

Math 476: Days 27-28

Prop: For each stable measure ν on $S^2 \exists \gamma \in \mathrm{PSL}(2, \mathbb{C})$ s.t. $B(\gamma_* \nu) = 0$. The element γ is unique up to postcomposition by $g \in \mathrm{SO}(3) < \mathrm{PSL}(2, \mathbb{C})$.

Why is the proposition true?

This is where we use the hyperbolic geometry: we want to define the **hyperbolic** center of mass of a measure on the sphere at infinity. Why is this the thing to do?

① If $C(\nu)$ is the hyperbolic center of mass of the stable measure ν on S^2 & $\gamma \in \mathrm{PSL}(2, \mathbb{C})$, then

$$\gamma(C(\nu)) = C(\gamma_* \nu).$$

In other words, the hyperbolic center of mass is invariant w.r.t. the $\mathrm{PSL}(2, \mathbb{C})$ action on $\mathbb{H}^3 \cup S^2$. This is obvious since $\mathrm{PSL}(2, \mathbb{C})$ acts by isometries on \mathbb{H}^3 .

② $C(\nu) = \vec{0} \Leftrightarrow B(\nu) = \vec{0}$. We will see why this is true shortly.

Now, why are these 2 properties what we want?

Well, if $\nu = \frac{1}{2} \sum r_i \delta_{e_i}$ is the measure corresponding to a stable collection of weighted points, then it will turn out to be the case that $C(\nu)$ is in the interior of the unit ball. But then \exists a unique (up to rotation) isometry γ of \mathbb{H}^3 sending $C(\nu)$ to $\vec{0}$. By ①, this means that

$$\vec{0} = C(\gamma_* \nu) = C\left(\frac{1}{2} \sum r_i \delta_{\gamma(e_i)}\right).$$

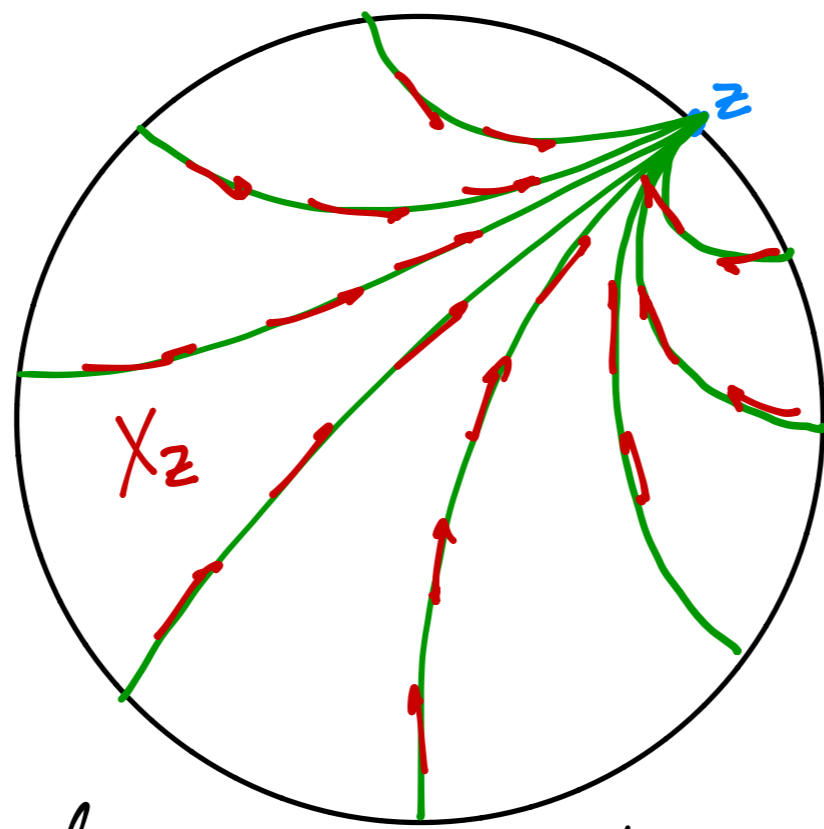
But then by ②, the Euclidean center of mass $B(\gamma_* \nu) = \sum \frac{r_i}{2} \gamma(e_i)$ is also at the origin, so $(\gamma(e_1), \dots, \gamma(e_n))$, which is in the same $\mathrm{PSL}(2, \mathbb{C})$ -orbit as (e_1, \dots, e_n) & hence in the same equivalence class in $(\mathbb{P}^1)^n / \mathrm{PSL}(2, \mathbb{C})$, corresponds to a closed polygon.

So now how should we define $C(v)$?

Well, at each point $p \in B^3 \cong \mathbb{H}^3$, we can define a vector $X_v(p)$ by

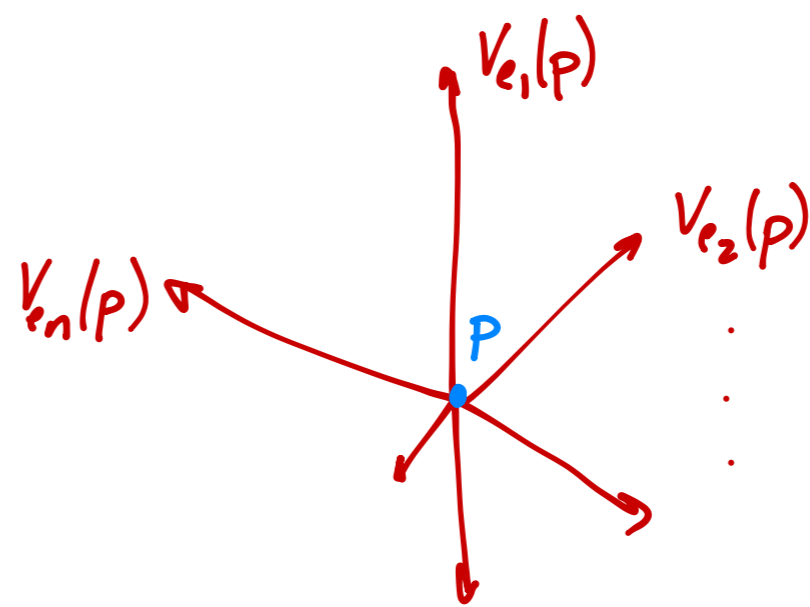
$$X_v(p) := \int_{S^2} V_z(p) d\nu(z)$$

where V_z is the unit vector field on \mathbb{H}^3 that points along the hyperbolic geodesic to $z \in S^2$.



In other words, $X_v(p)$ is the visual average of v along all hyperbolic rays emanating from p .

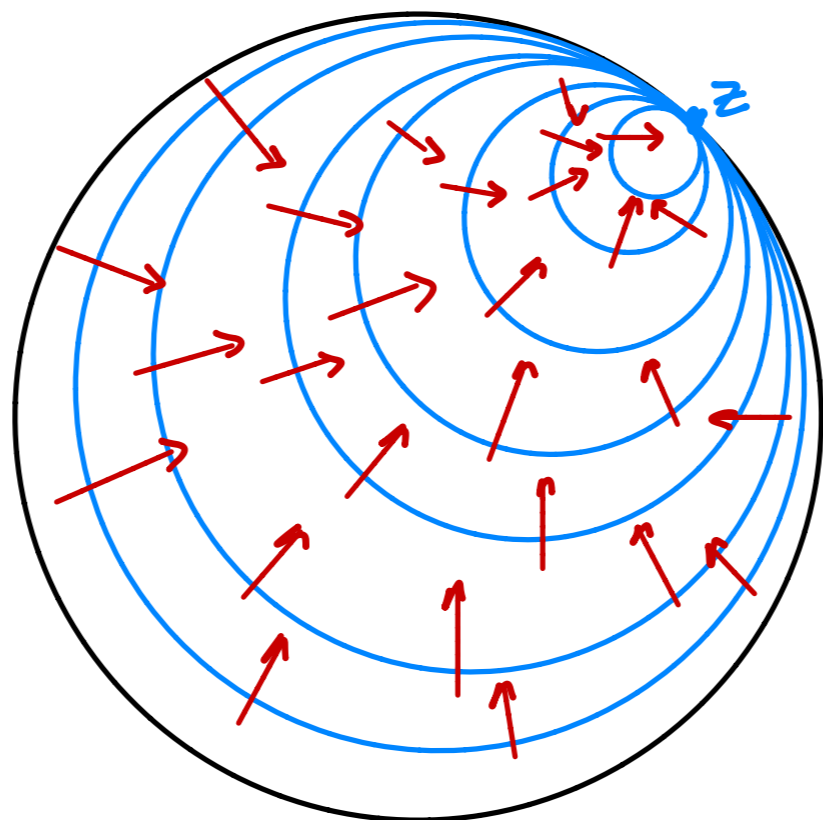
If v is atomic, then $\int_{S^2} V_z(p) d\nu(z) = \sum \frac{r_i}{Z} V_{e_i}(p)$:



But then the hyperbolic center of mass should be the (unique!) point where this is exactly balanced:

Def: The hyperbolic (or conformal) center of mass of the stable mass v on S^2 is the unique zero of the vector field X_v .

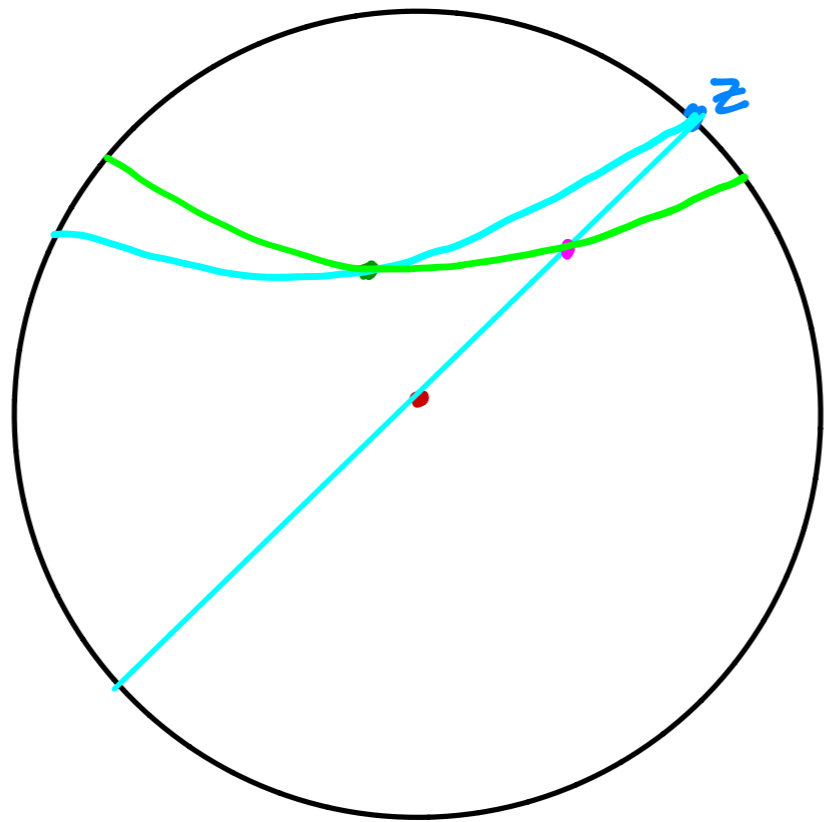
Equivalently, V_z is the gradient of a function $h_z: B^3 \rightarrow \mathbb{R}$ whose level sets are the horospheres centered at $z \in S^2$



of course, h_z is defined up to a constant, so might as well choose $h_z(\bar{0}) = 0$.

In fact, $h_z(p) = \frac{1}{2} \log\left(\frac{1-|p|^2}{|z-p|^2}\right)$ & one can show that $-h_z(p) = -\frac{1}{2} \log\left(\frac{1-|p|^2}{|z-p|^2}\right) = \lim_{r \rightarrow 1^-} [d(p, rz) - d(0, rz)]$

where $d(x, y)$ is the hyperbolic distance from x to y .



But then $X_v = \nabla H_v$, where $H_v(p) := \int_{S^2} h_z(p) d\nu(z)$.

Then $C(v)$ is a critical point of H_v , & existence & uniqueness follow because the restriction of

$-H_v$ to the hyperbolic geodesics is strictly convex.

Mathematica demo of closing by finding the central center of mass.