

Math 676: Day 3

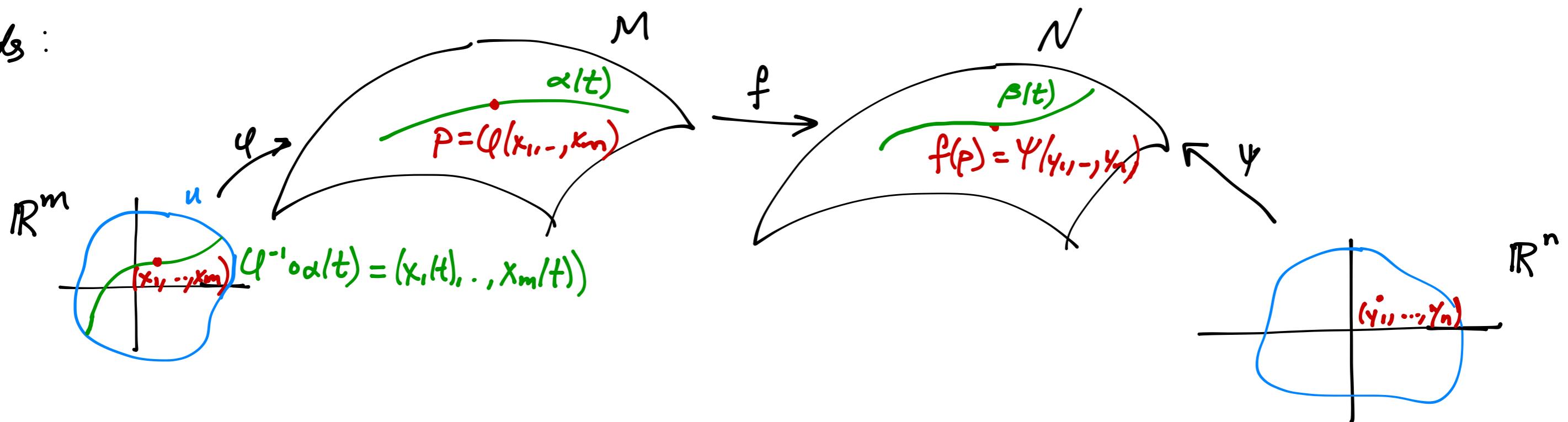
Def: Suppose M^m & N^n are manifolds & $f: M \rightarrow N$ smooth. For $p \in M$, the differential of f at p is the

Liner up $d_f_p: T_p M \rightarrow T_{f(p)} N$ given by:

For $v \in T_p M$, choose $\alpha: (-\varepsilon, \varepsilon) \rightarrow M$ s.t. $\alpha(0) = p$, $\alpha'(0) = v$. Let $B = f \circ \alpha$ & define

$$d_f_p(v) := \beta'(0).$$

In coords:



$$(y_1, \dots, y_n) = \psi^{-1} \circ f \circ \phi(x_1, \dots, x_m) = (y_1(x_1, \dots, x_m), \dots, y_n(x_1, \dots, x_m))$$

Then

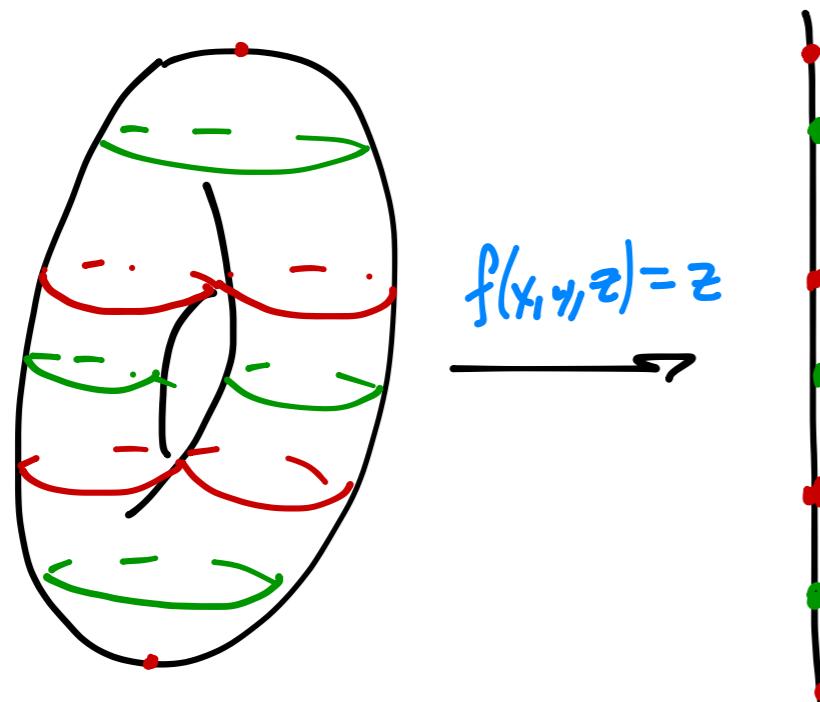
$$d(\psi^{-1})_{f(p)} \beta'(0) = \left(\sum \frac{\partial y_i}{\partial x_j} x_j'(0), \dots, \sum \frac{\partial y_n}{\partial x_j} x_j'(0) \right) = \begin{pmatrix} \frac{\partial y_i}{\partial x_j} \\ \vdots \\ \frac{\partial y_n}{\partial x_j} \end{pmatrix} (x_j'(0))$$

↑ $n \times m$ matrix ↑ m -element column vector
"df"
"v"

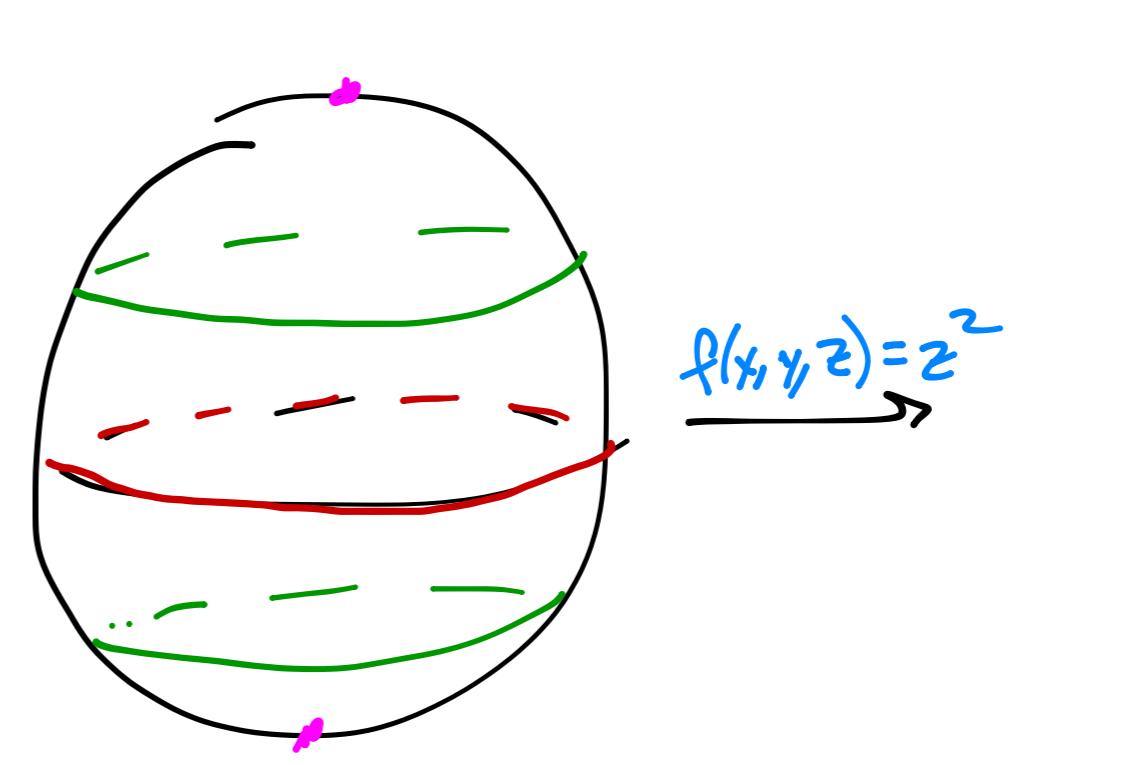
Def: Let $f: M^m \rightarrow N^n$ be smooth. A point $p \in M$ is a **critical point** of f if $d_f_p: T_p M \rightarrow T_{f(p)} N$ is not surjective; then

$f(p)$ is a **critical value** of f . A point $g \in N$ which is not a critical value is a **regular value**.

Classic Example:



Ex:



Thm: If $g \in N$ is regular, then $f^{-1}(g)$ is a smooth submanifold of M of dimension $m-n$.

Prof: Inverse Function Thm. \square

Ex: Define $f: M_{n \times n}(\mathbb{R}) \rightarrow \{\text{symmetric } n \times n \text{ matrices}\}$ by $f(A) = AAT$. Then f is always surjective & $f^{-1}(I) = O(n)$ is a

smooth submanifold of dimension $n^2 - \frac{n(n+1)}{2} = \frac{n(n-1)}{2}$.

Ex: Remember our map $\mu: \underbrace{S^{d-1} \times \dots \times S^{d-1}}_n \rightarrow \mathbb{R}^d$ given by $\mu(\vec{e}_1, \dots, \vec{e}_n) = \sum_{i=1}^n \vec{e}_i$. Then $\partial \in \mathbb{R}^d$ is a regular value when $n \geq 2$, so

the polygon space $\mu^{-1}(\partial)$ is a smooth submanifold of codimension d .

Vector Fields:

Df: A vector field X on a smooth nfd M is a smooth section of the tangent bundle TM ; i.e., a smooth map $X: M \rightarrow TM$. Given how we've defined tangent vectors, this means a vector field is just a linear derivation on $C^\infty(M)$.

Note: If $q: U \subset \mathbb{R}^n \rightarrow M$ is a coord. chart at $p \in M$, then

$$X(p) = \sum q_i(p) \frac{\partial}{\partial x_i}, \text{ where each } q_i: U \rightarrow \mathbb{R} \text{ is smooth & } \left\{ \frac{\partial}{\partial x_i} \right\} \text{ is the basis of } T_p M \text{ associated w/ } (U, q).$$

• As a map $C^\infty(M) \rightarrow C^\infty(M)$, a vector field acts as

$$(Xf)(p) = \sum q_i(p) \frac{\partial f}{\partial x_i}|_p$$

which naturally is a smooth function on M .

Df: If X & Y are smooth vector fields on M , the Lie bracket of X & Y is a vector field $[X, Y]$ defined by

$$[X, Y]f := X(Yf) - Y(Xf)$$

In coords., if $X = \sum a_i \frac{\partial}{\partial x_i}$ & $Y = \sum b_i \frac{\partial}{\partial x_i}$, then

$$[X, Y]f = X(Yf) - Y(Xf) = X\left(\sum b_i \frac{\partial f}{\partial x_i}\right) - Y\left(\sum a_i \frac{\partial f}{\partial x_i}\right) = \sum_{i,j} a_j \left(\frac{\partial b_i}{\partial x_j} \frac{\partial f}{\partial x_i} + b_i \frac{\partial^2 f}{\partial x_j \partial x_i} \right) - \sum_{i,j} b_j \left(\frac{\partial a_i}{\partial x_j} \frac{\partial f}{\partial x_i} - a_i \frac{\partial^2 f}{\partial x_j \partial x_i} \right)$$

$$= \sum \left(a_j \frac{\partial b_i}{\partial x_j} - b_j \frac{\partial a_i}{\partial x_j} \right) \frac{\partial f}{\partial x_i} + \sum a_i b_j \left(\frac{\partial^2 f}{\partial x_i \partial x_j} - \frac{\partial^2 f}{\partial x_j \partial x_i} \right)^0$$

$$= \left(\sum_{i,j} a_j \frac{\partial b_i}{\partial x_j} - b_j \frac{\partial a_i}{\partial x_j} \right) \frac{\partial}{\partial x_i} f$$

local coord expression for $[X, Y]$

Prop: If X, Y, Z are smooth vector fields on M & $a, b \in \mathbb{R}$, $f, g \in C^\infty(M)$, then

$$\textcircled{1} [X, Y] = -[Y, X] \text{ (anti-commutativity)}$$

$$\textcircled{2} [aX + bY, Z] = a[X, Z] + b[Y, Z] \text{ (linearity)}$$

$$\textcircled{3} [[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0 \text{ (Jacobi identity)}$$

$$\textcircled{4} [fX, gY] = fg[X, Y] + f(Xg)Y - g(Yf)X$$