

## Math 676: Day 24

Recall, we're trying to find the GIT quotient  $X//G$ , where  $G$  is an algebraic gp acting on the projective variety  $X$  (i.e., implicitly, on the toroidal line bundle  $\mathcal{O}_X(-1)$  on  $X$ ).

Def:  $x \in X$  is **semistable** if  $\exists s \in H^0(X, \mathcal{O}_X(r))^G$  with  $r > 0$  s.t.  $s(x) \neq 0$ .

Def: A semistable point  $x \in X$  is **stable** if  $\bigoplus_i H^0(X, \mathcal{O}(r))^G$  separates orbits near  $x$  & the stabilizer of  $x$  is finite.

Now, what's going on geometrically?

Thm: Suppose  $x \in X$  &  $\tilde{x} \in \mathcal{O}_X(-1)$  covers  $x$ . Then

$$\textcircled{1} \quad x \text{ is semistable} \iff 0 \notin \overline{G \cdot \tilde{x}}$$

$$\textcircled{2} \quad x \text{ is stable} \iff G \cdot \tilde{x} \text{ is closed in } \mathbb{C}^{n+1} \text{ & } \tilde{x} \text{ has finite stabilizer.}$$

Idea:  $G$ -inv homogeneous factors of degree  $r > 0$  on  $\tilde{X}$  are carried on orbits, & hence on their closures. So if  $\overline{G \cdot \tilde{x}} \geq 0$ , then all such factors are zero & so  $x$  is not semistable.

Moreso, if  $x$  is stable, then inv factors separate orbits and  $G \cdot \tilde{x}$ , so  $G \cdot \tilde{x}$  is the zero locus of some collection of inv. factors, & hence closed.

Prop:  $x \in X_{ss}$  is stable  $\iff$  the orbit  $G \cdot x$  is closed in  $X_{ss}$  &  $\dim G \cdot x = \dim G$ .

Of course, understanding entire group orbits is really hard... it's typically easier to understand 1-parameter subgroups, i.e., copies of  $\mathbb{C}^* \subset G$ .

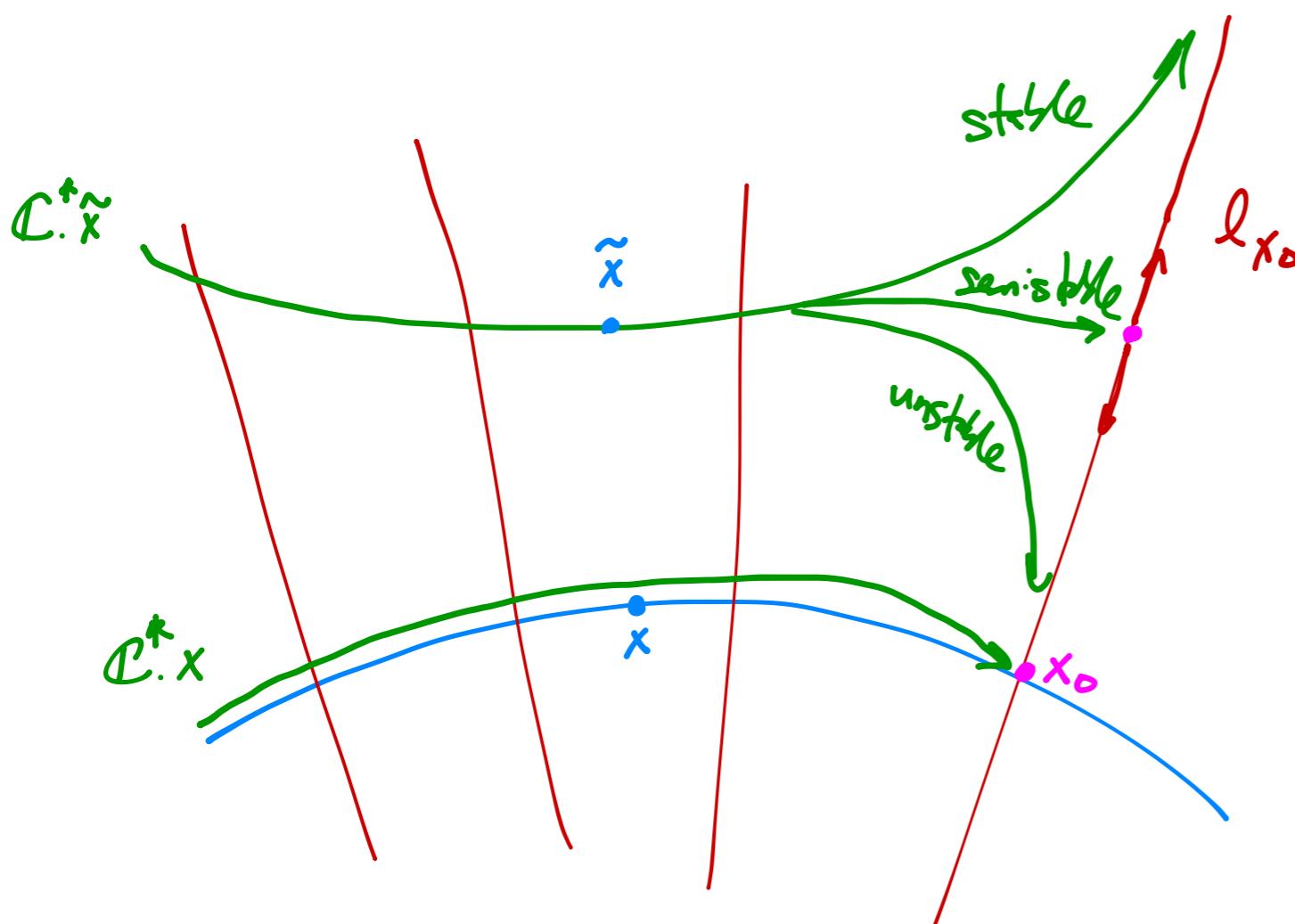
We can apply the theorem above to the orbits of all 1-parameter subgps, where we have the following easier characterization:

For  $x \in X$ , let  $x_0 = \lim_{\lambda \rightarrow 0} \lambda \cdot x$ , which is a fixed point of the  $\mathbb{C}^*$  action, so  $\mathbb{C}^*$  acts on the line  $l_{x_0}$  in  $\mathbb{C}^{n+1}$  generated by  $x_0 \in P^n$ . Of course, a  $\mathbb{C}^*$  action on a line is of the form  $\lambda \cdot z = \lambda^p z$  where  $p$  is the weight of the action. So define  $p(x)$  to be the weight of the induced  $\mathbb{C}^*$  action on  $l_{x_0}$ .

## Hilbert-Mumford Criterion:

- If  $\rho(x) < 0$  for all 1-parameter subps, then  $x$  is stable.
- If  $\rho(x) \leq 0$  for all 1-parameter subps, then  $x$  is semi-stable.
- If  $\rho(x) > 0$  for some 1-parameter subp, then  $x$  is unstable.

Idea:



The orbit is closed  $\Leftrightarrow$  it is asymptotic to a negative weight  $C^*$  action on the identity line at both  $\lambda \rightarrow 0$  &  $\lambda \rightarrow \infty$ .

But it suffices to consider  $\lambda \rightarrow 0$ , since the  $\lambda \rightarrow \infty$  case is the  $\lambda \rightarrow 0$  case of the more 1-param subp.

Ex: Now, we consider  $n$  points on  $P^1$  & the diagonal action of  $PGL(2, \mathbb{C}) = PSL(2, \mathbb{C})$ .

Specifying  $n$  points is the same as specifying a degree  $n$  hunger poly. whose roots are the points (strictly speaking, this only specifies  $n$  unordered points, or a point in the symmetric product  $\sum^n P^1$  rather than in  $(P^1)^n$ , but I'm going to ignore this)

Prop: ①  $(p_1, \dots, p_n) \in (P^1)^n$  is semi-stable  $\Leftrightarrow$  no more than  $n/2$  of the  $p_i$ 's are equal.

②  $(p_1, \dots, p_n) \in (P^1)^n$  is stable  $\Leftrightarrow$  fewer than  $n/2$  of the  $p_i$ 's are equal.

Pf: Exercise.