

**MATH 676**

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**Finite element methods in  
scientific computing**

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# **Lecture 9:**

## **A second example:**

**The *step-2* tutorial program**

**-**

**Degrees of freedom (DoFs)**

# step-2

## **Step-2 shows:**

- How degrees of freedom are defined with finite elements
- The *DoFHandler* class
- How DoFs are connected by bilinear forms
- Sparsity patterns of matrices
- How to visualize a sparsity pattern

## step-2

### **Sparsity of system matrices:**

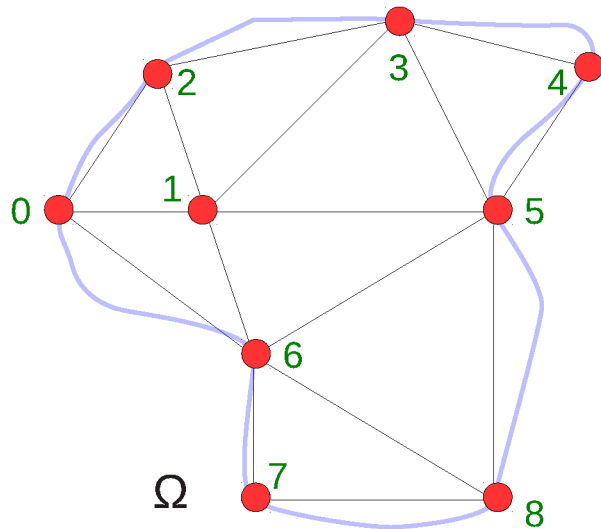
- For PDEs, finite element matrices are *always sparse*
- Result of
  - *local* definition of shape functions
  - *locality* of the differential operator

Sparsity is not a coincidence. It is a design choice of the finite element method.

**Sparsity can not be overestimated as a factor in the success of the FEM!**

## step-2

**Example:** Consider this mesh and bilinear form:



$$\begin{aligned} A_{ij} &= (\nabla \phi_i, \nabla \phi_j) \\ &= \int_{\Omega} \nabla \phi_i \cdot \nabla \phi_j \, dx \end{aligned}$$

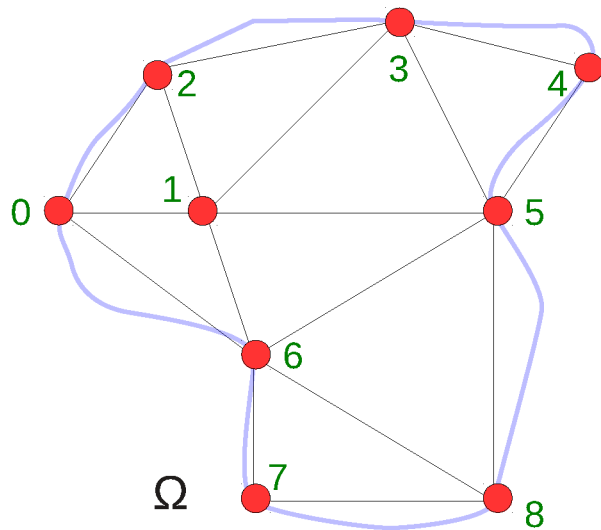
**Note:** In general we have that

- $A_{00} \neq 0, A_{01} \neq 0, A_{02} \neq 0, A_{06} \neq 0$
- $A_{03} = A_{04} = A_{05} = A_{07} = A_{08} = 0$

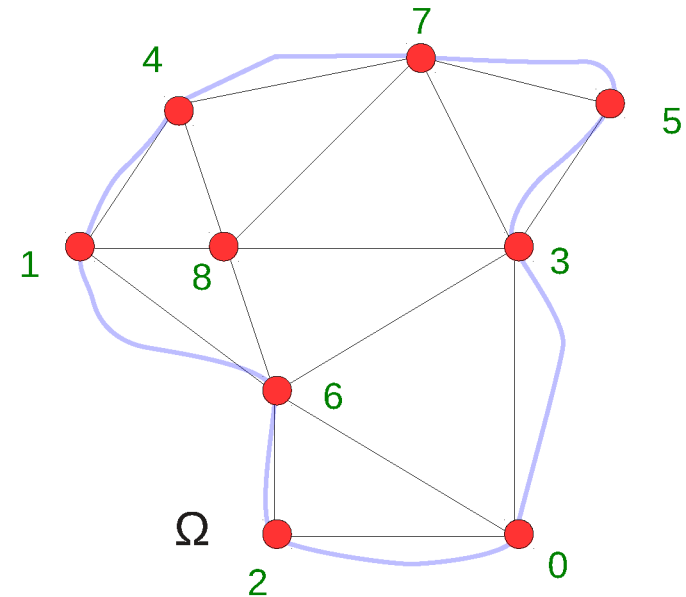
The bigger the mesh, the more zeros there are per row!

# step-2

**Renumbering:** The order of enumerating degrees of freedom is arbitrary



VS.



## Notes:

- Resulting matrices are just permutations of each other
- Both sparse, but some algorithms care

## step-2

Read through the commented program at

[http://www.dealii.org/7.1.0/doxygen/deal.II/step\\_2.html](http://www.dealii.org/7.1.0/doxygen/deal.II/step_2.html)

Then play with the program:

```
cd examples/step-2
```

```
cmake -DDEAL_II_DIR=/a/b/c . ; make run
```

This will run the program and generate output files:

```
ls -l
```

Then run *gnuplot* as described in the documentation

```
gnuplot
```

**Next step:** Play by following the suggestions in the results section. This is the best way to learn!

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