

## Math 476: Day 14

Last time I gave (as a series of) the justification that the trajectories of the Hamilton vector field  $X_H$  associated to a smooth map  $H: (M, \omega) \rightarrow \mathbb{R}$  preserve the value of  $H$ .

Key Example: Consider  $M = S^2$  w/ the standard symplectic structure  $\omega = d\theta \wedge dz$ , & consider the height function  $H(\theta, z) = z$ . Then  $L_{X_H} \omega = L_{X_H} d\theta \wedge dz = dH = dz$ , so  $X_H = \frac{\partial}{\partial \theta}$  &  $\varphi_t(\theta, z) = (\theta + t, z)$  is rotation around the  $z$ -axis, which obviously preserves the height.

Okay, now notice in this case that the flow of  $X_H$  is **periodic**:  $\varphi_t = \varphi_{t+2\pi}$ .

In fact, the trajectories (mild curves) of  $X_H$  are also exactly the **orbits** of the  $S^1$  action which rotates the sphere around the  $z$ -axis.

Still yet another way, the circle action gives a (1-parameter) family of **symmetries** of the sphere, & the function  $H$  gives a corresponding **conserved quantity**.

Noether's Principle: Every symmetry of a mechanical system has a corresponding conserved quantity.

Since (by Darboux's Thm) any symplectic mfld looks locally like  $(\mathbb{R}^{2n}, \omega_{std})$  & here like the phase space of a mechanical system, Noether's Principle should hold, in some sense, on all symplectic mflds.

We will see that it does, but first notice the consequence: given a mfld w/ a symmetry, the associated conserved quantity gives a **coordinate** on the mfld ... & if you have lots of symmetries, you get lots of coordinates.

The key example here is a **toric symplectic mfld**:  $(M^{2n}, \omega)$  w/ an action  $(S^1)^n \times (M, \omega)$  which preserves the symplectic structure. Then we should have  **$n$  conserved quantities**... even better, on the orbits you can just push forward the angle coords. on the torus, giving  $n+n=2n$  coords on  $(M, \omega)$ , which is what you want!

Okay, so the moral of the story is that group actions are good. Also, recall that our polygon space is  $\mathbb{R}^3/\text{SO}(3)$ , where  $\text{SO}(3)$  acts diagonally. So we need to understand group actions on symplectic manifolds anyway.

If  $M$  is a manifold &  $X \in \mathfrak{X}(M)$  is complete (e.g., if  $M$  is compact), then we have the associated flow  $\varphi: M \times \mathbb{R} \rightarrow M$  which solves the initial value problem

$$\begin{cases} \varphi_0 = \text{id}_M \\ \frac{d\varphi_t}{dt} = X \circ \varphi_t \end{cases}$$

Lemma:  $\varphi_t \circ \varphi_s = \varphi_{t+s} \quad \forall s, t \in \mathbb{R}$ .

Cor:  $\varphi_t^{-1} = \varphi_{-t}$

Cor:  $\mathbb{R} \rightarrow \text{Diff}(M)$  given by  $t \mapsto \varphi_t$  is a group homomorphism.

The image  $\{\varphi_t : t \in \mathbb{R}\}$  is called a **one-parameter group of diffeomorphisms**.

Now,  $\mathbb{R}$  is a Lie group. In general, a **Lie group** is a manifold  $G$  which is also a group so that

$$\begin{array}{ll} G \times G \rightarrow G & G \rightarrow G \\ (g, h) \mapsto gh & g \mapsto g^{-1} \end{array}$$

are smooth maps.

Moreover, the map  $\mathbb{R} \rightarrow \text{Diff}(M)$  defined above is an example of a **Lie group action**. In general, an action of the Lie group  $G$  on the manifold  $M$  is a group homomorphism  $\gamma: G \rightarrow \text{Diff}(M)$  (here this is implicitly a **left action**)

$$g \mapsto \gamma_g$$

They are associated evaluation maps  $\text{ev}_p: M \times G \rightarrow G$

$$(p, g) \mapsto \gamma_g(p)$$

The action is **smooth** if  $\text{ev}_p$  is a smooth map.

Obviously, in the case of a complete v.f.  $X$  on  $M$ , the action is smooth; conversely, all smooth  $\mathbb{R}$ -actions on  $M$  are defined

by an associated complete v.f.:  $\gamma \mapsto X_p = \frac{d\gamma_t(p)}{dt}|_{t=0}$

Now, a smooth action of  $G$  on a symplectic manifold  $(M, \omega)$  is **symplectic** if the image of  $\gamma: G \rightarrow \text{Diff}(M)$  is contained in  $\text{Symp}(M)$ , the group of symplectomorphisms of  $(M, \omega)$ .