}_0 \end{aligned}$$

where  $P : L^2(U)^n = H \oplus H^\perp \rightarrow H$ ,  
 $P : H_0^1(U)^n \rightarrow V$ ,

and  $A = -P\nabla^2 : V \rightarrow V'$ .

Evidently  $\vec{u}(t) \in L^2[0, T; V], \vec{u}'(t) \in L^2[0, T; V']$ , so  $\vec{u}(t) \in W_2(0, T)$  and the initial condition is satisfied in the sense of  $C[0, T; H]$  for  $\vec{u}_0 \in H$ .

**Theorem** Suppose  $\vec{f}(t) \in L^2[0, T; V']$ , and  $\vec{u}_0 \in H$ . Then the linearized N-S system has a unique weak solution  $\vec{u}(t) \in L^2[0, T; V]$ , with  $\vec{u}'(t) \in L^2[0, T; V']$ , so  $\vec{u}(t) \in W_2(0, T)$ . The initial condition is satisfied in the sense of  $C[0, T; H]$ .

Proof-

1) Define an approximate solution-

Let  $\{\vec{w}_j\}$  denote the orthonormal basis of eigenfunctions of A and, for  $N = 1, 2, \dots$

$$\vec{u}_N(t) = \sum_{j=1}^N c_{j,N}(t) \vec{w}_j,$$

where the  $\{c_{j,N}\}$  are chosen such that for  $1 \leq k \leq N$ ,

$$\begin{aligned} \left( \frac{d}{dt} \vec{u}_N(t), \vec{w}_k \right)_H + \nu [[\vec{u}_N(t), \vec{w}_k]] &= (\vec{f}(t), \vec{w}_k)_H \\ (\vec{u}_N(0), \vec{w}_k)_H &= (\vec{u}_0, \vec{w}_k)_H \end{aligned}$$

Since  $[[\vec{w}_j, \vec{w}_k]] = (A\vec{w}_j, \vec{w}_k)_H = \lambda_j (\vec{w}_j, \vec{w}_k)_H$  this approximate system is equivalent to

$$\begin{aligned} \frac{d}{dt} c_{j,N}(t) + \nu \lambda_j c_{j,N}(t) &= f_j(t) \quad 1 \leq j \leq N, \\ c_{j,N}(0) &= (\vec{u}_0, \vec{w}_j)_H \end{aligned}$$

and this linear system of ordinary differential equations has a unique solution for each N.

2) A-priori estimates-

For each N,

$$\left\{ \begin{array}{l} a) \|\vec{u}_N(\bullet)\|_{C[0, T; H]} \\ b) \|\vec{u}_N(\bullet)\|_{L^2[0, T; V]} \\ c) \|\partial_t \vec{u}_N(\bullet)\|_{L^2[0, T; V']} \end{array} \right\} \leq C(\|u_0\|_H + \|\vec{f}\|_{L^2[0, T; V']})$$

3) Existence

$\{\vec{u}_N(t)\}$  is bounded in  $L^2[0, T; V]$  by 2b)

$\{\partial_t \vec{u}_N(t)\}$  is bounded in  $L^2[0, T; V']$  by 2c)

Then there exists a subsequence  $\{\vec{u}_{N'}(t)\}$  such that

$$\begin{aligned} \vec{u}_{N'}(t) &\rightarrow \vec{u}(t) \quad \text{weakly in } L^2[0, T; V] \\ \partial_t \vec{u}_{N'}(t) &\rightarrow \vec{v}(t) \quad \text{weakly in } L^2[0, T; V'] \end{aligned}$$

Then the usual distributional argument implies  $\partial_t \vec{u} = \vec{v}(t)$ , hence  $\vec{u}(t) \in W_2[0, T] \subset C[0, T; H]$ .

It remains to be shown that the limit,  $\vec{u}(t)$ , is a weak solution of the linearized N-S system. Let

$$V_N = \left\{ \vec{v}(t) = \sum_{k=1}^N a_k(t) \vec{w}_k, a_k \in C^1[0, T], \forall k \right\}$$

Then it follows from the approximate equation that

$$\begin{aligned} \int_0^T (\vec{u}'_N(t), \vec{v}(t))_H dt + \nu \int_0^T [ [\vec{u}_N(t), \vec{v}(t)] ] dt &= \int_0^T (\vec{f}(t), \vec{v}(t))_H dt \quad \forall \vec{v} \in V_N \\ \downarrow & \quad \quad \quad \downarrow \\ \text{weakly in } L^2[0, T; V'] & \quad \quad \quad \text{weakly in } L^2[0, T; V] \\ \downarrow & \quad \quad \quad \downarrow \\ \int_0^T (\vec{u}'(t), \vec{v}(t))_H dt + \nu \int_0^T [ [\vec{u}(t), \vec{v}(t)] ] dt &= \int_0^T (\vec{f}(t), \vec{v}(t))_H dt \quad \forall \vec{v} \in \bigcup_{N>0} V_N \end{aligned}$$

Since  $\{\vec{w}_k\}$  is an orthonormal basis for  $V$ , it follows that  $\bigcup_{N>0} V_N$  is dense in  $L^2[0, T; V]$  and thus the limit is a weak solution for the pde. To see that  $\vec{u}(0) = \vec{u}_0$ , we choose a  $v \in C^1[0, T; V]$  such that  $\vec{v}(T) = 0$  and integrate by parts with respect to  $t$  in the approximate equation before passing to the limit.

We can even show that the approximate solution  $\vec{u}_N$  converges strongly in the norm of  $L^2[0, T; V]$  to  $\vec{u}(t)$  using the argument we applied to linear parabolic equations in the previous course. Uniqueness is proved as it was then as well. ■

### The Semigroup Approach to NL Navier Stokes

Consider a bounded open set  $U \subset R^n$  ( $n = 2, 3$ ) with smooth boundary  $\partial U$ . Then the nonlinear N-S system is

$$\begin{aligned} \partial_t \vec{u}(x, t) - \nu \nabla^2 \vec{u}(x, t) + (\vec{u} \cdot \nabla) \vec{u} + \nabla p &= \vec{f}(x, t) \quad (x, t) \in U_T \\ \operatorname{div} \vec{u}(x, t) &= 0 \quad \text{in } U_T \\ \vec{u} &= \vec{0} \quad (x, t) \in \partial U \times (0, T) = \partial U_T \\ \vec{u}(x, 0) &= \vec{u}_0(x) \quad x \in U \end{aligned}$$

This can be expressed abstractly as

$$\begin{aligned} \vec{u}'(t) + A\vec{u}(t) &= \vec{F}(\vec{u}(t), t) \quad \text{in } (0, T) \\ \vec{u}(0) &= \vec{u}_0 \end{aligned}$$

where

$$\begin{aligned} A &= -P(\nu \nabla^2): D_A \rightarrow H \\ \vec{F}(\vec{u}(t), t) &= P\vec{f}(\bullet, t) - P(\vec{u} \cdot \nabla) \vec{u}(t). \end{aligned}$$

We must be able to show that

$$\vec{F} : H_\alpha \times [0, \infty) \rightarrow H$$

such that for some  $0 < \mu < 1$ ,

$$\|\vec{F}(\vec{u}(t), t) - \vec{F}(\vec{v}(\tau), \tau)\|_H \leq C_R (|t - \tau|^\mu + \|\vec{u} - \vec{v}\|_\alpha) \quad \forall t, \tau \in [0, T], \vec{u}, \vec{v} \in B_R(0) \subset H_\alpha$$

If  $\vec{f}(t)$  is Lipschitz continuous with values in H, then

$$\left\| P\vec{f}(t) - P\vec{f}(\tau) \right\|_H \leq C|t - \tau| \quad \forall t, \tau \in [0, \infty).$$

Now,  $H_\alpha \subset W^{1,2}(U)$  if  $2\alpha > 1$  and  $H_\alpha \subset C^0(\bar{U})$  if  $4\alpha > n$ . Then for  $N(\vec{u}) = (\vec{u} \cdot \nabla)\vec{u}$  we have

$$\|N(\vec{u})\|_H = \left( \int_U |(\vec{u} \cdot \nabla)\vec{u}|^2 dx \right)^{1/2} \leq \|\vec{u}\|_\infty \|\nabla\vec{u}\|_0$$

and

$$\begin{aligned} \|\vec{u}\|_\infty &\leq C_1 \|\vec{u}\|_\alpha \quad \text{if } 4\alpha > n \\ \|\nabla\vec{u}\|_0 &= \|\vec{u}\|_V \leq C_2 \|\vec{u}\|_\alpha, \quad \text{if } 2\alpha > 1. \end{aligned}$$

Therefore,  $\|N(\vec{u})\|_H \leq C \|\vec{u}\|_\alpha^2$  for  $\left\{ \begin{array}{l} \alpha > \frac{1}{2} \quad n = 2 \\ \alpha > \frac{3}{4} \quad n = 3 \end{array} \right\}$

which implies  $N : H_\alpha \rightarrow H$  is bounded for  $\alpha > \frac{n}{4}$ .

In addition,

$$\begin{aligned} \|N(\vec{u}) - N(\vec{v})\|_H &= \|\vec{u} \cdot \nabla\vec{u} - \vec{v} \cdot \nabla\vec{v}\|_H \\ &\leq \|(\vec{u} \cdot \nabla)(\vec{u} - \vec{v})\|_H + \|\vec{u} - \vec{v}\|_\infty \|\nabla\vec{v}\|_H \\ &\leq \|\vec{u}\|_\alpha \|(\vec{u} - \vec{v})\|_V + \|\vec{u} - \vec{v}\|_\alpha \|\vec{v}\|_V \\ &\leq (\|\vec{u}\|_\alpha + \|\vec{v}\|_\alpha) \|\vec{u} - \vec{v}\|_\alpha \leq 2R \|\vec{u} - \vec{v}\|_\alpha \end{aligned}$$

for all  $\vec{u}, \vec{v} \in B_R(0) \subset H_\alpha$  provided  $\alpha > \frac{3}{4}$ . (when  $n = 2$ ,  $\alpha > \frac{1}{2}$  is sufficient). Then we have,

**Theorem** For  $\alpha > \frac{n}{4}$  and all  $\vec{u}_0 \in H_\alpha$ , and for  $\vec{f}(t)$  Lipschitz continuous in t with values in H, there is a positive  $T > 0$  and  $\vec{u} \in C[0, T; H_\alpha] \cap C^1[0, T; H_0]$  such that u solves the abstract N-S initial value problem (in the strong sense since  $-A$  generates an analytic

semigroup). In addition,

$$\nabla p = \vec{f} - \partial_t \vec{u} - A\vec{u} - \vec{u} \cdot \nabla \vec{u} \in C[0, T; H_0].$$

The solution is unique but there is no information about the size of  $T$ . We could try to establish that

$$\|\vec{u}(t)\|_\alpha \leq K \quad \text{for all } t$$

by means of an energy estimate; i.e. let

$$E(t) = \int_U \left\{ \frac{1}{2} |\nabla \vec{u}(t)|^2 - \Phi(\vec{u}) \right\} dx \quad \Phi'(\vec{u}) = F(\vec{u}).$$

Then under appropriate hypotheses on  $F$ , we may be able to show that  $E'(t) \leq 0$ , and

$$\|\vec{u}(t)\|_{1/2}^2 \leq k_0 E(t) + k_1.$$

This gives a uniform bound on  $\|\vec{u}(t)\|_{1/2}$  but since we need  $\alpha > \frac{1}{2}$  to get existence of a solution in  $H_\alpha$ , this approach fails. (i.e., energy estimates always involve the so-called "energy norm",  $\|\vec{u}(t)\|_{1/2} = \|\vec{u}(t)\|_\gamma$ ).