

## 8 Jordan canonical form

Throughout this section, we will work with an operator  $T \in \mathcal{L}(V)$ , and assume that its characteristic polynomial  $\chi_T(X)$  factors as a product of linear factors, so that

$$\chi_T(X) = \prod_{i=1}^r (X - \lambda_i)^{e_i}.$$

This always happens if  $V$  is a complex vector space, and sometimes happens if  $V$  is a real vector space.

Recall that we have the following concepts. Let  $T$  be an operator on a finite-dimensional vector space. Choose a basis for  $T$ , ultimately irrelevant. We have defined the

- Characteristic polynomial:  $\det(X \text{id} - [T])$ .
- Minimal polynomial; the smallest polynomial such that  $\text{minpoly}(T) = 0$ .

The characteristic polynomial encodes information about the eigenvalues. In fact,  $\lambda$  is an eigenvalue if and only if  $\chi_T(\lambda) = 0$ .

It turns out that the zeros of the minimal polynomial are the same; we have  $\chi_T(\lambda) = 0$  if and only if  $\mu_T(\lambda) = 0$ .

Let  $\lambda_1, \dots, \lambda_r$  be the distinct eigenvalues of  $T$ . Let  $U_i = \text{null}(T - \lambda_i)$ , and write  $\chi_T(X) = \prod (X - \lambda_i)^{e_i}$ . We know that  $T$  is diagonalizable if and only if  $e_i = \dim U_i$  for each  $i$ .

Our goal is to assess what happens when this fails. In doing so, we'll get a canonical form for an operator, whether or not it's diagonalizable. As a side effect, we'll be able to compute the minimal polynomial of an operator, too.

Before going too far, it's nice to have the following results:

**Lemma** If  $U \subseteq V$  and  $T \in \mathcal{L}(V)$  and  $U$  invariant under  $T$ , then  $\text{charpoly}_{T|_U} \mid \text{minpoly}_{T|_V}$ .

**Proof** Choose a basis, and then use facts about determinants. □

**Lemma** If  $U \subseteq V$  and  $T \in \mathcal{L}(V)$  and  $U$  invariant under  $T$ , then  $\text{minpoly}_{T|_U} \mid \text{minpoly}_{T|_V}$ .

**Proof** Sketch, anyway. Let  $f$  and  $g$  be the respective minimal polynomials. Divide  $g$  by  $f$ , so that  $g(X) = a(X)f(X) + r(X)$ ,  $\deg r < \deg f$ . Then  $r(T)$  annihilates  $U$ , and thus must be zero; otherwise, this would contradict minimality of  $f$ . □

### 8.1 Generalized eigenvectors

There are two sources of difficulty in diagonalizing matrices. One is that, depending on which numbers we work with, a given polynomial may not factor, e.g.,  $X^2 + 1$  working over the reals. By fiat, we have eliminated this possibility.

The other is somehow more intrinsic, and not so easily fixed. Consider  $T \in \mathcal{L}(\mathbb{R}^2)$  with matrix  $[T]_{\text{Std}} = \begin{pmatrix} 3 & 1 \\ 0 & 3 \end{pmatrix}$ . Then 3 is the only eigenvalue, but  $\dim \text{null}(T - 3 \text{id}) = 1$ . What's going on here?

In this example, the *algebraic multiplicity* of the eigenvalue is 2, reflecting the fact that the characteristic polynomial is  $(X - 2)^2$ . Still, if you take the operator  $(T - 3)^2$ , then *everything* is annihilated.

In general, if  $T \in \mathcal{L}(V)$  and  $\lambda$  is an eigenvalue of  $T$ , a vector  $v \in V$  is called a *generalized eigenvector* of  $T$  if

$$(T - \lambda \text{id})^j v = 0$$

for some  $j$ .

So, we need to get good at understanding iterates of operators.

**Lemma**

- a. For all  $k$ ,  $\text{null } S^k \subseteq \text{null } S^{k+1}$ .
- b. If  $\text{null } S^k = \text{null } S^{k+1}$ , then for all  $j$   $\text{null } S^k = \text{null } S^{k+j}$ .

**Proof** First part is easy. For the last, suppose we know that  $\text{null } S^k = \text{null } S^{k+j}$ ; we will try to show that  $\text{null } S^k = \text{null } S^{k+j+1}$ . One inclusion is free; for the other, we need to show that if  $S^{k+j+1}(v) = 0$ , then  $S^k v = 0$ . But

$$\begin{aligned} 0 &= S^{k+j+1}(v) \\ &= S^{k+1}(S^j v) \\ S^j v &\in \text{null } S^{k+1} \\ S^j v &\in \text{null } S^k \\ v &\in \text{null } S^{j+k} \\ &= \text{null } S^k \end{aligned}$$

□

**Proposition** If  $n = \dim V$ , then  $\text{null } S^n = \text{null } S^{n+1} = \dots$ .

**Proof** Let  $k$  be the first value at which  $\text{null } S^k = \text{null } S^{k+1}$ . Then we have  $\dim \text{null } S < \dim \text{null } S^2 \dots < \dim \text{null } S^k \leq n$ , so that  $k \leq n$ . □

We can do something similar with images of operators.

**Lemma**  $S \in \mathcal{L}(V)$ ,  $\dim V = n$ .

- a. For all  $k$ ,  $\text{im}(S^k) \supseteq \text{im}(S^{k+1})$ .
- b.  $\text{im } S^n = \text{im } S^{n+1} = \dots$ .

**Proof** For the first part, if  $v \in \text{im } S^{k+1}$ , then  $v = S^{k+1}(w) = S^k(Sw) \in \text{im } S^k$ .

For the second, we know that if  $j \geq n$ , then  $\text{im } S^j = \text{im } S^n$ . But

$$\begin{aligned}\dim V &= \dim \text{im } S^j + \dim \text{null } S^j \\ &= \dim \text{im } S^j + \dim \text{null } S^n \\ &= \dim \text{im } S^n + \dim \text{null } S^n \\ \dim \text{im } S^n &= \dim \text{im } S^j\end{aligned}$$

□

**Corollary**  $S$  acts invertibly on  $\text{im } S^n$ .

**Lemma** If  $S \in \mathcal{L}(V)$ ,  $\dim V = n$ , then there is a direct sum decomposition

$$V = \text{im } S^n \oplus \text{null } S^n.$$

**Proof** Considering the operator  $S^n$ , we know that  $\dim \text{im } S^n + \dim \text{null } S^n = n$ . To show that we get a direct sum, we need to show that the intersection is trivial, so that the dimension of the space spanned by them is  $n$ , and then the sum is direct.

So, suppose  $v \in \text{im } S^n \cap \text{null } S^n$ . Then  $v = S^n(w)$  for some  $w$ , and  $S^n(v) = 0$ .

$$\begin{aligned}S^n(v) &= 0 \\ S^{2n}(w) &= 0\end{aligned}$$

But  $\text{null } S^n = \text{null } S^{2n}$ , so

$$\begin{aligned}S^n(w) &= 0 \\ v &= 0\end{aligned}$$

□

**Theorem** Let  $\lambda$  be an eigenvalue of an operator  $T \in \mathcal{L}(V)$ . Then there is a decomposition

$$V = \text{null}(T - \lambda \text{id})^n \oplus U$$

where each summand is invariant under  $T$ , and  $\lambda$  is not an eigenvalue for the action of  $T$  on  $U$ .

**Proof** Consider  $S = T - \lambda \text{id}$ , and apply the previous result. We get

$$V = \text{null}(S^n) \oplus \text{im } S^n$$

and we call the last part  $U$ . Now, if  $(T - \lambda \text{id})^n(v) = 0$ , then  $T(T - \lambda \text{id})^n(v) = 0$ . This shows that one summand is invariant under  $T$ , and thus the other is, too. Moreover, since  $S$  is invertible on  $\text{im } S^n$ ,  $\lambda$  is not an eigenvalue for the action of  $T$  on  $\text{im } S^n$ . □

Note that  $\text{null}(T - \lambda \text{id})^n$  is exactly the space of *generalized* eigenvectors associated to  $\lambda$ .

**Corollary** In the above decomposition, we have

$$\begin{aligned}\text{charpoly}_T(X) &= (X - \lambda)^{\dim \text{null}(T - \lambda \text{id})^n} \text{charpoly}_{T|_U}(X) \\ \text{minpoly}_T(X) &= \text{minpoly}(T|_{\text{null}(T - \lambda \text{id})^n}) \text{minpoly}(T|_U)\end{aligned}$$

**Proof** For the first one, use the fact that the decomposition of  $V$  forces a block-diagonal structure on  $[T]$ ; now use properties of determinants.

For the second, the minimal polynomial clearly divides the product. Then use the fact that they have no factor in common...  $\square$

**Theorem** If  $T \in \mathcal{L}(V)$  a complex vector space, let  $\lambda_1, \dots, \lambda_r$  be the distinct eigenvalues of  $T$ . Then

$$V = \bigoplus \text{null}(T - \lambda_i \text{id})^n.$$

**Proof** Let  $\lambda_1$  be the first such eigenvalue; write  $V = \text{null}(T - \lambda_1)^n \oplus U_1$ . Note that  $\lambda_1$  is not an eigenvalue of  $T$  acting on  $U_1$ . Now recurse; do the same thing for  $U_1$ .  $\square$

## 8.2 Bases for nilpotent actions

We work with an operator  $S$ , which we think of as being  $T - \lambda$ . Our goal is to understand the generalized eigenspace associated to  $\lambda$ , that is, the nullspace of  $S^n$ .

We can build up the space as follows.

Suppose  $v \in V$ ,  $S^j(v) = 0$ ,  $S^{j-1}(v) \neq 0$ .

**Lemma** The set  $\{S^{j-1}(v), S^{j-2}(v), \dots, S(v), v\}$  is linearly independent.

**Proof** We will prove by induction that  $\{S^{j-1}(v), \dots, S^{j-i}(v)\}$  is linearly independent. This is obvious for  $i = 1$ , since we're guaranteed that  $S^{j-1}(v) \neq 0$ .

Otherwise, assume we've secured the statement for  $i - 1$ , and that

$$\begin{aligned}a_{j-1}S^{j-1}(v) + a_{j-1}S^{j-2}(v) + \dots + a_{j-i+1}S^{j-i+1}(v) + a_{j-i}S^{j-i}(v) &= 0 \\ S^{i-1}(a_{j-1}S^{j-1}(v) + a_{j-1}S^{j-2}(v) + \dots + a_{j-i+1}S^{j-i+1}(v) + a_{j-i}S^{j-i}(v)) &= 0 \\ a_{j-i}S^{j-1}(v) &= 0 \\ a_{j-i} &= 0 \\ a_{j-1}S^{j-1}(v) + a_{j-1}S^{j-2}(v) + \dots + a_{j-i+1}S^{j-i+1}(v) &= 0\end{aligned}$$

so that each  $a_i = 0$ , by induction.  $\square$

For such a  $v$ , note that the space  $U_v = \text{span}\{S^{j-1}(v), \dots, S^2(v), S(v), v\}$  is invariant under  $S$ . The matrix of  $S|_{U_v}$  is a *nilpotent Jordan block*, which we should draw now but I'm too damned lazy.

**Lemma** The minimal polynomial for  $S|_{U_v}$  is  $X^j$ .

**Proof** □

### 8.3 Computing nilpotent Jordan forms

Let  $K_j = \text{null}(S^j)$ . There is always an inclusion  $K_{j-1} \subseteq K_j$ . Let  $L_j$  be a complement so that  $K_j = K_{j-1} \oplus L_j$ . Then  $L_j$  is the set of elements which are annihilated by  $S^j$ , but not by  $S^{j-1}$ .

**Lemma** Suppose  $j \geq 2$ . Then  $S(L_j) \subseteq L_{j-1}$ . If  $v \in L_j$  and  $S(v) = 0$ , then  $v = 0$ .

**Corollary** If  $v_1, \dots, v_r \in L_j$  are linearly independent, then so are  $S(v_1), \dots, S(v_r)$ .

Let  $k_j = \dim K_j$ ,  $\ell_j = \dim L_j$ . Then  $\ell_j = k_j - k_{j-1}$ .

We can read off the Jordan blocks, in the following sense.

Suppose that the chain stabilizes at  $m$ , so that  $K_m = K_{m+1} = \dots$ .

Then there are:

- $\ell_m$  Jordan blocks of size  $m$ .
- $\ell_{m-1} - \ell_m$  Jordan blocks of size  $m - 1$
- $\ell_{m-2} - \ell_{m-1}$  Jordan blocks of size  $m - 2$ .
- $\dots$
- $\ell_k - \ell_{k+1}$  Jordan blocks of size  $k$ .

The point is that, at each stage, we can fill up part of  $L_k$  using the images of elements from  $L_{k+1}$ ; the rest come from Jordan blocks of exact size  $k$ .

Moreover, the number of Jordan blocks of size *at least*  $k$  is just  $\ell_k$ .

**Example** Consider the operator  $S \in \mathcal{L}(\mathbb{R}^5)$  with matrix

$$[S] = \begin{bmatrix} 58 & -224 & 511 & -214 & 4 \\ 16 & -62 & 139 & -58 & 1 \\ 6 & -24 & 50 & -20 & 0 \\ 13 & -52 & 110 & -44 & 0 \\ -4 & 12 & -38 & 20 & -2 \end{bmatrix}$$

Then you can compute directly that  $S^5 = 0$ . Moreover, the dimensions of the nullspaces of various iterates of  $S$  are as follows:

$$\begin{array}{r}
 j \quad k_j = \dim K_j = \dim \text{null}(S^j) \\
 4 \qquad \qquad 5 \\
 3 \qquad \qquad 5 \\
 2 \qquad \qquad 4 \\
 1 \qquad \qquad 2 \\
 0 \qquad \qquad 0
 \end{array}$$

Let's see what we can say about the Jordan block structure of this thing. Note that that already  $A^3 = 0$ ; this means that the minimal polynomial divides  $X^3$ . Moreover,  $A^2 \neq 0$ , so that the minimal polynomial is exactly  $X^2$ .

Now,  $\dim L_3 = 1$ . Let  $v^{(3)}$  be a basis for it. Then the images of  $v^{(3)}$  under  $S$  are in the various spaces  $L_j$ , and we have

$$\begin{array}{r}
 L_3 \quad v^{(3)} \\
 L_2 \quad S(v^{(3)}) \\
 L_1 \quad S^2(v^{(3)})
 \end{array}$$

(In fact, you can check this directly, using  $v^{(3)} = ??$ )

Now,  $\dim L_2 = 4 - 2 = 2$ , but we've only found one vector in it so far. Let  $v^{(2)}$  be an element of  $L_2$  linearly independent from  $v^{(3)}$ . Then we have

$$\begin{array}{r}
 L_3 \quad v^{(3)} \\
 L_2 \quad S(v^{(3)}), v^{(2)} \\
 L_1 \quad S^2(v^{(3)}), S(v^{(2)})
 \end{array}$$

In fact, this is everything; for now we have found 2 independent elements in  $L_1$ , but  $\dim L_1 = 2$ .

So, consider the basis  $\mathcal{B} = \{S^2(v^{(3)}), S(v^{(3)}), v^{(3)}, S(v^{(2)}), v^{(2)}\}$ . With respect to this basis, we have

$$[S]_{\mathcal{B}} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

The characteristic polynomial of this operator is  $X^5$ , but its minimal polynomial is  $X^3$ .

#### 8.4 Return to generalized eigenvalues

So, let  $\lambda_1, \dots, \lambda_r$  be the distinct eigenvalues of  $T$ .

We have seen that there is a direct sum decomposition

$$V = \oplus(\text{null}((T - \lambda_j)^n)).$$

Let  $U_j = \text{null}(T - \lambda_j)^n$  be the generalized eigenspace associated to  $\lambda_j$ . Then using the previous, we may find a basis for  $U_j$  such that

$$[T - \lambda_j|_{U_j}]$$

is a Jordan block with zero's on the diagonal, so that  $[S|_{U_j}] = \dots$ . Moreover,  $[T|_{U_j}]$  is in Jordan form with  $\lambda_j$  on the diagonal.

**Example** Consider

$$T = \begin{bmatrix} 60 & -224 & 511 & -214 & 4 \\ 16 & -60 & 139 & -58 & 1 \\ 6 & -24 & 52 & -20 & 0 \\ 13 & -52 & 110 & -42 & 0 \\ -4 & 12 & -38 & 20 & 0 \end{bmatrix}.$$

Its characteristic polynomial is  $\chi_T(X) = (X - 2)^5$ . The work done before shows that there is a basis such that

$$[S]_{\mathcal{B}} = \begin{pmatrix} 2 & 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{pmatrix}$$

Assembling these bases for the various  $U_j$ , we have shown that in some basis  $[T]$  is in Jordan normal form.

And this is sort of the point of the whole thing. Suppose you promise to always order eigenvalues in a certain way. (It's obvious how to do this if the eigenvalues are real; it requires choices if the eigenvalues are complex.) Suppose further that you promise to order the Jordan blocks from, say, largest to smallest.

Then two matrices are similar – that is, they represent the same operator in different bases – if and only if they have the same Jordan form.

Here are some more results about Jordan form:

**Theorem** Suppose  $T \in \mathcal{L}(V)$ ,  $\dim V = n$ . Let  $\lambda_1, \dots, \lambda_r$  be the distinct eigenvalues, and suppose that

$$\chi_T(X) = \prod (X - \lambda_i)^{e_i}$$

where  $\sum e_i = n$ .

Let  $V_i = \ker(T - \lambda_i \text{id})$ , and let  $U_i = \ker((T - \lambda_i \text{id})^n)$ . Let the sizes of the Jordan blocks of  $U_i$  be given by  $s_{i,1} \geq s_{i,2} \geq \dots \geq s_{i,b_i}$ .

- $V_i$  is the eigenspace associated to  $\lambda_i$ .
- $U_i$  is the generalized eigenspace associated to  $\lambda_i$ .
- The minimal polynomial of  $T$  is

$$\prod (X - \lambda_i)^{s_{i,1}}.$$

- $T$  is diagonalizable if any of the following holds:

- For each  $i$ ,  $\dim V_i = e_i$
- For each  $i$ ,  $U_i = V_i$
- The size of each Jordan block is  $s_{i,j} = 1$
- The minimal polynomial of  $T$  is

$$\prod (X - \lambda_i).$$

- Let  $T' \in \mathcal{L}(V)$  be another linear operator. Then  $T$  and  $T'$  are similar if and only if  $\chi_T(X) = \chi_{T'}(X)$  and if they have the same Jordan block structure.

**Example** Suppose you know the following information about an operator  $T \in \mathcal{L}(\mathbb{R}^{20})$ :

- $\chi_T(X) = (X - 2)^{16}(X + 3)^4$
- Let  $S_2 = (T - 2)$ ,  $S_{-3} = (T + 3)$ . Suppose we have the following information:

$i$	$\dim \text{null}((S_2)^i)$
5	16
4	16
3	14
2	11
1	6
0	0

$i$	$\dim \text{null}((S_{-3})^i)$
5	4
4	4
3	4
2	4
1	3
0	0

What is the Jordan canonical form of this matrix?